

Installation, Operating, and Maintenance Manual

Firmware versions up to V3.2X

Document #H56874

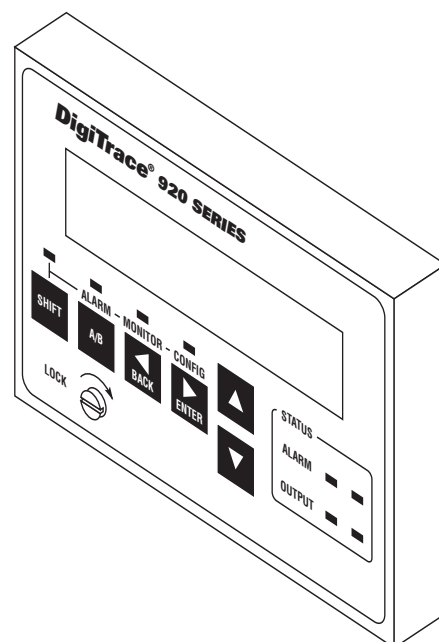
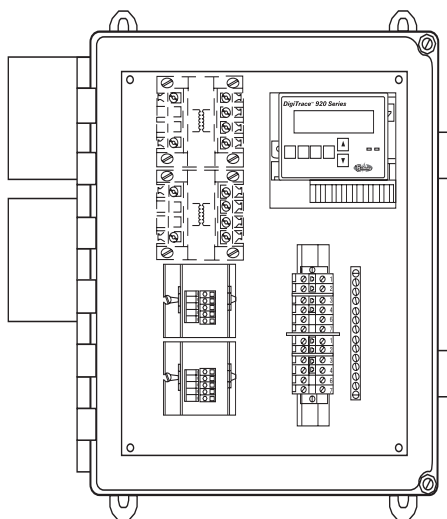
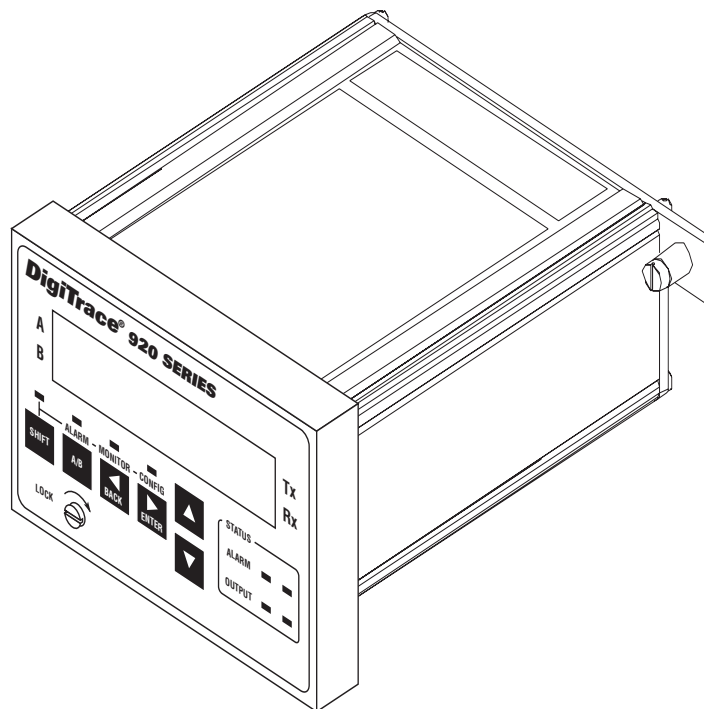


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Introduction

Installation and Maintenance Instructions for Firmware Versions up to and Including V3.2X

This manual provides information pertaining to the installation, operation, testing, adjustment, and maintenance of the DigiTrace® Model 920 Series Heat Trace Control and Monitoring products.

Additional copies of the operating manual may be ordered separately through your Tyco Thermal Controls representative or online at www.tycothermal.com using the document number H56874.

Notice: The information contained in this document is subject to change without notice.

Certification

Tyco Thermal Controls certifies that this product met its published specifications at the time of shipment from the Factory.

Limited Warranty

This Tyco Thermal Controls product is warranted against defects in material and workmanship for a period of 18 months from the date of installation or 24 months from the date of purchase, whichever occurs first. During the warranty period, Tyco Thermal Controls will, at its option, either repair or replace products that prove to be defective.

For warranty service or repair, this product must be returned to a service facility designated by Tyco Thermal Controls. The Buyer shall prepay shipping charges to Tyco Thermal Controls and Tyco Thermal Controls shall pay shipping charges to return the product to the Buyer. However, the Buyer shall pay all shipping charges, duties, and taxes for products returned to Tyco Thermal Controls from another country.

Tyco Thermal Controls warrants that the software and firmware designated by Tyco Thermal Controls for use with the DigiTrace 920 Controller will execute its programming instructions properly. Tyco Thermal Controls does not warrant that the operation of the hardware, or software, or firmware will be uninterrupted or error-free

Warranty Exclusion/Disclaimer

The foregoing warranty shall not apply to defects resulting from improper or inadequate maintenance by the Buyer, Buyer-supplied software or interfacing, unauthorized modification or misuse, operation outside of the specifications for the product, or improper installation.

No other warranty is expressed or implied. Tyco Thermal Controls disclaims the implied warranties of merchantability and fitness for a particular purpose.

Exclusive Remedies

The remedies provided herein are the buyer's sole and exclusive remedies. Tyco Thermal Controls shall not be liable for any direct, indirect, special, incidental, or consequential damages, whether based on contract, tort, or any other legal theory.

Conducted and Radiated Emissions—FCC/DOC Statement of Compliance

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used

in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at his own expense.

This equipment does not exceed Class A limits for radio emissions as set out in Schedule V to VIII of the Radio Interference Regulations of Communication Canada.

Cet appareil respecte les limites de bruits radioélectriques applicables aux appareils numériques de Classe A prescrites dans la norme sur le matériel brouilleur: "Appareils Numériques," NMB-003 édictée par le Ministre des Communications.

What's New

This section provides a summary of the new features that have been added since the last version of this manual was printed. It is assumed that the reader is already familiar with the earlier versions of the 920 Controller.

New Controller Features

- Alarm filtering is now available for:
 - LOW and HIGH TS ALARMS (see sections 3.7.7 on page 33 and 3.7.8 on page 34)
 - LOW and HIGH CURRENT ALARMS (see sections 3.8.2 on page 35 and 3.8.4 on page 36)
 - HIGH GFI ALARMS (see section 3.8.6 on page 36)
 - LOW and HIGH VOLTAGE ALARMS (see sections 3.8.9 on page 37 and 3.8.11 on page 38)
 - LOW and HIGH RESISTANCE ALARMS (see sections 3.8.13 on page 38 and 3.8.15 on page 39).

Alarm filtering will prevent an alarm from being indicated until the alarm condition has existed for the duration of the alarm filter time.
- Two new SWITCH CONTROL MODES have been added for use with Ambient Temperature control:
 - Proportional Ambient SSR
 - Proportional Ambient Contactor (see sections 3.5.3 on page 21 and 5.2 on page 50).
- ASCII and RTU ModBus™ communications protocol support (see section 3.9.1 on page 42).
- Support for an isolated, 2-wire RS-485 communications interface (see section 1.4.5).
- A 3-phase power calculation feature has been included for use with balanced, Y-connected heating loads (see section 3.5.10 on page 23).
- A Temperature Sensor (TS) Fail Mode feature is now available to allow the output to be forced ON or OFF when a control temperature failure occurs (see section 3.5.11 on page 23).
- A TEMPBUS™ feature to allow one "master" 920 controller to share its temperature sensor information with up to 25 "slave" controllers (up to 50 control points). This includes the addition of three TS CONTROL MODES (see sections 3.5.12 on page 24 and 5.4 on page 53).
- Support for 100 ohm nickel-iron RTDs along with the standard 100 ohm platinum types (see sections 3.5.13 on page 24 and 3.5.16 on page 25).
- Manual voltage source selection (see section 3.5.19 on page 26).
- Support for FORCE ON and FORCE OFF modes using the EXTERNAL input (see sections 3.5.27 on page 28 and 3.6.3 on page 29).
- Features to reload factory default parameters as well as copy configuration parameters from one point to another are now included (see section 3.11 on page 46).
- New maintenance alarming to track contactor wear (see section 3.8.23 on page 42).

-
- Monitor PEAK LOAD CURRENT, PEAK GFI, and the EXTERNAL INPUT STATUS through communications (see sections 4.3.6 on page 50, 4.3.7 on page 50, and 4.3.8 on page 50).

New Operator Console Features

- The ability to adjust the display scroll rate is now available (see section 3.6.10 on page 31).
- Maintenance data resetting is now supported (see section 4.3 on page 49).
- Display and reset the CONTACTOR CYCLE COUNTER (see section 4.3.3 on page 49).
- Limit the range of the CONTROL SETPOINT setting for 920 Operator Console users (see sections 3.5.29 on page 29 and 3.5.30 on page 29).
- An UNLOCK DATABASE feature was added to the 920 Operator Console's "Configuration Mode Main Menu" (see section 3.10.3 on page 46).
- The display test no longer occurs at startup; instead, the user may activate it from a menu option (see section 3.10.5 on page 46).

Section 1 Overview

1.1 Controllers Covered by this Manual

This document covers the 920 Series of heat trace controllers and available options. The information coincides with the specific releases of firmware for the 920 product which are listed on the cover. As Tyco Thermal Controls releases new firmware to modify or enhance the product significantly, new documentation will accompany these releases. To ensure that you are using the correct documentation for your particular version of controller, please check the firmware version number of the 920 against the version number listed on the front of this manual. This can be displayed using the optional 920 Operator Console or a communicating device. As subsequent changes are made, supplements to this document will be included in manuals shipped after the firmware is released. Supplements will make specific reference to the operational or functional changes.

1.2 Product Overview

1.2.1 DESCRIPTION

The 920 Series Heat-Tracing Controller controls, monitors, and communicates alarms and data for one or two heating circuits. As a dual-point device, it offers a complete range of control and monitoring features, as well as superior reliability compared to multipoint systems. Its modular, scalable architecture yields cost-effective multipoint assemblies without the expense of additional control points that are not required. Available for use with external solid-state relays (SSRs) or contactors in either one-, two-, or three-pole configurations and the ability to switch loads up to 600 Vac makes the 920 the most versatile product on the market.

1.2.2 FEATURES

A detailed description of available features can be found in Section III of this manual. Highlights of specific features are included in the following text.

Front Display

The control module includes LED status indicators to show output and alarm conditions. Using the optional 920 Operator Console, the setpoint temperature, actual control temperature, and load current are immediately accessible to plant operators and maintenance staff. The display units are field selectable for °F or °C.

–40°F to 140°F (–40°C to 60°C) Operation

Extended temperature operation permits installation in all but the harshest environments. SSR output modules are limited to operating ambient temperatures of 104°F (40°C) without derating.

Single or Dual Temperature Sensor Inputs

The ability to use one or two temperature sensor (TS) inputs for each control point allows the selection of one of eleven control modes and programming of all temperature parameters.

High and Low Temperature Alarms

High and low temperature alarms are offered for both inputs of each control point.

High and Low Current Alarms

Low current alarm is more than just a continuity level alarm. The 920 offers full adjustment over the entire current measurement range for both high and low current alarm limits.

Solid State or Contactor Output

The 920 is available with externally-mounted solid-state relay (SSR) output switches or contactors. With the SSR option, the user may select a time-proportional control algorithm, a simple deadband mode, or one of two ambient control algorithms. The contactor versions always use either the deadband mode or the proportional ambient contactor mode. Switching device failure alarms are supported for both types of output devices.

Ground-Fault Alarm and Trip

Ground-fault (GF) current levels are monitored and displayed in milliamps. The availability of the actual ground-fault level gives the user the choice of both alarm and trip levels suitable for the particular installation. Using multiple SSRs or a multipole contactor allows all powered legs of non-neutral circuits to be switched off under GF conditions.

Overcurrent Protection

A unique overcurrent protection algorithm greatly reduces the possibility of damage to the circuit or the controller in the event of a temporary overload while allowing for initially high in-rush currents (SSR options only).

Soft Starting

Given the circuit breaker size, the 920 will limit the energy let-through to help prevent nuisance breaker trips due to cable in-rush. This feature makes the controller particularly attractive for use with self-regulating cables (SSR options only).

Minimum/Maximum Temperature Tracking

The controller maintains the minimum and maximum temperature values seen by the controller since the last reset of these values. This is helpful in determining causes of temperature alarms.

Latching/Non-Latching Temperature Alarms

User-selectable, non-latching temperature alarms allow the controller to automatically clear the alarm when the condition no longer exists.

High and Low Voltage Alarms

Operating at voltages less than design can cause serious loss of heater output. The alarming of preset voltage deviations ensures availability of sufficient wattage output.

Power Limiting

The 920 will control the maximum output wattage if the full load power exceeds the specified maximum power setpoint. This feature eliminates the need for low voltage transformers in many applications and can assist in standardization of heating cable types (SSR options only).

Autocycling

The controller will energize the circuit for 10 seconds at a programmable interval. Circuit alarms will be generated at the time of autocycle instead of when the heat is required. This feature eliminates the need for a preventive maintenance program as these tests are performed at regular intervals by the controller.

Temperature Sensor Failure Alarm

Both open and shorted sensors are detected and alarmed by the controller.

Random Start

A startup delay between 0 and 9 seconds ensures that all units do not come on line at the same time.

Full Digital Communications

An optional internal communications interface allows the communication of alarms and analog data to a monitoring system. Industry-standard RS-232 or RS-485 serial communications are available for applications requiring direct interfacing to other devices. The modem version maintains compatibility with legacy products including the GCC-9000/780 Series (Group Communications Controller). With the availability of the heat trace data at the user's fingertips, historical trending of temperatures, power consumption, or other parameters are available for analysis and system optimization.

CSA C/US and Factory Mutual Approved

The 920 series of controllers is approved for Class I, Division 2, Groups A,B,C,D and Zone 2 hazardous locations, making it ideal for direct installation in the field. This can save the significant expense of wiring back to a centrally-located electrical distribution center.

1.3 Modular Components

The 920 series controller is made up of a number of building blocks, allowing the ultimate in design flexibility. Each component's primary function is described below.

1.3.1 CONTROL MODULE

The 920 control module forms the heart of a single- or dual-point heat trace control solution. Each plug-in module provides all of the intelligence required to control and monitor two independent heat trace circuits. It includes indicators for alarm and output status and a connector for use with a 920 Operator Console. An internal connector is provided to plug into an optional communications interface.

The control module packaging provides a rugged, vibration-proof design. Once it is plugged into a terminal board, the module is fastened using the two captive screws included as part of the rear cover. It is important that these two screws be securely fastened whenever the module is powered.

1.3.2 TERMINAL BOARD

The terminal board eases maintenance and troubleshooting by providing a termination point for all of the low-voltage signals. The 920 control module may be installed or removed without disturbing the field wiring. Temperature sensor, communications, and alarm control wiring are connected to the lever-operated spring terminals, providing gas-tight, vibration-resistant connections.

1.3.3 OPERATOR CONSOLE

A large, easy-to-read alphanumeric display and menu-driven interface ease controller configuration and eliminate the need for an external programmer. The console may be left installed permanently or may be installed temporarily for display/setup during maintenance and troubleshooting. Access is available for all monitored parameters, programmed values, and alarm information. Enhanced security is provided by password protection.

The unique design of the operator console allows it to be installed or removed under power, even in hazardous areas.

1.3.4 SWITCH INTERFACE

Universal single-phase current monitoring, single- or 3-phase ground-fault detection, and voltage monitoring are provided by the Switch Interface (SIS/SIC) module. One device is required for each control point, and two versions are available: SIS for use with SSRs, and SIC for use with the contactor. Both units also incorporate a universal power supply, allowing operation directly from 100 Vac to 277 Vac. Use with higher trace voltages is also possible, using a separate power source or a small step-down transformer.

Redundant operation is supported, allowing a control module to automatically power itself from either of two switch interface modules or both. This permits one heat-trace circuit to be turned off for maintenance without affecting the operation of the other circuit.

1.3.5 COMMUNICATIONS INTERFACE

In applications where the user wishes remote configuration capability or wants to communicate trace information and/or alarms to another device such as the GCC (Group Communications Controller), an optional communications interface may be installed in the control module.

A modem version that maintains compatibility with legacy products is available, or other industry-standard interfaces such as RS-232 and RS-485 may be specified.

1.3.6 SOLID-STATE RELAY OUTPUT MODULE

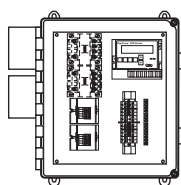
In applications where the benefits of solid-state control are desired, a modular solid-state relay (SSR) is available. This component is easily installed on the outside of an enclosure using a single 3/4 NPT knockout and locknut providing a weatherproof seal. This allows the heat generated by the SSR to be dissipated directly to the ambient air, without increasing the internal temperature of the enclosure. When applications require two-pole or 3-phase switching, multiple SSR modules may be ganged together, allowing the same component to be used.

1.4 Controller Assemblies

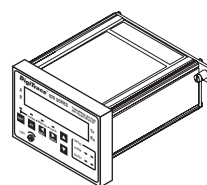
Due to its modular packaging, the 920 easily supports single-, dual-, or multi-point configurations. Factory standard assemblies are available in a variety of enclosure types, and panels made up of multiple points are also available. Refer to the Ordering Guide in section 1.5 on page 10 for a sample listing of available configurations. If your application requires a customized solution, please contact your Tyco Thermal Controls representative for help in specifying an assembly suited to your particular requirements.

1.5 Ordering and Configuration Guide

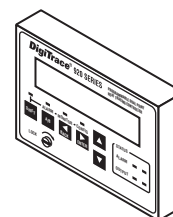
920 series control assemblies are ordered as three separate items:



Enclosure assembly



Control module(s)
(One for every two circuits)



Optional operator
console(s)

Fig. 1.6 920 series control assemblies

Tyco Thermal Controls maintains a shelf stock of enclosure assemblies, control modules, and consoles. All other enclosure assemblies are built to order. Not all options may be listed. Contact your local representative for any special applications you may have.

1.5.1 ENCLOSURE ASSEMBLY

Enclosure Assemblies			
Description	Catalog number	Part number	Weight/lbs
DigiTrace 920 controller–2 Pt in a 14" x 12" x 8" FRP enclosure with window and quick-release latches, control module, and operator console. 1P 30 A 277 V SSR/pt. Controls two circuits, each with a 1-pole solid-state relay. (Approved for Class 1, Div. 2 areas)	920*E4FWL*SIS302*SS3102*HTC*CON	10160-010	27
DigiTrace 920 controller–2 Pt in a 14" x 12" x 8" FRP enclosure with window and quick-release latches, control module, and operator console. Includes an isolated 2-wire RS-485 communication option. 1P 30 A 277 V SSR/pt. Controls two circuits, each with a 1-pole solid-state relay. (Approved for Class 1, Div. 2 areas)	920*E4FWL*SIS302*SS3102*HTC485*CON	10160-011	27
DigiTrace 920 controller–2 Pt in a 14" x 12" x 8" FRP enclosure with window and quick-release latches, control module, and operator console. 2P 30 A 277 V SSR/pt. Controls two circuits, each with a 2-pole solid-state relay. (Approved for Class 1, Div. 2 areas)	920*E4FWL*SIS302*SS3202*HTC*CON	10160-012	32
DigiTrace 920 controller–2 Pt in a 14" x 12" x 8" FRP enclosure with window and quick-release latches, control module, and operator console. Includes an isolated 2-wire RS-485 communication option. 2P 30 A 277 V SSR/pt. Controls two circuits, each with a 2-pole solid-state relay. (Approved for Class 1, Div. 2, areas)	920*E4FWL*SIS302*SS3202*HTC485*CON	10160-013	32
DigiTrace–DigiTrace Supervisory Software	DigiTrace Supervisor	10391-002	1
Note: The NEC (and CEC) rules specify that all ungrounded—i.e., hot—legs of a circuit, must be switched in the event of a ground fault. This means for 207 V single-phase applications, you must specify a 2-pole (2P) version if you are not using external GFI breakers.			
Control Modules			
DigiTrace 920 controller–Control module only (No communications options installed)	920HTC	10260-001	1
DigiTrace 920 controller–Control module with an isolated 2-wire RS-485 communication option installed	920HTC*485	10260-004	1
DigiTrace 920 controller–Control module with modem communications option installed	920HTC*MDM	10260-002	1
Operator Console			
DigiTrace 920 controller–Operator console	920CON	10260-005	1

Contact your local representative for other available configurations that are not listed above.

Section 2 Installation and Wiring



Caution: Be sure all personnel involved in installation, servicing, and programming are qualified and familiar with electrical equipment, their ratings and proper practices and codes. Multiple voltages and signal levels may be present during the installation, operation, and servicing of this product. Do not power the product until the safety provisions outlined in this section have been observed.

2.1 Introduction

This section includes information on the initial inspection, preparation for use, and storage instructions for the 920 series heat trace controller.



Caution: Solid-state relay (SSR) modules may be extremely hot immediately after power is removed. Exercise care when handling SSRs.

2.2 Initial Inspection

Inspect the shipping container for damage. If the shipping container or cushioning material is damaged, it should be kept until the contents of the shipment have been verified for completeness and the equipment has been checked mechanically and electrically. Procedures for configuring and operating the heat trace controller are given in Section 3 on page 18. If the shipment is incomplete there is mechanical damage, a defect, or the controller does not pass the electrical performance tests, notify your Tyco Thermal Controls representative. If the shipping container is damaged, or the cushioning material shows signs of stress, notify the carrier as well as your Tyco Thermal Controls representative. Keep the shipping materials for the carrier's inspection.

2.3 Operator Safety Considerations

The standard 920 controller using solid-state relays is suitable for Class I, Division 2, Groups A, B, C, D and Zone 2 hazardous areas. Hazardous areas are defined by Article 500 of the National Electrical Code and Section 18 of the Canadian Electrical Code. Contactor-based assemblies are suitable for use in ordinary (non-hazardous) areas only.



Caution: Many wiring configurations will use more than one power source and all must be de-energized prior to performing any maintenance on a controller circuit.

2.4 Operating Environment

The operating environment should be within the limitations described in the 920 heat trace controller specifications outlined in Appendix A on page 61.

2.5 Installation Location

The wide ambient operating temperature range of the controller permits installation in any convenient location. Considerations should include expected atmospheric conditions, accessibility for maintenance and testing, the location of existing conduits, and hazardous area rating. Ambient temperature conditions may affect load current ratings.



Caution: Always be sure that the intended location is classified as an area that the product is approved for as defined by Article 500 of the National Electrical Code and/or Part I, Section 18 of the Canadian Electrical Code.

2.6 Mounting Procedures

Mounting hole dimensions for the standard enclosures are shown in Appendix B on page 63. If possible, conduit entries should be made in the bottom of the enclosure to reduce the possibility of water entry or leakage. Conduit entries must be drilled/punched following the enclosure manufacturer's recommendations. Use bushings suitable for the enclosure type and install such that the completed installation remains waterproof. Grounding hubs and conductors must be installed in accordance with Article 501-4(b) of the National Electrical Code and Part I of the Canadian Electrical Code.

The user may want to consider enclosure drain holes in applications where moisture is a problem; drill 0.125" holes in the bottom of the enclosure on both the left and right sides. Two holes reduce the possibility that one will plug and ensures drainage if the enclosure is not perfectly level. Note that drilling holes in the enclosure compromises the NEMA 4 rating. Controllers should be removed from the enclosure before any holes are drilled or cut to prevent damage due to flying debris.

2.6.1 CONTROL MODULE INSTALLATION AND REMOVAL



Caution: Always ensure that the power to the unit is turned off during installation or removal to avoid the risk of injury and damage to the controllers.



Warning—Explosion Hazard! Do not install or remove the control module while the unit is powered.

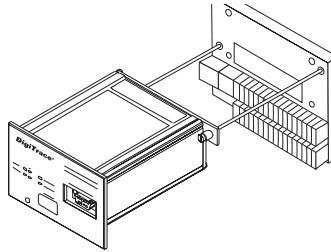


Fig 2.1 Control module installation

The 920 series controller is designed to be mounted to a flat back plate/panel using a terminal board. This plug-in design simplifies installation and maintenance by allowing all of the low-voltage field wiring to remain undisturbed while a control module is installed or removed.

Installation of the control module is easily accomplished by plugging it into the connector on the terminal board.

- The module is fully inserted once its rear cover is flush to the top surface of the terminal board. The connectors are designed to be self-aligning, so no undue force should be required.
- Next, secure the module using the two captive screws provided (one located on each side of the rear cover). These should thread easily into the terminal board. Be sure to align the screws properly to avoid cross-threading them.

To remove the control module, loosen the two captive screws. Once they have been completely loosened, they will float freely in their respective retaining collars without falling out. The module may now simply be pulled straight out of its connection.

2.6.2 OPERATOR CONSOLE INSTALLATION AND REMOVAL

The operator console is designed to be easily installed or removed while the controller is powered—even in Class I Division 2 and Zone 2 hazardous areas. It may be temporarily or permanently installed.

The console is installed in three steps:

Step 1 “Hook” the lip provided on the rear cover of the console over the top edge of the control module front plate.

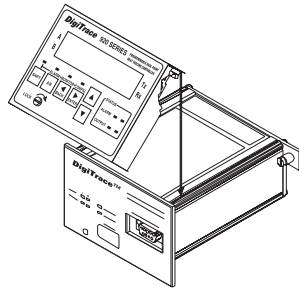


Fig. 2.2 Console installation – Step 1

Step 2 “Hinge” the bottom of the console downwards until it is flush with the front of the control module.

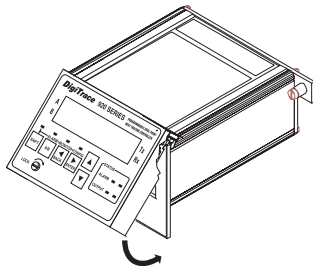


Fig. 2.3 Console installation – Step 2

Step 3 If the console is to be permanently installed, secure it to the control module using the captive screw provided. It should be finger tight only. **Do not over-tighten the screw or damage to the console housing may occur.**

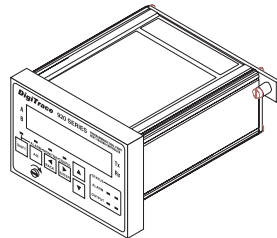


Fig. 2.4 Console installation – Step 3

To remove the console, follow the three steps outlined above in reverse order.

2.7 Wiring

Wiring diagrams for typical configurations are included in Appendix C on page 68.



Caution: Always verify wiring connections before applying power to the controller or connected circuits. To avoid injury or equipment damage, do not install or remove wiring while controller power is on.

To minimize the chance of loose connections, the terminal board uses lever-operated, spring-loaded terminals. See Appendix A on page 61 for allowable wire sizes and recommended insulation strip lengths.

2.7.1 TEMPERATURE SENSOR CONNECTIONS

Use shielded, twisted, three-conductor wire for the extension of RTD leads. The wire size should ensure that the maximum allowable lead resistance is not exceeded. Shields on RTD wiring should be grounded at the controller end only, using the terminals provided.

Temperature Sensors	Terminal No.
Point A – Shield	25
Point A TS 1 Source (WHT)	26
Point A TS 1 Sense (WHT)	27
Point A TS 1 Common (RED)	28
Point A – Shield	9
Point A TS 2 Source (WHT)	10
Point A TS 2 Sense (WHT)	11
Point A TS 2 Common (RED)	12
Point B – Shield	29
Point B TS 1 Source (WHT)	30
Point B TS 1 Sense (WHT)	31
Point B TS 1 Common (RED)	32
Point B – Shield	13
Point B TS 2 Source (WHT)	14
Point B TS 2 Sense (WHT)	15
Point B TS 2 Common (RED)	16



Note: Some RTDs may be constructed with the Sense wire color-coded as Black.

2.7.2 ALARM RELAY CONNECTIONS

The alarm output relay is a programmable dry contact output. It may be programmed for N.O., N.C., steady or flashing operation, and is typically used to annunciate an alarm to an external device such as a DCS, PLC, etc.



Note: The alarm relay is intended to be used for switching low-voltage, low-current signals. *Do not use this relay to directly switch line voltages.* Ensure that your application stays within the ratings of the relay contacts as defined in Appendix A on page 61.

The alarm relay may also be used in conjunction with the +9 Vdc source to switch an external, line-voltage relay to drive a local pilot light, etc. Refer to the wiring diagrams in Appendix C on page 68 for example connection details.

Alarm and Control Signals	Terminal No.
Alarm relay dry contact output	17
Alarm relay dry contact output	18
Ground	19
+9 Vdc nominal Out (100 mAmps maximum)	1
Common	2
Common	3

2.7.3 EXTERNAL INPUT/OUTPUT

These input and output terminals are used to implement the Override and Ambient Temperature Control Mode features. Refer to Section 3 on page 18 for programming details, and Appendix C on page 68 for example wiring diagrams.

Miscellaneous Signals	Terminal No.
External input (+)	20
External input (-)	21
External output (+)	4
External output(-)	5

2.7.4 COMMUNICATION SIGNAL CONNECTIONS

The communications terminal assignments change based on the type of option installed. If present in a control module, the type of communications interface will be identified by a label located next to the module's rating label.

Communications wiring should use twisted conductor, shielded cable. Shields on communications wiring should be grounded at one end only, using the terminals provided.

The following tables define the appropriate signal connections for the various types of interfaces:

RS-485 (2-Wire) Connections

Communication Signal	Terminal No.
Receive/transmit data (+)	6
Receive/transmit data (-)	22
Shield	8
Shield	24

RS-232 Connections

Communication Signal	Terminal No.
Receive data	6
Data carrier detect	7
Clear to send	8
Transmit data	22
Request to send	23
Common	24

Modem Interface Connections (Note that these particular signals are not polarity sensitive)

Communication Signal	Terminal No.
Modem	6
Modem	22
Shield	8
Shield	24

2.7.5 POWER CONNECTIONS

All of the power terminals are numbered for easy identification. Do not attempt to use wire sizes that exceed the marked terminal ratings and avoid terminating two wires on the same terminal whenever possible.

Always be sure that all terminals are adequately tightened according to the terminal manufacturer's specification. See Appendix A on page 61 for allowable wire sizes, recommended insulation strip lengths, and tightening torque. A loose terminal can cause arcing and damage to the terminal or incorrect operation of the controller.



Note: Make sure that power terminals are re-tightened several days after installation. Stranded wire will tend to compress when initially installed; therefore, these terminals should be checked for tightness several times after the system is installed to ensure that a good connection is main-

tained. Be certain to use the proper size screwdriver for the terminal blocks to minimize the chance of damage to the terminals.

If the controllers are installed in either a metallic or non-metallic enclosure, follow the enclosure manufacturer's recommendations for proper grounding. Do not rely on conduit connections to provide a suitable ground.

Grounding terminals/screws are provided for connection of system ground leads. Proper system grounding is required for safe and correct operation of the controller's protection features.

2.7.6 INPUT POWER

The 920 controller may be powered directly from the trace voltage (120 Vac to 277 Vac), through a step-down transformer, or from a separate circuit. The same wiring terminal assignments are used in all configurations, as defined below:

Power Connections	Terminal No.
Line/L1 power input	1
Line/L1 Control Power Input	2
Neutral/L2 Power Input	3
Neutral/L2 Control Power Input	4
L3 Power Input (3Ph only)	5
Line/L1 Output to Trace	6
Neutral/L2 Output to Trace	7
L3 Output to Trace (3Ph only)	8

Note that terminals 5 and 8 are only used for implementing 3-phase switching (this is true for both SSR and contactor configurations).

When powering the controller directly from the incoming trace power (120 Vac to 277 Vac), jumpers are installed between terminals 1 and 2 and 3 and 4. This is the standard factory configuration. When the controller is to be powered from another voltage source, the jumpers between terminals 1 and 2 and 3 and 4 should be removed, and the controller power connected to terminals 2 and 4.

In applications where a neutral-based 4-wire 3-phase source is available, the controller may be powered from one line to neutral connection, while the trace is operated from the line-to-line connection, eliminating the need for step-down transformers or separate power sources. This can be accomplished by removing the jumper between terminals 3 and 4 only. Controller power can then be derived from the L1 trace power on terminals 1 and 2 and the incoming neutral connection for controller power would be connected to terminal 4.

Wiring diagrams for typical 1- and 2-pole configurations are included in Appendix C on page 68.



Note: The contactor version Switch Interface modules provide a switched line voltage signal to drive the contactor coil. This is derived from the control power and, as such, requires that the contactor coil voltage be specified to match the control voltage present on terminals 2 and 4.



Caution: Many wiring configurations will use more than one power source and all must be de-energized prior to performing any maintenance on a controller circuit. When servicing one control point, remember that power may also be present on the second control point.

2.8 Initial Power-up



Caution: Before applying power to the controller, ensure that powering the circuit will not damage it if power limiting or the setpoint temperature have not been set correctly. If there is any doubt, the load should be disconnected until the 920 has been suitably programmed for correct and safe operation.

2.8.1 INITIAL CABLE TEST

To minimize the risk of damage to the controller due to a cable fault, the integrity of the heating cable should be verified by:

1. Using a megger to perform a high-voltage insulation test
2. Using an ohmmeter to ensure that the heating cable is not shorted

These tests must be performed with the controller output disconnected. Once the cable has been checked, it may be reconnected to the controller and power applied.

2.8.2 RANDOM START DELAY

All 920 series control modules incorporate a RANDOM START-UP DELAY feature, ensuring that all units do not power on at the same time. When power is first applied to a controller, it will hold its output off for a random time (0 to 9 seconds), equal to the last digit of the HTCBUS™ communications address (see section 3.9.2 on page 43). Once the start-up delay has timed out, the controller will begin normal operation.

2.9 Setup for the 920

The 920 may be programmed using the optional 920 Operator Console, or a Group Communications Controller (GCC) if the modem communications option is installed. For instructions on the operation of these devices, refer to the corresponding operating manuals. For complete instructions on programming the 920, see the Section 3 on page 18.

2.9.1 VOLTAGE READING SETUP

The 920 series control module is tested, calibrated, and ordered separately from the switch interface modules which contain the voltage sensing circuitry. This prevents Tyco Thermal Controls from calibrating the control modules to specific switch interfaces and removing any component inaccuracies. Generally, the voltage readings will be within 3 Vac to 5 Vac when shipped from Tyco Thermal Controls. If more accurate voltage readings are desired, they may be adjusted as part of the initial setup of the controller. This requires measurement of the trace voltage using a multimeter and adjusting the VOLTAGE TURNS RATIO setting to arrive at more accurate voltage readings. See section 3.5.21 on page 26.

2.9.2 SWITCH RATING SETUP (SSR ONLY)

The 920 series control module is ordered and shipped as a separate item from the enclosure assembly. This prevents Tyco Thermal Controls from predetermining the SWITCH CURRENT RATING settings since various types of output switches are available.

The user should verify that the switch current ratings are set properly for the rating of the solid-state relays that are included as part of the enclosure assembly. Refer to section 3.5.7 on page 22 for more information on the SWITCH CURRENT RATING setting. Tyco Thermal Controls default setting is defined in Appendix F on page 76.

Section 3 Programming and Configuration

3.1 Introduction

This section provides complete operating and setup instructions for the 920 Series Heat-Tracing Controller. The text describes each available function in detail, its purpose, valid range settings, the procedure for use, and some operational tips and suggestions.

While configuring the controller, it is important to remember that the 920 series controller is a two control point device. Both control points allow completely independent operation and, as such, have their own individual settings that must be configured. Throughout the text, the first control point is referred to “Point A” and the second as “Point B.”

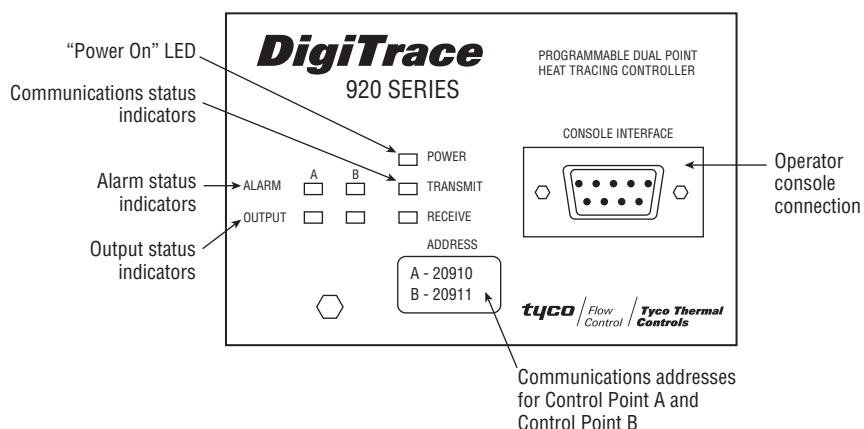


Fig 3.1 DigiTrace 920 front panel

3.2 Front Panel Features

Front panel features of the heat trace controller are shown in Figure 3.1. The remainder of this Section describes the front panel status and display LEDs.

3.2.1 920 FRONT PANEL DISPLAY

The basic 920 series control module front panel includes seven LED indicators. Four of these are used to indicate the “Output” and “Alarm” status of control points A and B.

Status LEDs

OUTPUT The OUTPUT LED, when illuminated steadily, indicates that the output of the controller is turned on and is allowing current to flow in the trace circuit. For SSR versions, a flashing LED indicates that the controller is pulsing its output on and off to maintain the setpoint temperature and/or control the average amount of current/power the tracer uses. A separate LED is provided for Point A and Point B.

ALARM The ALARM LEDs will flash (approximately once per second) when the controller has detected an alarm condition. A separate LED is provided for Point A and Point B.

TRANSMIT The TRANSMIT LED (“Tx”) flashes when the controller is sending information over its communications port to another device. This LED is only used when an optional communications interface is installed.

RECEIVE The “RECEIVE” LED (“Rx”) flashes when the controller is receiving information over its communications port from another device. This LED is only used when an optional communications interface is installed.

POWER Indicates the module is powered on.



Note: Older versions of the controller may not have this LED.

3.3 920 Operator Console Display

The optional 920 Operator Console provides a menu-driven, alphanumeric interface to ease configuration and troubleshooting. The following features are part of the controller’s programming, but are only used in conjunction with the 920 Operator Console. For a detailed description of each of the console features and operating instructions, refer to the separate *DigiTrace 920 Series HTC Operator Console—Installation and Operating Instructions* (Tyco Thermal Controls reference H56903).

3.4 920 Functions

The sections that follow explain the various functions of the 920 controller and how they can be accessed. The first line of each section identifies the function to be described. Each section goes on to explain the **Purpose** of the function, the **Range** over which it may be set, the **Procedure** for setting or enabling the feature, and finally any **Notes** or **Cautions** that pertain to the particular function.

Setting and using the alarming functions of the 920 controller is a two step procedure:

1. The alarm must be enabled or disabled accordingly. When using the 920 Operator Console, access to all alarming functions is available using the CONFIGURE mode sub-menus. When using the Model 780/GCC-9000 Group Communications Controller, the alarm masks may be found in the HTC SETUP Section. Please see the appropriate operating manual for instructions on accessing these parameters.
2. The corresponding alarm point value may be modified appropriately for the application. When using the 920 Operator Console, access to the alarm points is also available using the CONFIGURE mode sub-menus. Modification of the alarm setpoint values is found in the HTC SETPOINTS Section of the Model 780/GCC-9000 Group Communications Controller. Please see the appropriate operating manual for instructions on accessing this feature.



Note: The 920 Operator Console or the Model 780/GCC-9000 will *not* allow modification of an alarm point value if the alarm has been disabled (DIS) with the exception of the HIGH TS ALARM temperature settings. These may still be modified if the corresponding HIGH LIMIT CUTOUT has been enabled (ENA).

3.5 Control Point Setup

This Section describes the setup parameters that relate to a specific control point—either Point A or Point B. These parameters must be configured for each of the two control points that are used.

3.5.1 CONTROL SETPOINT TEMPERATURE

Purpose: The CONTROL SETPOINT temperature is the value at which the heat trace controller maintains the circuit temperature through either proportional, proportional ambient SSR, proportional ambient contactor, or deadband control, depending on the controllers' configuration. The CONTROL SETPOINT temperature is compared to the temperature measured by the control temperature sensor (TS). A decision is then made to turn on or turn off the output to control power to the tracer.

Range: -76°F to 1058°F (-60°C to 570°C)

Procedure: Adjust the CONTROL SETPOINT temperature value to the desired maintain temperature. The HTC will switch the output ON and OFF in an attempt to maintain this temperature.



Notes:

- See section 5.2 on page 50 of this manual for an explanation of Proportional, Proportional Ambient SSR, Proportional Ambient Contactor and Deadband Control algorithms.
- When using an optional 920 Operator Console (for V3.11 and up) the CONTROL SETPOINT temperature range may be limited to the CONSOLE SETPOINT MAXIMUM and MINIMUM values (see sections 3.5.29 on page 29 and 3.5.30 on page 29). This is a safety feature to prevent users in the field from modifying the CONTROL SETPOINT temperature setting to a dangerous level.

3.5.2 ALPHANUMERIC TAG ASSIGNMENT

Purpose: A 19-character alphanumeric TAG may be assigned to a control point to allow it to be easily associated with a pipe, vessel, process, circuit, drawing name or number.

Setting: Any combination of 19 characters from A-Z, 0-9, /, -, ., (,) or #.

Procedure: Using the 920 Operator Console, enter the desired text. Refer to the separate *DigiTrace 920 Series HTC Operator Console—Installation and Operating Instructions* (Tyco Thermal Controls reference H56903) for TAG entry information.

3.5.3 SWITCH CONTROL MODE

Purpose: This allows selection of the type of algorithm to be used by the HTC to maintain the CONTROL SETPOINT temperature. There are four different control algorithms available in the HTC—proportional, proportional ambient SSR, proportional ambient contactor, and deadband. See section 5.2 on page 50 for a complete explanation of these controlling techniques as implemented in the HTC.

Setting: PROPORTIONAL, PROPORTIONAL AMBIENT SSR (V3.11+), PROPORTIONAL AMBIENT CONTACTOR (V3.11+), or DEADBAND

Procedure: Select the desired control technique. Note that deadband control and proportional ambient contactor should be selected when using contactors or when precise control and advanced current handling functions are not required.



Note: If deadband is selected, a DEADBAND setting will be available in the HTC configuration menu, else a PROPORTIONAL BAND setting will be available. No MAXIMUM POWER, SWITCH CURRENT RATING or CIRCUIT BREAKER CURRENT RATING settings are available when the controller is set to operate in either contactor mode. If proportional ambient contactor is selected, the CYCLE TIME setting will also be available.

3.5.4 PROPORTIONAL BAND SETTING

(For use with the three proportional control modes only)

Purpose: When an HTC equipped with SSRs is used to control a heating circuit, proportional or proportional ambient SSR modes are normally used, allowing for more precise temperature control. When using contactors, the proportional ambient contactor mode should be selected.

This programmable proportional band acts to vary the on to off time of the output based on the difference between the measured control temperature and the desired CONTROL SETPOINT temperature.

Range: 2°F to 90°F (1°C to 50°C)
2°F to 630°F (1°C to 350°C) V3.2x and up

Procedure: Adjust the PROPORTIONAL BAND setting to the desired differential from the CONTROL SETPOINT temperature.



Notes:

- See section 5.2 on page 50 for an explanation of how the three proportional modes use the PROPORTIONAL BAND setting.
- When using series-type, constant wattage, or self-regulating tracers in an ambient temperature control application, significant energy savings may be realized by setting the PROPORTIONAL BAND to match the expected range of operating ambient temperatures. Tracer design is normally done assuming worst-case conditions, where 100% of the design output power is required to maintain the desired minimum temperature. When the ambient temperature is above the design minimum but some heat is still required, adjusting the PROPORTIONAL BAND width accordingly will allow only the amount of power required by the application to be consumed, while maintaining the minimum required temperature.

Example: A water line must be protected from freezing when the ambient temperature falls below 10°C. Either the proportional ambient SSR or proportional ambient contactor mode is selected as the control method (depending on the type of switch being used). The heater and insulation are chosen to impart enough heat to the line to keep it from freezing at a worst-case ambient temperature of -40°C. At 10°C, the heater should be completely off, since no heat is required at this temperature to guarantee that the product will not freeze. It follows that the amount of heat required by the water line decreases as the ambient temperature increases from -40°C to 10°C (theoretically, at -15°C the heater output should be approximately 50%). Setting

the CONTROL SETPOINT temperature to 10°C, and the PROPORTIONAL BAND to 50°C, will force the controller's output to be 100% on at -40°C, 50% on at -15°C, and off at 10°C.

3.5.5 DEADBAND SETTING

(Deadband control mode only or if a point controls an INHIBIT output signal)

Purpose: When an HTC equipped with a contactor is used to control a trace circuit, it is necessary to use deadband rather than proportional control. This is done to prevent the contactor from switching on and off rapidly and being worn out prematurely. This deadband acts as an on/off control where the decision to turn the output off or on is based upon a window of difference between the measured control temperature and the desired CONTROL SETPOINT temperature.

Range: 2°F to 90°F (1°C to 50°C)

Procedure: Adjust the DEADBAND setting to the desired differential from the desired CONTROL SETPOINT temperature. When the control temperature is above the setpoint + deadband value, the controller will turn off the output to the tracer. If the control temperature drops down below the setpoint, the output will be turned back on. Note that the smaller the DEADBAND setting, the more often the contactor will cycle on and off, decreasing its operational life.



Notes:

- See section 5.2 on page 50 for an explanation of deadband control. Note that the MAXIMUM POWER, SWITCH CURRENT RATING, and CIRCUIT BREAKER CURRENT RATING settings are not available when the HTC is set to deadband mode (typically when switching a contactor).
- The DEADBAND parameter is also available for Point A when the EXTERNAL OUTPUT is configured for use as an INHIBIT output. See section 3.6.4 on page 30 for additional details.

3.5.6 CYCLE TIME SETTING (V3.11 AND UP)

(For proportional ambient contactor control mode only)

Purpose: This parameter determines the minimum amount of time it will take for a complete contactor ON-OFF-ON cycle.

Range: 10 to 255 minutes

Procedure: Adjust the CYCLE TIME setting to yield the desired contactor ON+OFF time for a particular duty cycle. For instance, if the contactor should remain on for five minutes with a 50% duty cycle, then the CYCLE TIME should be 10 minutes. A new duty cycle (based on measured control temperature, PROPORTIONAL BAND and CONTROL SETPOINT) is calculated every time the contactor is required to change state.



Notes:

- If the calculated duty cycle is 0% or 100%, then the contactor will not change state and the duty cycle will not be calculated again for a time period = CYCLE TIME/30.
- The minimum cycle time setting is 10 minutes, and the minimum controller output duty cycle is 3%. This results in a minimum contactor ON time of 18 seconds.

3.5.7 SWITCH CURRENT RATING SETTING (SSR ONLY)

Purpose: The SWITCH CURRENT RATING setting defines the current rating of the output switch. It is used by the controller to limit the maximum average current that will be allowed to flow to the load before it begins to adjust the output duty cycle, limiting the amount of current to an acceptable level.

Range: 0.3 to 100.0 amps
(CURRENT TURNS RATIO = 1.00)

Procedure: Adjust the SWITCH CURRENT RATING setting to match the current rating of the output device (i.e. 30.0 amps). Note that the SWITCH CURRENT RATING setting is affected by the CURRENT TURNS RATIO setting. The absolute maximum adjusted SWITCH CURRENT RATING setting is 300.0 amps. The absolute minimum adjusted SWITCH CURRENT RATING setting is 0.1 amps. See section 3.5.22 on page 26 for more information regarding the CURRENT TURNS RATIO function.

3.5.8 CIRCUIT BREAKER CURRENT RATING SETTING (SSR ONLY)

Purpose: The CIRCUIT BREAKER CURRENT RATING setting helps prevent in-rush induced nuisance tripping of the circuit breaker immediately upstream of the controller. The HTC evaluates the square of the current related to time (I^2T) and adjusts the output duty cycle accordingly, limiting the amount of current to an acceptable level.

Range: 0.3 to 100.0 amps
(CURRENT TURNS RATIO = 1.00)

Procedure: Adjust the CIRCUIT BREAKER CURRENT RATING setting to the heating circuit breaker size (i.e. 30.0 amps). Note that the CIRCUIT BREAKER CURRENT RATING setting is affected by the CURRENT TURNS RATIO setting. The absolute maximum adjusted CIRCUIT BREAKER CURRENT RATING setting is 300.0 amps. The absolute minimum adjusted CIRCUIT BREAKER CURRENT RATING setting is 0.1 amps. See section 3.5.22 on page 26 for more information regarding the CURRENT TURNS RATIO function.



Note: This feature should *not* be used to reduce the size of a circuit breaker or increase the maximum heating cable length. It can be quite effective in preventing nuisance trips due to incorrect design or factors outside those considered by the design.

3.5.9 MAXIMUM POWER SETTING (SSR ONLY)

Purpose: This user-selectable level limits the maximum amount of power applied to a heat trace circuit. This is an average power calculated by the controller using the average current and applied voltage. The HTC switches the output on and off rapidly to limit the average current to an appropriate level. The MAXIMUM POWER level may be adjusted to eliminate step-down transformers, lower the effective output wattage of a cable, or implement energy management of the heat trace circuit.

Range: 3 to 33,000 Watts
(VOLTAGE and CURRENT TURNS RATIOS = 1.00)

Procedure: Adjust the MAXIMUM POWER level to the desired value (watts). Use the TEST TRACING function to observe the power limiting operation.



Notes:

- This function may be set within reasonable limits for the particular tracer being powered. The effective resolution of the setting is limited to 1/30th of the calculated full on power.
- Do not set the MAXIMUM POWER below full output for applications that do not require control of power.
- This feature is affected by the VOLTAGE and CURRENT TURNS RATIO settings. The maximum range using adjusted values of voltage and current is 65,535 watts. See sections 3.5.21 on page 26 and 3.5.22 on page 26 for more information regarding the turns ratio functions.

3.5.10 3-PHASE POWER CALCULATION (V3.11 AND UP)

Purpose: This parameter selects the type of power calculation that the HTC is to perform.

Setting: NO or YES

Procedure: If an automatic 3-phase power calculation is desired, select YES. If a normal power calculation is desired, select NO.



Note: For the total 3-phase power calculation to be accurate the following conditions must be met:

- All three phases must be balanced and star ("Y") connected
- The measured corrected current is one of the phase currents
- The measured corrected voltage is the line to line voltage

The formula used to calculate this total power is: $P_{\text{total}} = \sqrt{3} \times I_{\text{phase}} \times V_{\text{line-line}}$

3.5.11 TS FAIL MODE (V3.11 AND UP)

Purpose: This parameter determines whether the HTC turns the output switch ON or OFF if all selected temperature sensors fail to provide a control temperature.

Setting: OFF or ON

Procedure: If the HTC should turn the output switch off when it cannot read a valid control temperature, then select OFF; otherwise, if the output switch should turn on, then select ON.



Note: This parameter is part of the TS CONTROL MODE.

3.5.12 TEMPERATURE SENSOR CONTROL MODE

Purpose: The TS CONTROL MODE allows the selection of one of eleven possible temperature control modes for the controller. The different modes allow redundant fail-safe temperature sensing, averaging, or minimum maintain temperature control.

Setting: Select one of the following eleven possible modes:

Control TS and Description

CONTROL USING TS 1, FAIL OFF/ON
CONTROL USING TS 1, FAIL TO TS 2
CONTROL USING TS 2, FAIL OFF/ON
CONTROL USING TS 2, FAIL TO TS 1
CONTROL ON AVERAGE, FAIL OFF/ON
CONTROL ON AVERAGE, FAIL TO GOOD
CONTROL ON LOWEST, FAIL OFF/ON
CONTROL ON LOWEST, FAIL TO GOOD

The following are only available in V3.11+:

CONTROL USING EXT. INPUT, FAIL OFF/ON
CONTROL USING EXT. INPUT, FAIL TO TS 1
CONTROL USING EXT. INPUT, FAIL TO TS 2

Where OFF/ON = Controller's output switch turned OFF or ON as determined by the TS FAIL MODE.

Example: With a TS CONTROL MODE of CONTROL ON AVERAGE, FAIL TO GOOD, the controller will measure both sensors (TS 1 and TS 2), averaging the two temperature value; display the results; and cycle the heater ON or OFF to maintain the CONTROL SETPOINT temperature. This is the primary control mode. If either sensor should fail, the controller will transfer control to the remaining "good" sensor and generate the appropriate TS 1 or TS 2 FAILURE ALARM (assuming that the alarm is enabled). The temperature will now be maintained based on this measured value. If the remaining good sensor fails, the controller will turn the heater OFF or ON as determined by the TS FAIL MODE setting. The appropriate TS 1 or TS 2 FAILURE ALARM will be also be generated.

Procedure: Select the control mode that best suits the application.



Notes:

- Ensure that TS FAILURE ALARMS are enabled. See sections 3.7.1 on page 32, 3.7.4 on page 32, and 3.7.10 on page 34 for a complete explanation of RTD failure detection in the HTC.
- If the selected TS CONTROL MODE uses the EXTERNAL INPUT then the EXTERNAL INPUT must be set to TEMPBUS™ (see Section 3.6.3). Also, the CONTROL TS FAILURE ALARM is non-latching in this mode.
- Fail safe mode is always disabled if the TS CONTROL MODE = EXT. INPUT, FAIL OFF/ON.

3.5.13 TS 1 TYPE (V3.11 AND UP)

Purpose: This parameter specifies the type of RTD that is connected to the HTC's TS 1 input.

Setting: 3-wire 100 Ω platinum or 2-(or 3-) wire 100 Ω nickel-iron (Ni-Fe)

Procedure: Select the type of RTD that is connected to the TS 1 input.



Note: If a 2-wire 100 Ω nickel-iron (Ni-Fe) RTD is selected then the TS 1 LEAD RESISTANCE must be entered manually (see section 3.5.14 on page 24).

3.5.14 TS 1 LEAD RESISTANCE (V3.11 AND UP)

(For Ni-Fe RTDs only)

Purpose: This parameter specifies the lead resistance of a 2-wire nickel-iron RTD connected to the HTC's TS 1 input.

Range: 0 to 20.00 Ω

Procedure: Measure the resistance of one of the nickel-iron RTD leads (from the RTD to the HTC's TS 1 input) and use this value as the TS 1 LEAD RESISTANCE.

3.5.15 TS 1 HIGH LIMIT CUTOUT

Purpose: When enabled, the TS 1 HIGH LIMIT CUTOUT feature will override the CONTROL SETPOINT temperature and force the controller output off if the TS 1 reading exceeds the HIGH TS 1 ALARM temperature setting. This is a non-latching condition, so once the TS 1 reading drops below the HIGH TS 1 ALARM temperature setting, the controller will resume normal operation.

Setting: ENABLE or DISABLE

Procedure: Enable or disable the cutout feature as desired.



Notes:

- The TS 1 HIGH LIMIT CUTOUT feature overrides an autocycle test. A pending autocycle will be initiated immediately after the TS 1 temperature drops below the HIGH TS 1 ALARM temperature setting.
- If a TS 1 failure occurs and the TS 1 HIGH LIMIT CUTOUT feature is enabled, the switch output will latch off regardless of the TS CONTROL MODE setting or the TS FAIL MODE setting.
- If the TS 1 HIGH LIMIT CUTOUT feature is enabled, then the HIGH TS 1 ALARM temperature setting can be set, regardless of whether the HIGH TS 1 ALARM is enabled.

3.5.16 TS 2 TYPE (V3.11 AND UP)

Purpose: This parameter specifies the type of RTD that is connected to the HTC's TS 2 input.

Setting: 3-wire 100 Ω platinum or 2- (or 3-) wire 100 Ω nickel-iron (Ni-Fe)

Procedure: Select the type of RTD that is connected to the TS 2 input.



Note: If a 2-wire 100 Ω nickel-iron (Ni-Fe) RTD is selected then the TS 2 LEAD RESISTANCE must be entered (see section 3.5.17 on page 25).

3.5.17 TS 2 LEAD RESISTANCE (V3.11 AND UP)

(For Ni-Fe RTDs only)

Purpose: This parameter specifies the lead resistance of a 2-wire nickel-iron RTD connected to the HTC's TS 2 input.

Range: 0 to 20.00 Ω

Procedure: Measure the resistance of one of the nickel-iron RTD leads (from the RTD to the HTC's TS 2 input) and use this value as the TS 2 LEAD RESISTANCE.

3.5.18 TS 2 HIGH LIMIT CUTOUT

Purpose: When enabled, the TS 2 HIGH LIMIT CUTOUT feature will override the CONTROL SETPOINT temperature and force the controller output off if the TS 2 reading exceeds the HIGH TS 2 ALARM temperature setting. This is a non-latching condition, so once the TS 2 reading drops below the HIGH TS 2 ALARM temperature setting, the controller will resume normal operation.

Setting: ENABLE or DISABLE

Procedure: Enable or disable the cutout feature as desired.



Notes:

- The TS 2 HIGH LIMIT CUTOUT feature overrides an autocycle test. A pending autocycle will be initiated immediately after the TS 2 temperature drops below the HIGH TS 2 ALARM temperature setting.
- If a TS 2 failure occurs and the TS 2 HIGH LIMIT CUTOUT feature is enabled, the switch output will latch off regardless of the TS CONTROL MODE setting or the TS FAIL MODE setting.

- If the TS 2 HIGH LIMIT CUTOFF feature is enabled, then the HIGH TS 2 ALARM temperature setting can be set, regardless of whether the HIGH TS 2 ALARM is enabled.

3.5.19 VOLTAGE SOURCE (V3.11 AND UP)

Purpose: This parameter specifies which voltage source the HTC should use for its voltage measurements.

Setting: POINT A or POINT B or FIXED

Procedure: If the HTC is not powered from a dedicated switch interface an alternate voltage source can be selected. If a fixed constant voltage value is to be used then that FIXED VOLTAGE SETTING must also be entered (see section 3.5.20 on page 26).



Notes:

- If an alternate voltage source is selected, then all voltage alarming features are disabled for this HTC and the VOLTAGE TURNS RATIO is not used.
- It is not possible to set both points to use the others' voltage source.

3.5.20 FIXED VOLTAGE SETTING (V3.11 AND UP)

(Only if VOLTAGE SOURCE = FIXED)

Purpose: This parameter specifies the voltage value that the HTC should use when the VOLTAGE SOURCE = FIXED.

Range: 0 to 1000 Volts

Procedure: Adjust the FIXED VOLTAGE setting to the desired level.



Note: All voltage alarming features are disabled for this HTC and the VOLTAGE TURNS RATIO is not used when the VOLTAGE SOURCE is set to FIXED.

3.5.21 VOLTAGE TURNS RATIO ADJUSTMENT

Purpose: The VOLTAGE TURNS RATIO adjusts voltage readings for applications where a controller is switching a load through a step-up or step-down transformer, or is being powered from a source with a different voltage level than the trace voltage.

Range: 0.10 to 9.90 (TO 1)

Procedure: Adjust the VOLTAGE TURNS RATIO to equal the ratio of the circuit voltage to the controller input voltage. Compare the indicated voltage to the measured voltage after setting the turns ratio and adjust until the two readings are as close as possible.

e.g.: Heating Circuit Voltage: 480 Volts
Module Input Voltage: 120 Volts
VOLTAGE TURNS RATIO Setting: 4.00



Notes:

- When the VOLTAGE TURNS RATIO has been set appropriately, the HTC will calculate the circuit power using the adjusted current and voltage readings. Voltage alarms also use the adjusted circuit voltages.
- The VOLTAGE TURNS RATIO is not used if the selected VOLTAGE SOURCE is not from the dedicated switch interface.

3.5.22 CURRENT TURNS RATIO ADJUSTMENT

Purpose: The CURRENT TURNS RATIO adjusts current readings for applications where a controller is monitoring a load through an external step-up or step-down current transformer.

Range: 0.10 to 60.00 (TO 1)

Procedure: Adjust the CURRENT TURNS RATIO to equal the ratio of the primary to secondary windings of the external current transformer. Compare the indicated current to the measured current after setting of the CURRENT TURNS RATIO and adjust until the two readings are as close as possible.



Note: When the CURRENT TURNS RATIO has been set appropriately, the HTC will calculate the circuit power using the adjusted current and voltage readings. Current alarms, as well as the switch and circuit breaker limiting functions, also use the adjusted circuit currents.

3.5.23 AUTOCYCLE ENABLING

Purpose: The autocycle function momentarily (approximately 10 seconds) applies power to the heating circuit at the selected interval. It is used to test the integrity of the heating circuit. Alarms present at the time of autocycle then become latched and remain active after the completion of the autocycle function. Auto-cycling effectively eliminates the need for preventive maintenance by automatically verifying the heating circuit integrity.

Setting: ENABLE or DISABLE

Procedure: Enable or disable the auto-cycling feature as desired. If the feature is disabled, you will not be prompted to enter the AUTOCYCLE INTERVAL or AUTOCYCLE UNITS.



Notes:

- Auto-cycling should always be enabled for normal operation. Disabling this feature should only be required where the HTC system is monitoring a circuit exercised by some other device or means. Although this function defeats temperature control and forces output on, the controller will continue to adjust the output for protection purposes or power limiting (SSR option only).
- Auto-cycling is inhibited if the controller is in the load shedding mode. See section 5.3 on page 52.
- If auto-cycling is enabled, the HTC will always autocycle for 10 seconds when power is initially applied.
- If auto-cycling is enabled, TS FAIL MODE = OFF and all the control temperature sensors have failed, the HTC will still perform an autocycle.
- If an alarm condition, with an alarm filter time greater than 0, appears during the auto-cycling, then the autocycle may be extended (past the 10 seconds) until the alarm filter time has expired.

3.5.24 AUTOCYCLE TIME INTERVAL

Purpose: AUTOCYCLE INTERVAL is the number of hours/minutes between successive heating circuit integrity tests depending on the AUTOCYCLE UNITS specified.

Range: 1 to 240

Procedure: Set the AUTOCYCLE INTERVAL to the desired time period.



Notes:

- When using proportional ambient contactor mode, the CYCLE TIME setting should be less than the AUTOCYCLE INTERVAL otherwise auto-cycling could affect the duty cycle.
- If an AC ALARM becomes active during an autocycle, but the AUTOCYCLE INTERVAL expires prior to the corresponding ALARM FILTER time, then auto-cycling will continue until the ALARM FILTER time has elapsed.
- For the earliest possible alarming of heating circuit problems the AUTOCYCLE INTERVAL should be set to a small value.

3.5.25 AUTOCYCLE TIME UNITS

Purpose: The autocycle time units parameter allows selection of minutes or hours for the AUTOCYCLE INTERVAL setting.

Setting: HOURS or MINUTES

Procedure: Set the AUTOCYCLE UNITS to the desired time units.

3.5.26 INHIBIT CONTROL (V3.00 ONLY)

Purpose: This feature allows the HTC's EXTERNAL INPUT to override the controller's temperature control and force the output switch off. This is especially useful when the user wishes to turn a controller or a group of controllers off over the summer months, during maintenance, or when a line is flowing and does not require heating.

Setting: ENABLE or DISABLE

Procedure: Enable or disable the INHIBIT CONTROL for the control point being programmed.



Notes:

- The EXTERNAL INPUT must also be programmed as INHIBIT before this parameter can be set. See section 3.6.3 on page 29 for further details.
- If the autocycle feature is enabled, it will continue to function even when the INHIBIT mode is active.
- Fail-safe mode is inactive if the INHIBIT mode is active.
- Both of the LOW TS ALARMS are inactive if the INHIBIT mode is active.

3.5.27 OVERRIDE SOURCE (V3.11 AND UP)

Purpose: An override signal can be sent to the HTC from one of two sources. This override signal can be used to override the controller's temperature control and force the output switch off or on. This is especially useful when the user wishes to turn a controller or a group of controllers off over the summer months, during maintenance, or when a line is flowing and does not require heating.

Setting: REMOTE or EXT. INPUT

Procedure: If the override signal will be generated remotely and received by the HTC via the optional communications interface, select REMOTE as the OVERRIDE SOURCE. If the override signal will be received by the HTC via the external input terminals on the 920 terminal board, select EXTERNAL INPUT as the OVERRIDE SOURCE.



Notes:

- If the EXTERNAL INPUT is not configured as either INHIBIT or FORCE ON then OVERRIDE SOURCE will always automatically be set to REMOTE. See section 3.6.3 on page 29 for further details.
- If the autocycle feature is enabled, it will continue to function even when an INHIBIT override signal is being received as long as load shedding is not active.
- Fail-safe mode is inactive if an INHIBIT override signal is being received.
- Load shedding and fail-safe mode are inactive if a FORCE ON override signal is being received.
- Only the LOW TS ALARMS for temperature sensors used by the TS CONTROL MODE are inactive if an INHIBIT override signal is being received.

3.5.28 LOAD SHEDDING ENABLING

Purpose: The load shedding function allows the controller output to be forced OFF by way of a remote contact input on the 780 Group Communications Controller or using the communications port and an upstream device. It may be used to turn OFF the output of one or more controllers in order to reduce energy consumption to avoid peak demand surcharges, remove power from unused circuits, or remove power from circuits that may be subjected to steam cleaning.

Setting: ENABLE or DISABLE

Procedure: Enable or disable the load shedding control mode as desired.



Notes:

- To completely configure the HTC for load shedding operation, the following additional parameters must be set up if using the Model 780/GCC-9000:
 - Fail-safe mode
 - Load shedding GCC contact association
- These additional parameters may only be accessed using the Group Communications Controller. See the appropriate section of the GCC manual for further details.
- Fail-safe mode is not supported when using proportional ambient SSR mode or proportional ambient contactor mode.
- Fail-safe mode is not supported if the TS CONTROL MODE = EXT. INPUT, FAIL OFF/ON.
- For fail-safe mode to function, at least one LOW TS ALARM of the controlling temperature sensor(s) must be enabled and the corresponding LOW TS ALARM temperature setting must be less than the CONTROL SETPOINT temperature.

3.5.29 CONSOLE SETPOINT MAXIMUM (V3.11 AND UP)



Note: The CONSOLE SETPOINT MAXIMUM is not displayed on the optional 920 Operator Console.

Purpose: When using an optional 920 Operator Console (for V3.11 and up) the maximum setting of the CONTROL SETPOINT temperature may be limited to the CONSOLE SETPOINT MAXIMUM value. This is a safety feature to prevent users in the field from modifying the CONTROL SETPOINT temperature setting to a dangerous level.

Range: –76°F to 1058°F (–60°C to 570°C)

Procedure: Adjust the CONSOLE SETPOINT MAXIMUM temperature value to limit the maximum allowable CONTROL SETPOINT TEMPERATURE that may be set using the optional 920 Operator Console. The CONSOLE SETPOINT MAXIMUM may only be set using a communicating device such as the Model 780/GCC-9000. See the 780/GCC-9000 manual for the proper procedure.

3.5.30 CONSOLE SETPOINT MINIMUM (V3.11 AND UP)



Note: The CONSOLE SETPOINT MINIMUM is not displayed on the optional 920 Operator Console.

Purpose: When using an optional 920 Operator Console (for V3.11 and up) the minimum setting of the CONTROL SETPOINT temperature may be limited to the CONSOLE SETPOINT MINIMUM value. This is a safety feature to prevent users in the field from modifying the CONTROL SETPOINT temperature setting to a dangerous level.

Range: –76°F to 1058°F (–60°C to 570°C)

Procedure: Adjust the CONSOLE SETPOINT MINIMUM temperature value to limit the minimum allowable CONTROL SETPOINT TEMPERATURE that may be set using the optional 920 Operator Console. The CONSOLE SETPOINT MINIMUM may only be set using a communicating device such as the Model 780/GCC-9000. See the 780/GCC-9000 manual for the proper procedure.

3.6 Common Controller Setup

The following section describes the setup parameters that are common for both of the two control points—Point A and Point B. These parameters need only be configured once to define their operation for both control points.

3.6.1 TEMPERATURE DISPLAY UNITS

Purpose: This allows selection of the type of temperature units to display when using the 920 Operator Console. All temperature-related values will be displayed in the selected units.



Note: This setting will not affect the temperature units displayed at a 780/GCC-9000 Group Communications Controller. The GCC may be set independently.

Setting: DEGREES C or DEGREES F

Procedure: Adjust the setting to the desired temperature units (°F or °C).



Note: To minimize possible confusion, temperature units should be set the same on the HTC and any other communicating devices.

3.6.2 VERSION OF FIRMWARE AND HARDWARE

Purpose: The first three digits of the version number indicate the revision level of the firmware programmed into the controller. As new features are added to the HTC, the firmware revision level is incremented to allow the user to determine which features are available for the particular unit being used. The fourth digit (V3.11 and up only) indicates the type of 920 hardware. A “0” indicates that an EPROM is being used, which means the firmware cannot be upgraded without replacing the EPROM. A “1” indicates that the firmware is stored in a FLASH memory device and can be upgraded via the optional communications interface.

3.6.3 EXTERNAL INPUT PORT

Purpose: This input port may be used as an OVERRIDE SOURCE or a TEMPBUS™ temperature source for either point. As an OVERRIDE SOURCE, it can sense a remote dry contact closure and

override the controller's temperature control and force its output switch off or on. As a TEMPBUS™ temperature source, either controller can control its output switch using the TEMPBUS™ temperature rather than temperatures from TS 1 or TS 2.

Setting: NOT USED, TEMPBUS (V3.11+), INHIBIT or FORCE ON (V3.11+)

Procedure: If the EXTERNAL INPUT is not being used by either point, select NOT USED. If either point requires a TEMPBUS™ temperature signal, select TEMPBUS™ and set the point TS CONTROL MODE to a mode using the EXTERNAL INPUT (see section 3.5.12 on page 24). For TEMPBUS™ operation description see section 5.4 on page 53.

If a remote dry contact closure should force either point's output switch off, select INHIBIT. If a remote dry contact closure should force either point's output switch on, select **FORCE ON**.

If the EXTERNAL INPUT is set to INHIBIT or FORCE ON, the point's OVERRIDE SOURCE (for V3.11+) must be set to EXT. INPUT or its INHIBIT CONTROL (for V3.00) must be enabled.



Notes:

- When used with the INHIBIT/FORCE ON feature, a contact closure sensed by the EXTERNAL INPUT will initiate the INHIBIT/FORCE ON mode. An open input will cause the controller to revert to normal temperature control operation. One possible use of the INHIBIT feature is to use an external device (such as a flow meter) to provide a contact closure if there is flow in a line. As long as the line has adequate flow, the heating will be off (INHIBITED from operating). See Appendix C on page 68 for typical connection diagrams when using this input.
- EXTERNAL INPUT must be set to INHIBIT or FORCE ON before OVERRIDE SOURCE (for V3.11+) can be set to EXT. INPUT; or INHIBIT CONTROL (for V3.00) can be edited. For V3.11 and up, setting EXTERNAL INPUT to NOT USED or TEMPBUS™ will automatically set OVERRIDE SOURCE to REMOTE.

3.6.4 EXTERNAL OUTPUT PORT

Purpose: The EXTERNAL OUTPUT port can be programmed to allow Point A to function as a “master” 920 HTC to control up to 25 “slave” 920 HTC units. A “master” can either force its “slaves” to override their temperature control and force their output switch off (INHIBIT), or it can send its control temperature to its “slaves” so they can do their own temperature control using this temperature (TEMPBUS™).

An INHIBIT “master” may be useful when a number of “slave” controllers use their own RTDs, but are to be turned off based on the ambient temperature. This will allow disabling of the “slave” controllers during the summer months, during a maintenance shutdown, etc.

A TEMPBUS™ “master” may be useful when a number of “slave” controllers do not have their own temperature sensors and are set to control the ambient temperature.

Setting: NOT USED, TEMPBUS (V3.11+) or INHIBIT

Procedure: Select NOT USED if Point A is not a “master” controlling the EXTERNAL OUTPUT port. Select INHIBIT if Point A will be controlling the EXTERNAL OUTPUT port as an INHIBIT “master.” Select TEMPBUS™ if Point A will be sending its control temperature out the EXTERNAL OUTPUT port. For TEMPBUS™ operation description see section 5.4 on page 53.



Notes:

- The “master” and “slave” controllers must be installed in the same enclosure. The EXTERNAL OUTPUT PORT signal is not intended to be connected over extended distances or between enclosures.
- If EXTERNAL OUTPUT is set to INHIBIT, then the DEADBAND parameter for Point A will be used to define the operation of the EXTERNAL OUTPUT port, even though the SWITCH CONTROL MODE for Point A may not be set for DEADBAND operation. See section 3.5.5 on page 22 for additional details regarding the DEADBAND mode.
- If the EXTERNAL INPUT PORT input is not being used, Point B may be configured as a “slave” for a controller with its Point A configured as a “master.”

3.6.5 FLASH ALARM OUTPUT SETTING

Purpose: Programs the alarm output relay for flashing or steady output in case of an alarm condition.

Setting: YES (Flash) or NO (Steady)

Procedure: Set the alarm output relay to flash or not to flash on an alarm condition, whichever suits the application.



Notes:

- If the alarm output is used to drive a pilot light, select YES to enable flashing operation. When the output is also configured for normally closed operation, the pilot light will be on steady for normal operation, flash in case of alarm and be extinguished due to a bulb failure or loss of power.
- If multiple alarm outputs from different controllers are wired in series (i.e.: multipoint panels), set this parameter to NO (steady).

3.6.6 ALARM OUTPUT NORMAL STATE

Purpose: Configures the alarm output relay for normally open or normally closed operation. The normal condition is assumed to be when the HTC is powered and no alarms exist.

Setting: N.O. (Normally Open) or N.C. (Normally Closed)

Procedure: Set the alarm output relay to normally open or normally closed to suit the application.



Note: If a pilot light is used for indication of alarms, normally closed operation provides a steady illumination of the lamp when the circuit is operating correctly. A light that is flashing or out indicates a fault condition. A burned out lamp is readily identified if the HTC is set to flash the alarm output relay in case of alarm. See the section 3.6.5 on page 31.

3.6.7 LANGUAGE

Purpose: Defines which language the optional 920 Operator Console uses when prompting the user for input and/or displaying messages and status.

Setting: ENGLISH or FRANCAIS

Procedure: Select the language of choice—ENGLISH for English prompts and messages, or FRANCAIS for French prompts and messages.

3.6.8 POINT B USED

Purpose: Allows the second control point (Point B) to be disabled when it is not being used. This is an easy method of disabling all ALARMS, etc. without having to set each parameter.

Setting: YES or NO

Procedure: Select NO to disable Point B, choose YES to use Point B.



Notes:

- Selecting NO has the following effect on Point B parameters:
 - All relevant ALARMS are masked
 - The control output is held off
 - No programming, configuration, or messages are available using the optional 920 Operator Console
- Complete Point B access remains available using the optional communications interface.

3.6.9 PASSCODE

See section 3.10.1 on page 45.

3.6.10 SCROLL DELAY SETTING (V3.11 AND UP)

Purpose: For ease of viewing, allows the user to modify the speed at which information is scrolled on the optional Operator Console.

Range: 0.07 to 0.25 seconds

Procedure: Decreasing the scroll delay value will cause the information on the display to scroll faster. Increasing the scroll delay value will cause the information on the display to scroll slower.

3.7 Temperature Alarms

This section defines the temperature-related alarming functions of the 920 controller. These parameters must be set up individually for both Point A and Point B.

3.7.1 TEMPERATURE SENSOR 1 FAILURE ALARM

Purpose: Enabling TS 1 FAILURE will provide indication of an open or shorted failure of TS 1.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable alarming of a failed first temperature sensor (TS 1) as required.



Notes:

- This failure alarm should be enabled if a temperature sensor is connected to the TS 1 input.
- This alarm is always latched and must be reset by the user.

3.7.2 LOW TEMPERATURE SENSOR 1 ALARM

Purpose: If enabled, the LOW TS 1 ALARM allows for alarming of low temperature conditions as sensed by the first temperature sensor (TS 1).

Alarm Mask: ENABLE or DISABLE

Range: -76°F to 1058°F (-60°C to 570°C)

Procedure: Adjust the LOW TS 1 ALARM temperature setpoint to the desired value. Note that the LOW TS 1 ALARM must be enabled in order to adjust the LOW TS 1 ALARM temperature setpoint.



Notes:

- This alarm should normally be enabled and the setpoint should be appropriate for the heating application. Maintaining a minimum 5°C differential between low temperature alarming and the CONTROL SETPOINT temperature will minimize nuisance alarming due to momentary dips in temperature. Another alternative to this is to configure the controller for non-latching temperature alarms.
- This alarm must be enabled and its setpoint must be below the CONTROL SETPOINT temperature if fail-safe mode uses the temperature from TS 1.



3.7.3 HIGH TEMPERATURE SENSOR 1 ALARM

Purpose: If enabled, the HIGH TS 1 ALARM allows for alarming of high temperature conditions as sensed by the first temperature sensor (TS 1).

Alarm Mask: ENABLE or DISABLE

Range: -76°F to 1058°F (-60°C to 570°C)

Procedure: Adjust the HIGH TS 1 ALARM temperature setpoint to the desired value. Note that the HIGH TS 1 ALARM must be enabled in order to adjust the HIGH TS 1 ALARM temperature setpoint unless the TS 1 HIGH LIMIT CUTOUT feature is enabled.



Note: This alarm should only be used for applications involving a product that is sensitive to over temperature. General use may result in nuisance alarms due to the outflow of hot product or steam. This may be a case where the alarm should be enabled and nonlatching temperature alarming used. A high temperature condition resulting from a forced on failure of the heating circuit should first be alarmed by the SWITCH FAILURE ALARM. See section 3.8.18 on page 40 for more information.

3.7.4 TEMPERATURE SENSOR 2 FAILURE ALARM

Purpose: Enabling TS 2 FAILURE provides indication of an open or shorted failure of TS 2.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable alarming of a failed second temperature sensor (TS 2) as required.

**Notes:**

- If no second sensor is installed, disable this alarm. This failure alarm should be enabled if a second temperature sensor is connected to the TS 2 input.
- This alarm is always latched and must be reset by the user.

3.7.5 LOW TEMPERATURE SENSOR 2 ALARM

Purpose: If enabled, the LOW TS 2 ALARM allows for alarming of low temperature conditions as sensed by the second temperature sensor (TS 2).

Alarm Mask: ENABLE or DISABLE

Range: -76°F to 1058°F (-60°C to 570°C)

Procedure: Adjust LOW TS 2 ALARM temperature setpoint to the desired value. Note that the LOW TS 2 ALARM must be enabled in order to adjust the LOW TS 2 ALARM temperature setpoint.

**Notes:**

- If no second sensor is installed, this alarm should be disabled. This alarm should be enabled and the setpoint should be appropriate for the heating application. Maintaining a minimum 5°C differential between low temperature alarming and the CONTROL SETPOINT temperature minimizes nuisance alarming due to momentary dips in temperature. Another alternative to this is to configure the controller for non-latching temperature alarms.
- This alarm must be enabled and its setpoint must be below the CONTROL SETPOINT temperature if fail-safe mode uses the temperature from TS 2.

3.7.6 HIGH TEMPERATURE SENSOR 2 ALARM

Purpose: If enabled, the HIGH TS 2 ALARM allows for alarming of high temperature conditions as sensed by the second temperature sensor (TS 2).

Alarm Mask: ENABLE or DISABLE

Range: -76°F to 1058°F (-60°C to 570°C)

Procedure: Adjust the HIGH TS 2 ALARM temperature setpoint to the desired value. Note that the HIGH TS 2 ALARM must be enabled in order to adjust the HIGH TS 2 ALARM temperature setpoint unless the TS 2 HIGH LIMIT CUTOFF feature is enabled.



Note: If no second sensor is installed, disable this alarm. This alarm may be used for applications where a product that is sensitive to over temperature is involved. General usage could result in nuisance alarms due to the flow of hot product or steam out. This may be a case where the alarm could be enabled and non-latching temperature alarming used. A high temperature condition resulting from a forced on failure of the heating circuit should first be alarmed by the SWITCH FAILURE ALARM. See section 3.8.18 on page 40 for more information.

3.7.7 LOW TEMPERATURE SENSOR ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The LOW TS ALARM FILTER will prevent LOW TS 1 and/or LOW TS 2 ALARMS from being indicated until their corresponding alarm condition has existed for the duration of the LOW TS ALARM FILTER time.

Range: 0 to 999 Minutes

Procedure: Adjust the LOW TS ALARM FILTER time to the desired value. Note that either the LOW TS 1 ALARM and/or the LOW TS 2 ALARM must be enabled in order to adjust the LOW TS ALARM FILTER time.

**Notes:**

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, then the alarm will not be indicated again until the entire alarm filter time has expired.

3.7.8 HIGH TEMPERATURE SENSOR ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The HIGH TS ALARM FILTER will prevent HIGH TS 1 and/or HIGH TS 2 ALARMS from being indicated until their corresponding alarm condition has existed for the duration of the HIGH TS ALARM FILTER time.

Range: 0 to 999 minutes

Procedure: Adjust the HIGH TS ALARM FILTER time to the desired value. Note that either the HIGH TS 1 ALARM and/or the HIGH TS 2 ALARM must be enabled in order to adjust the HIGH TS ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.
- The HIGH TS ALARM FILTER time setting does not affect the cutout time when the HIGH LIMIT CUTOFF feature is enabled.

3.7.9 LATCH TEMPERATURE SENSOR ALARMS SETTING

Purpose: This allows for the selection of automatic clearing of all HIGH and LOW TS ALARMS (non-latching) when a temperature alarm condition no longer exists or permanent alarming of such a condition (latching) until the alarm is manually reset.

Setting: YES (LATCHING) or NO (NONLATCHING)

Procedure: Adjust the LATCH TS ALARMS setting to the desired mode (latching or nonlatching).



Notes:

- If your application is subject to periodic situations where cold or hot product is part of the process, it may be appropriate to configure the HTC for nonlatching temperature alarms to avoid nuisance alarms. If it is important to be aware of any temperature alarm conditions that may have existed in a pipe, the HTC should be configured for latching temperature alarms.
- This setting does not affect the TS FAILURE ALARMS; these are always latching.

3.7.10 CONTROL TEMPERATURE SENSOR FAILURE ALARM

Purpose: CONTROL TS FAILURE ALARM indicates a failure of the temperature sensor designated as the control sensor.

One of eleven TS CONTROL MODES may be selected. These modes determine which TS INPUT and/or EXT. INPUT is designated to provide the control temperature. See section 3.5.12 on page 24 for a full description of the temperature sensor control designations.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable the alarming of a failure of the designated control temperature sensor as required.



Note: This alarm should always be enabled. If the controller experiences a CONTROL TS FAILURE it will turn the output off or on (as specified by TS FAIL MODE) until this alarm is cleared. If the TS CONTROL MODE uses the EXTERNAL INPUT, a CONTROL TS FAILURE is self-clearing (i.e., is non-latching).

3.8 Other Alarms

This Section defines the nontemperature-related alarming functions of the 920 controller: current, ground fault, voltage and resistance. These parameters must be set up individually for both Point A and Point B.

3.8.1 LOW LOAD CURRENT ALARM

Purpose: Alarms current levels that are lower than a preset limit for the application. Monitoring for lower-than-expected current levels may be an effective means of continuity monitoring. See also HIGH RESISTANCE ALARM in section 3.8.14 on page 39.

Alarm Mask: ENABLE or DISABLE

Range: 0.3 to 100.0 amps
(CURRENT TURNS RATIO = 1.00)

Procedure: Adjust the LOW CURRENT ALARM level to the desired value. Note that the LOW CURRENT ALARM must be enabled in order to adjust the LOW CURRENT ALARM level. Also note that the LOW CURRENT ALARM level is affected by the CURRENT TURNS RATIO setting. The absolute maximum adjusted LOW CURRENT ALARM level is 300.0 amps. The absolute minimum adjusted LOW CURRENT ALARM level is 0.1 amps. See section 3.5.22 on page 26 for more information regarding the CURRENT TURNS RATIO function.



Notes (V3.00 only):

- To minimize nuisance LOW CURRENT ALARMS, the HTC must detect a current level less than the LOW CURRENT ALARM setpoint for a period longer than approximately 20 consecutive seconds.
- For series-type heating cables, adjusting the LOW CURRENT ALARM to 50% of full load current will properly alarm a problem and reduce nuisance alarms due to voltage dips. Parallel heaters should be adjusted to a level as close as possible to full load current but lower than the current at worst-case voltage. The low current setting as a percentage of full load current will vary depending on the facility and its power system.
- A LOW CURRENT ALARM may also result from a switch failed open. The controller cannot detect a switch failure due to no current. A no current condition would be identified by a LOW CURRENT ALARM (if enabled) and the analog value reported with the alarm will be 0.0 A.
- It may be advantageous to consider using the HIGH RESISTANCE ALARM to indicate a cable fault when using certain types of heaters. See sections 3.8.12 on page 38 and 3.8.14 on page 39 for an explanation of the resistance alarming feature.

3.8.2 LOW LOAD CURRENT ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The LOW CURRENT ALARM FILTER will prevent LOW LOAD CURRENT ALARMS from being indicated until a low current condition has existed for the duration of the LOW CURRENT ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the LOW CURRENT ALARM FILTER time to the desired value. Note that the LOW CURRENT ALARM must be enabled in order to adjust the LOW CURRENT ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.3 HIGH LOAD CURRENT ALARM

Purpose: Alarms current levels that are higher than a preset limit for the application.

Alarm Mask: ENABLE or DISABLE

Range: 0.3 to 100.0 amps
(CURRENT TURNS RATIO = 1.00)

Procedure: Adjust the HIGH CURRENT ALARM level to the desired value. Note that the HIGH CURRENT ALARM must be enabled in order to adjust the HIGH CURRENT ALARM level. Also note that the HIGH CURRENT ALARM level is affected by the CURRENT TURNS RATIO setting. The absolute maximum adjusted HIGH CURRENT ALARM level is 300.0 amps. The absolute minimum adjusted

HIGH CURRENT ALARM level is 0.1 amps. See section 3.5.22 on page 26 for more information regarding the CURRENT TURNS RATIO function.



Note: As the HTC automatically protects itself from overload, it would not normally be necessary to enable this alarm. This automatic protection can be used effectively to guard against accidental paralleling of heating circuits. In-rush or cold start currents typically associated with self-regulating cables may cause nuisance HIGH CURRENT ALARMS. If this is undesirable the alarm should be disabled.

3.8.4 HIGH LOAD CURRENT ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The HIGH CURRENT ALARM FILTER will prevent HIGH LOAD CURRENT ALARMS from being indicated until a high current condition has existed for the duration of the HIGH CURRENT ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the HIGH CURRENT ALARM FILTER time to the desired value. Note that the HIGH CURRENT ALARM must be enabled in order to adjust the HIGH CURRENT ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.5 HIGH GROUND-FAULT CURRENT ALARM

Purpose: Alarms ground-fault current levels which are higher than a preset limit for the application.

Alarm Mask: ENABLE or DISABLE

Range: 20 to 250 mAmps

Procedure: Adjust the HIGH GFI ALARM level to the desired value. Note that the HIGH GFI ALARM must be enabled in order to adjust the HIGH GFI level.

3.8.6 HIGH GROUND-FAULT CURRENT ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The HIGH GFI ALARM FILTER will prevent HIGH GFI ALARMS from being indicated until a high GFI condition has existed for the duration of the HIGH GFI ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the HIGH GFI ALARM FILTER time to the desired value. Note that the HIGH GFI ALARM must be enabled in order to adjust the HIGH GFI ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.7 GROUND-FAULT TRIP ALARM

Purpose: This value sets the upper limit of allowable ground-fault leakage current. Exceeding this limit will result in the output switch being latched off and the GFI TRIP ALARM activated to indicate a ground fault condition.

Alarm Mask: ENABLE or DISABLE

Range: 20 to 250 mAmps

Procedure: If ground-fault tripping is desired, enable the GFI TRIP ALARM and adjust the GF TRIP CURRENT to the desired value. To disable ground-fault tripping, disable the alarm. Note that the GFI TRIP ALARM must be enabled in order to adjust the G.F. TRIP CURRENT level.



Caution: *In order to implement a ground-fault trip function, all nongrounded power conductors must be opened upon detection of a ground-fault condition.*



Note: National Electrical Codes require that all legs of non-neutral based power sources be opened upon detection of a ground fault. Multipole switch configurations should be used on non-neutral based power systems. Check the requirements with your local electrical authority.

3.8.8 LOW VOLTAGE ALARM

Purpose: Alarms voltage levels that are lower than a preset limit for the application.

Alarm Mask: ENABLE or DISABLE

Range: 10 to 330 volts (VOLTAGE TURNS RATIO = 1.00)

Procedure: Adjust the LOW VOLTAGE ALARM level to the desired value. The LOW VOLTAGE ALARM must be enabled to adjust the LOW VOLTAGE ALARM level. Also, the LOW VOLTAGE ALARM level is affected by the VOLTAGE TURNS RATIO setting. The absolute maximum adjusted LOW VOLTAGE ALARM level is 1000 volts. The absolute minimum adjusted LOW VOLTAGE ALARM level is 1 volt. See section 3.5.21 on page 26 for more information regarding the VOLTAGE TURNS RATIO.



Notes:

- The LOW VOLTAGE ALARM is only available if VOLTAGE SOURCE is set to the Point being used.
- The LOW VOLTAGE ALARM should always be enabled. Since the HTC may be powered from either of two switch interface modules (assuming a dual-point installation), the loss of power on one circuit will not necessarily be indicated at the alarm output or as a communications failure.

3.8.9 LOW VOLTAGE ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The LOW VOLTAGE ALARM FILTER will prevent LOW VOLTAGE ALARMS from being indicated until a low voltage condition has existed for the duration of the LOW VOLTAGE ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the LOW VOLTAGE ALARM FILTER time to the desired value. The LOW VOLTAGE ALARM must be enabled to adjust the LOW VOLTAGE ALARM FILTER time. Also, the LOW VOLTAGE ALARM FILTER is only available if VOLTAGE SOURCE is set to the Point being used.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.10 HIGH VOLTAGE ALARM

Purpose: Alarms voltage levels that are higher than a preset limit for the application. Serves as a monitor of the voltage used to power the trace circuit.

Alarm Mask: ENABLE or DISABLE

Range: 10 to 330 volts (VOLTAGE TURNS RATIO = 1.00)

Procedure: Adjust the HIGH VOLTAGE ALARM level to the desired value. The HIGH VOLTAGE ALARM must be enabled in order to adjust the HIGH VOLTAGE ALARM level. Also, the HIGH VOLTAGE ALARM level is affected by the VOLTAGE TURNS RATIO setting. The absolute maximum adjusted HIGH VOLTAGE ALARM level is 1000 volts. The absolute minimum adjusted HIGH VOLTAGE ALARM level is 1 volt. See section 3.5.21 on page 26 for more information regarding the VOLTAGE TURNS RATIO function.



Note: The HIGH VOLTAGE ALARM is only available if VOLTAGE SOURCE is set to the Point being used.

3.8.11 HIGH VOLTAGE ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The HIGH VOLTAGE ALARM FILTER will prevent HIGH VOLTAGE ALARMS from being indicated until a high voltage condition has existed for the duration of the HIGH VOLTAGE ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the HIGH VOLTAGE ALARM FILTER time to the desired value. The HIGH VOLTAGE ALARM must be enabled to adjust the HIGH VOLTAGE ALARM FILTER time. Also, the HIGH VOLTAGE ALARM FILTER is only available if VOLTAGE SOURCE is set to the Point being used.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.12 LOW RESISTANCE ALARM

Purpose: Alarms heater resistance levels that have decreased from the NOMINAL RESISTANCE setting by more than the selected amount.

Alarm Mask: ENABLE or DISABLE

Range: 1 to 100% (deviation from NOMINAL RESISTANCE)

Procedure: Adjust the LOW RESISTANCE ALARM deviation to the desired value. The LOW RESISTANCE ALARM must be enabled in order to adjust the LOW RESISTANCE deviation.



Notes:

- This feature is not normally enabled. It can be used effectively to guard against accidental paralleling of heating circuits. Be careful when using this alarm feature with heating cables that exhibit a variable resistance with temperature. Low resistance alarming may not be practical when the load has an increasing resistance with temperature (such as self-regulating cables).
- Use of the LOW RESISTANCE ALARM assumes that the controller power is derived from the same circuit as the tracing power (either by direct connection or through a step-down transformer). Disable this alarm if the controller is powered from a separate circuit.
- No LOW RESISTANCE ALARMS will be generated if the measured voltage is below the LOW VOLTAGE ALARM setpoint, regardless of whether the LOW VOLTAGE ALARM is enabled. This stops an alarm from being generated when the circuit power is turned off. If the LOW VOLTAGE ALARM is disabled ensure that the LOW VOLTAGE setpoint is set to a relevant level otherwise no LOW RESISTANCE ALARMS will occur.
- LOW RESISTANCE ALARMS will only be generated if the output switch is on.

3.8.13 LOW RESISTANCE ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The LOW RESISTANCE ALARM FILTER will prevent LOW RESISTANCE ALARMS from being indicated until a low resistance condition has existed for the duration of the LOW RESISTANCE ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the LOW RESISTANCE ALARM FILTER time to the desired value. The LOW RESISTANCE ALARM must be enabled to adjust the LOW RESISTANCE ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.14 HIGH RESISTANCE ALARM

Purpose: Alarms heater resistance levels that have increased from the NOMINAL RESISTANCE setting by more than the selected amount. The HIGH RESISTANCE ALARM may be used to indicate an open or a high resistance connection or, when using constant-wattage parallel cables, may indicate the failure of one or more heating zones. It may also be used to monitor a failed series-type cable or connection in 3-phase applications while minimizing nuisance alarms created by voltage fluctuations.

Alarm Mask: ENABLE or DISABLE

Range: 1 to 250% (deviation from NOMINAL RESISTANCE)

Procedure: Adjust the HIGH RESISTANCE ALARM level to the desired value. The HIGH RESISTANCE ALARM must be enabled to adjust the HIGH RESISTANCE deviation.



Notes:

- Using the LOW CURRENT ALARM feature to ensure that unexpected decreases in current consumption by the heating cable are alarmed is a reliable method of monitoring the integrity of series-type heating cables. When using parallel-type heaters (zoned constant-wattage or self-regulating) or in 3-phase installations, the LOW CURRENT ALARM setting must be chosen as close as possible to the lowest expected current to detect failed zones, cable degradation, or a lost phase. The problem with such a close setting is that it inevitably leads to nuisance alarms, particularly when voltage fluctuations are present. By using the HIGH RESISTANCE ALARM, nuisance alarms due to voltage dips may be minimized.
- Use of the HIGH RESISTANCE ALARM assumes that the controller power is derived from the same circuit as the tracing power (either by direct connection or through a step-down transformer). Disable this alarm if the controller is powered from a separate circuit.
- Be careful when using this alarm feature with heating cables that exhibit a variable resistance with temperature. High resistance alarming may not be as effective if the load has a decreasing resistance with temperature.
- No HIGH RESISTANCE ALARMS will be generated if the measured voltage is below the LOW VOLTAGE ALARM setpoint, regardless of whether the LOW VOLTAGE ALARM is enabled. This stops an alarm from being generated when the circuit power is turned off. If the LOW VOLTAGE ALARM is disabled ensure that the LOW VOLTAGE setpoint is set to a relevant level, otherwise no HIGH RESISTANCE ALARMS will occur.
- HIGH RESISTANCE ALARMS will only be generated if the output switch is on.

3.8.15 HIGH RESISTANCE ALARM FILTER TIME SETTING (V3.11 AND UP)

Purpose: The HIGH RESISTANCE ALARM FILTER will prevent HIGH RESISTANCE ALARMS from being indicated until a high resistance condition has existed for the duration of the HIGH RESISTANCE ALARM FILTER time.

Range: 0 to 12 seconds

Procedure: Adjust the HIGH RESISTANCE ALARM FILTER time to the desired value. The HIGH RESISTANCE ALARM must be enabled to adjust the HIGH RESISTANCE ALARM FILTER time.



Notes:

- If an alarm condition appears and then disappears before the alarm filter time has expired, the filter timer is reset and the alarm condition must exist again for the entire alarm filter time before the corresponding alarm will be indicated.
- If the user resets an alarm while the alarm condition is still exists, the alarm will not be indicated again until the entire alarm filter time has expired.

3.8.16 NOMINAL RESISTANCE SETTING

Purpose: This parameter defines the nominal expected heater resistance. A value must be entered by the user to allow the HIGH and LOW RESISTANCE ALARMS to be used. In installations where the power source may experience periodic fluctuations (surges and/or brown-out conditions), alarming on resistance deviation offers an improved method of monitoring tracer integrity over simple LOW and HIGH CURRENT ALARMS. Since the ratio of voltage to current is

monitored, the HIGH and LOW RESISTANCE ALARMS offer cable monitoring that is relatively immune to voltage fluctuations.

Range: 2.00 to 2000.00 Ω

Procedure: The NOMINAL RESISTANCE value can only be set if either the LOW RESISTANCE and/or the HIGH RESISTANCE ALARMS are enabled. Once the controller and the heating cable have been installed, the following procedure should be used to determine the NOMINAL RESISTANCE setting:

- Adjust the CONTROL SETPOINT temperature to turn on the output switch.
- Allow the load to come up to design temperature and its power consumption to stabilize.
- Using the 920 Operator Console, access the RESISTANCE reading and record its value. Return the CONTROL SETPOINT temperature to its proper setting.
- Enter the recorded resistance value as the NOMINAL RESISTANCE setting.



Note: The setup procedure outlined above may have to be repeated a number of times to arrive at a correct nominal resistance setting. This value will be affected by the heating cable temperature, which in turn is affected by ambient temperature, insulation level, a full or empty pipe or vessel, etc.

3.8.17 OVERCURRENT TRIP ALARM (SSR ONLY)

Purpose: The overcurrent trip feature is always enabled when using an SSR output switch and is used to provide protection for the output switch. Enabling this alarm will only inform the user of an excessively high current condition and that the output switch has been latched off. During a high current condition, the controller attempts to soft start a heating cable by a technique involving measured in-rush current and the SWITCH CURRENT RATING. If the controller is unable to start the cable, it will eventually trip its output switch off and will not retry or pulse its output switch again. At this point the OVERCURRENT TRIP ALARM is latched on.



Notes:

- The controller is *not* a safety cutout or an overcurrent protective device as defined by the National and Canadian Electrical Codes (NEC and CEC). A protective device such as a circuit breaker or fuse must be included as part of a proper design and be selected in accordance with the requirements defined in the National Electrical Code (NEC) and/or the Canadian Electrical Code (CEC).
- The controller cannot protect the SSR from short circuits or excessive overcurrent conditions. Always ensure that the power is off prior to performing any maintenance or troubleshooting of the heating circuit. Verify that no damage has occurred to the cable or the controller prior to re-energizing the circuit.

Alarm Mask: ENABLE or DISABLE

Procedure: Adjust the SWITCH CURRENT RATING setting to the actual current rating of the SSR. Enable or disable the alarm as required. Note that the OVERCURRENT TRIP ALARM does not have to be enabled in order to adjust the SWITCH CURRENT RATING setting.



Note: This alarm should be left enabled since an overcurrent trip condition would normally represent a serious problem. This is a factory-set alarm value and disabling the alarm does not disable the overcurrent trip function. In some applications the use of self-regulating cables will produce very high in-rush currents during cold startup. These currents may exceed the overcurrent trip limit and the controller will not be able to soft start the trace circuit. If this condition persists, please contact your nearest sales office for recommendations and solutions to this problem.

3.8.18 SWITCH FAILURE ALARM

Purpose: The purpose of the SWITCH FAILURE ALARM is to indicate that an output switch failure has occurred. The controller determines that if the output switch is turned off and there is load current present, then the output switch has failed closed and the alarm is latched on.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable the alarming of an output switch that has failed in the closed position.



Note: The SWITCH FAILURE ALARM should always be enabled. A high temperature condition as a result of a failed circuit can only be caused if the output switch fails closed. When an output switch fails closed, the controller cannot turn the tracer power off, therefore no protection features are available (ground-fault trip, power limiting, etc.). If a SWITCH FAILURE ALARM is detected, the unit should be serviced immediately.

3.8.19 HTC RESET ALARM

Purpose: The HTC RESET ALARM is used to indicate:

1. Power to the HTC has been interrupted and subsequently restored.
2. A transient has caused the HTC's microprocessor to restart.
3. An internal condition has caused the HTC's microprocessor to restart its program.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable alarming on reset as desired.



Note: Normally the HTC RESET ALARM is left disabled since powering the controller off and on for maintenance or troubleshooting would require the user to reset this alarm every time. If the particular installation includes a Model 780/GCC-9000, this alarm may be left enabled since resets are not considered normal occurrences and the Model 780/GCC-9000 provides the capability to easily log and reset alarms such as these. The difference in time between when a COMMUNICATIONS FAIL ALARM and an HTC RESET ALARM are logged provide an indication of how long the circuit has been "OFF."

3.8.20 CIRCUIT BREAKER LIMITING STATUS (SSR ONLY)

Purpose: The circuit breaker limiting feature is always enabled when using an SSR output switch and is intended to prevent the circuit breaker immediately upstream of the controller from tripping during a temporary overcurrent condition. Enabling this alarm will only inform the user that circuit breaker limiting is currently active.

Alarm Mask: ENABLE or DISABLE

Procedure: Adjust the CIRCUIT BREAKER CURRENT RATING setting to the heating circuit breaker size (i.e. 15.0 or 20.0 amps). Enable or disable the alarm as required. The CIRCUIT BREAKER LIMITING ALARM need not be enabled in order to adjust the CIRCUIT BREAKER CURRENT RATING setting.



Notes:

- This is a non-latching alarm.
- This alarm is advisory. If the measured current exceeds the level that would cause the upstream circuit breaker to release, the HTC will begin to switch the SSR ON and OFF rapidly to limit the average current to an acceptable level.

3.8.21 POWER-LIMITING STATUS (SSR ONLY)

Purpose: The power-limiting feature is always enabled when using an SSR output switch and is intended to limit the average amount of power that is applied to the trace circuit. The controller measures the voltage and current of the trace circuit and will vary its output switch to limit the amount of power applied to the trace to the value set by the MAXIMUM POWER setting. Enabling this alarm will only inform the user that power limiting is currently active.

Alarm Mask: ENABLE or DISABLE

Procedure: Adjust the MAXIMUM POWER setting to the desired value. Enable or disable the alarm as required. The POWER LIMITING ALARM need not be enabled to adjust the MAXIMUM POWER setting.



Notes:

- This is a non-latching alarm.
- This alarm is advisory and is normally disabled. It will be active if the MAXIMUM POWER setting is set below the power output level required for temperature maintenance. In other words, if the circuit demands the maximum power allowed and the alarm is enabled, then

this alarm will be indicated and the output switch will pulse ON and OFF to limit the average power output to a value approximately equal to the MAXIMUM POWER setting

3.8.22 SWITCH LIMITING STATUS (SSR ONLY)

Purpose: The switch limiting feature is always enabled when using an SSR output switch and provides protection for the output switch. Enabling this alarm will only inform the user that switch limiting is currently active and an excessively high current condition is present. The controller pulses its output switch for a small number of cycles and reads the resulting current. If the measured current exceeds the SWITCH RATING setting, the duty cycle of its output switch will be varied so that an average current not exceeding the SWITCH RATING setting is maintained.

Alarm Mask: ENABLE or DISABLE

Procedure: Adjust the SWITCH CURRENT RATING setting to the actual current rating of the SSR. Enable or disable the alarm as required. The SWITCH LIMITING ALARM need not be enabled to adjust the SWITCH CURRENT rating setting.



Notes:

- This is a non-latching alarm.
- This alarm is normally enabled. Currents in this range cannot be considered normal and should be investigated.

3.8.23 CONTACTOR COUNT ALARM (V3.11 AND UP)

Purpose: Generates an alarm if the number of off-to-on transitions of a contactor reaches or exceeds the CONTACTOR COUNT ALARM setting. This serves as a method to perform preventative maintenance on the contactor before a failure is likely to occur.

Alarm Mask: ENABLE or DISABLE

Range: 0 to 999999 off-to-on transitions

Procedure: Adjust the CONTACTOR ALARM setting to the desired value. The CONTACTOR ALARM must be enabled to adjust the CONTACTOR ALARM setting.



Note: The CONTACTOR ALARM is only available if the SWITCH CONTROL MODE is set to either DEAD-BAND or PROPORTIONAL AMBIENT CONTACTOR.

3.8.24 EEROM DATA FAILURE ALARM

Purpose: The EEROM DATA FAILURE ALARM indicates that the controller has detected a failure in its nonvolatile memory.

Alarm Mask: ENABLE or DISABLE

Procedure: Enable or disable alarming of a nonvolatile memory failure as desired.



Note: The EEROM DATA FAILURE ALARM should always be enabled. This memory stores all of the controller's configuration and calibration settings and the alarm will only be generated if the microprocessor cannot bypass the failed area of its memory. This indicates an internal problem, and the control module should be replaced and returned to Tyco Thermal Controls for repair.

3.9 Communications Setup

The following section describes the setup parameters that relate to the way the controller communicates with another device. If the optional communications interface is not installed in the 920 control module, these parameters need not be configured. All these parameters are common for both of the two control points—Point A and Point B, except the HTCBUS™ ADDRESS, MODBUS™ ADDRESS, and MODBUS™ SUB ADDRESS settings, as applicable.

3.9.1 PROTOCOL

Purpose: Defines the communications language used by the controller to communicate with other devices.

Setting: HTCBUS or MODBUS ASCII (V3.11+) or MODBUS RTU (V3.11+)

Procedure: Select the HTCBUS™ protocol when communicating with existing Tyco Thermal Controls Heat Trace Control products, including the Model 780/GCC-9000 Group Communications Controller.

If you are communicating directly with the controller using a different device, select the MODBUS protocol. For a detailed description of the controller's MODBUS mapping, please refer to the separate *DigiTrace 920 Series Heat Trace Controller—Modbus Protocol Interface Mapping document* (Tyco Thermal Controls reference H57366).

3.9.2 HTCBUS™ ADDRESS

Purpose: Defines the communications address to be used by the controller when using the HTCBUS™ protocol to communicate with a Model 780/GCC-9000. When in the Point A configuration menu, this sets the Point A HTCBUS™ ADDRESS; when in the Point B configuration menu, this sets the Point B HTCBUS™ ADDRESS. Either may be set independently of the other.

Range: 1 to 16,777,215

Procedure: Set the communications address as desired. This must be an address unique to the entire communications network to avoid messaging conflicts. The HTCBUS™ protocol must be selected in order to set the HTCBUS™ ADDRESS.



Note: A unique HTCBUS™ communications address is always assigned by Tyco Thermal Controls and identified by the label on the front of the 920 control module (see Figure 3.1). Use the preassigned address whenever possible to minimize the chances of an address being duplicated in the user's system.

3.9.3 MODBUS ADDRESS (V3.11 AND UP)

Purpose: The MODBUS™ ADDRESS, along with the MODBUS™ SUB ADDRESS, defines the communications address to be used by the controller when using either MODBUS™ protocol to communicate with a MODBUS™ compatible device. When in the Point A configuration menu, this sets the Point A MODBUS™ ADDRESS; when in the Point B configuration menu, this sets the Point B MODBUS™ ADDRESS. Either may be set independently of the other.

Range: 1 to 247

Procedure: Set the communications address as desired. Together with the MODBUS™ SUB ADDRESS, this combination must be unique to the entire communications network to avoid messaging conflicts. Either MODBUS™ protocol must be selected in order to set the MODBUS™ ADDRESS.

3.9.4 MODBUS SUB ADDRESS (V3.11 AND UP)

Purpose: The MODBUS™ SUB ADDRESS, along with the MODBUS™ ADDRESS, defines the communications address to be used by the controller when using either MODBUS™ protocol to communicate with a MODBUS™ compatible device. When in the Point A configuration menu, this sets the Point A MODBUS™ SUB ADDRESS; when in the Point B configuration menu, this sets the Point B MODBUS™ SUB ADDRESS. Either may be set independently of the other.

Range: 0 to 31

Procedure: Set the communications sub address as desired. Together with the MODBUS™ ADDRESS, this combination must be unique to the entire communications network to avoid messaging conflicts. Either MODBUS™ protocol must be selected in order to set the MODBUS™ SUB ADDRESS.



Note: Since a 920 HTC does not use all 65,535 data addresses available for each MODBUS™ ADDRESS, this data address range is subdivided to allow up to 32 HTCs to share the same MODBUS™ ADDRESS. This increases the number of HTCs allowed on a single MODBUS™ port from 247 to 7,904 (=247 x 32). This requires that any HTC sharing the same MODBUS™ ADDRESS as another HTC must have its own unique MODBUS™ SUB ADDRESS.

3.9.5 BAUD RATE

Purpose: Defines the data rate at which communications occur.

Setting: AUTO or 9600 or 4800 or 2400 or 1200 or 600 or 300

Procedure: Select the data rate to be compatible with other devices that will be connected to the controller for communications purposes.



Note: Not all communications interfaces support the various data rates, so the data rate should be set to AUTO. The controller will automatically select a BAUD RATE that is compatible with the communications interface installed. If BAUD RATE = AUTO and a MODEM communication interface is used, a data rate of 300 is selected. Otherwise, if BAUD RATE = AUTO and a non-MODEM communications interface is used, a data rate of 9600 is used.

3.9.6 PARITY (MODBUS™) (V3.11 AND UP)

Purpose: Defines the type of parity bit used with MODBUS™ communications.

Setting: NONE or ODD or EVEN

Procedure: Select the desired type of parity. Note that PARITY can only be selected when using either MODBUS™ protocol.

3.9.7 HARDWARE

Purpose: Identifies the type of communications interface installed in the 920 control module. The controller automatically determines and displays which communications interface type is available.

Values: NONE, MODEM or RS-232 or RS-485

3.9.8 DRIVER

Purpose: Defines the way the controller's program communicates with the communications interface.

Setting: AUTO or RS-232 or RS-485 or MODEM

Procedure: Select AUTO to enable the controller to choose the setting that matches the communications interface installed.

3.9.9 PROFILE

Purpose: Defines the way the controller's program supports communications handshaking and communication interface signals.

Setting: AUTO or
FLOW CONTROL RS-232 or
STANDARD RS-232 or
3-WIRE RS-232 or
RS-485 or
EXTERNAL MODEM or
1200 BAUD MODEM or
300 BAUD MODEM

Procedure: Select the PROFILE to be compatible with other devices connected to the controller for communications purposes. The setting should be AUTO. The controller will automatically select a profile based on the type of communications interface installed in the 920 control module.



Notes:

- AUTO: Selects a communications profile based on the data rate and the type of communications interface installed in the control module.
- FLOW CONTROL RS-232: Continuously asserts RTS (Request To Send), CTS (Clear To Send) is required to enable any data transmitted, uses DCD (Data Carrier Detect) to qualify receive data.

- STANDARD RS-232: Continuously asserts RTS, CTS is required to initiate a transmit sequence, but is ignored once transmitting has begun, uses DCD to qualify receive data. This is the profile used when PROFILE = AUTO and an RS-232 communication interface is used with 920 V3.00.
- 3-WIRE RS-232: Continuously asserts RTS, CTS and DCD are ignored. This is the profile used when PROFILE = AUTO and an RS-232 communication interface is used with 920 V3.11+.
- RS-485: Uses RTS and the Tx Delay timer, CTS and DCD are ignored. This is the profile used when PROFILE = AUTO and an RS-485 communication interface is used.
- EXTERNAL MODEM: Uses RTS and the Tx Delay timer, ignores CTS, uses DCD to qualify each receive data character and to sense an idle channel condition.
- 1200 BAUD MODEM: Uses RTS with a fixed 10 msec Tx Delay time, ignores CTS, uses DCD to qualify each receive data character. This is the profile used when PROFILE = AUTO, BAUD RATE = 1200 and a MODEM communication interface is used.
- 300 BAUD MODEM: Uses RTS with a fixed 30 msec Tx Delay time, ignores CTS, uses DCD to qualify each receive data character. This is the profile used when PROFILE = AUTO, BAUD RATE = 1200 and a MODEM communication interface is used.

3.9.10 TX DELAY

Purpose: Allows a programmable delay between the receipt of a communications message and the controller's reply. In some applications, it may be necessary to delay the controller's response to an inquiry for a short period of time to allow external devices to start up, stabilize, and/or synchronize.

Range: 0.00 to 2.50 seconds

Procedure: Set the amount of delay between the receipt of a message and the controller's response as required.



Note: This selectable TX DELAY is only used if the PROFILE is set to either RS-485 or AUTO and an RS-485 interface is installed.

3.10 Operator Console Functions

The following features are part of the controller's programming, but are only used in conjunction with the optional 920 Operator Console. For a detailed description of each of the console features and operating instructions, refer to the separate document *DigiTrace 920 Series HTC Operator Console—Installation and Operating Instructions* (Tyco Thermal Controls reference H56903) for the particular version of controller firmware that you are using.

3.10.1 PASSCODE

Purpose: The four-digit PASSCODE feature prevents unauthorized users from modifying the controller's configuration parameters via a 920 Operator Console.

Range: 0000 to 9999

Procedure: Enter the desired PASSCODE (in the "Common Setup" sub-menu) using the optional 920 Operator Console keypad. A PASSCODE of 0000 disables the lockout feature and allows all configuration parameters to be modified using the 920 Operator Console without requiring a PASSCODE. Setting the PASSCODE to any other value will require the database to be unlocked, by entering the correct PASSCODE, prior to modifying any of the controller's configuration parameters using the optional 920 Operator Console.



Note: The PASSCODE can only be edited if it is set to 0 or the database has been unlocked by entering the proper PASSCODE.

3.10.2 LOCK DATABASE

Purpose: If the PASSCODE has been enabled (PASSCODE is not set to 0) and the user has unlocked console modification access to the controller's configuration parameters, the LOCK DATABASE feature allows the user to re-lock this modification access once programming has been completed.

Procedure: Select the LOCK DATABASE function (at the end of the “Configuration Mode Main Menu”) to lock out 920 Operator Console configuration modification access. The display will confirm the operation by displaying a “DATABASE LOCKED” message.



Note: 920 Operator Console configuration modification access will automatically re-lock after approximately 5 minutes of keypad inactivity.

3.10.3 UNLOCK DATABASE

Purpose: If a PASSCODE has been enabled (PASSCODE is not set to 0) and the user wants to modify any of the controller’s configuration parameters using a 920 Operator Console, the database must first be unlocked.

Procedure: Try modifying any configuration parameter, or select the UNLOCK DATABASE function (at the end of the “Configuration Mode Main Menu” for V3.11 and up), and a prompt for the PASSCODE will appear. If the correct PASSCODE is entered, the display will confirm the operation by displaying a DATABASE UNLOCKED message.

3.10.4 TEST TRACING

Purpose: The TEST TRACING feature provides an easy method of temporarily overriding the temperature control, without having to modify the CONTROL SETPOINT temperature or any other configuration parameter.

Procedure: Select the TEST TRACING function to force the output switch on for approximately 30 seconds. After the test time has expired, the unit will automatically revert to normal operation.



Notes:

- This feature only overrides temperature control; it does not override other control parameters such as power limiting.
- This feature is inhibited if the point is in load-shedding mode.

3.10.5 DISPLAY TEST (V3.11 AND UP)

Purpose: The DISPLAY TEST feature provides an easy method of illuminating each display segment and all the LEDs of the 920 Operator Console to ensure that they are functioning properly.

Procedure: Select the DISPLAY TEST and watch the 920 console to verify that each display segment and each LED is illuminated during the test sequence.



Note: Pressing any key on the 920 Operator Console keypad during the DISPLAY TEST causes the DISPLAY TEST to abort.

3.11 Copy Configuration Functions (V3.11 and up)

The following functions provide a quick method of setting all of the controller’s configuration parameters to a predefined state.

3.11.1 COPY DEFAULTS TO COMMON (V3.11 AND UP)

Purpose: Loads Tyco Thermal Controls’ default configuration parameters that are common to both Point A and Point B as defined in Appendix F.

Procedure: Enter the “Copy Configuration Sub-Menu” and select DEFAULTS TO COMMON.



Notes:

- This function overwrites the communication configuration parameters, which could affect existing communications to the controller.
- This function causes the OVERRIDE SOURCE for each point to be set to REMOTE. This is because the EXTERNAL INPUT setting is set to NOT USED.

3.11.2 COPY DEFAULTS TO POINT A (V3.11 AND UP)

Purpose: Loads the point-specific Tyco Thermal Controls default configuration parameters, as defined in Appendix F, for Point A. As well, all of Point A’s maintenance data are reset. All load-

shedding parameters (including fail-safe) are configured with default values. The CONSOLE SET-POINT MAXIMUM and MINIMUM are also configured with default values.

Procedure: Enter the “Copy Configuration Sub-Menu” and select DEFAULTS TO A.

3.11.3 COPY DEFAULTS TO POINT B (V3.11 AND UP)

Purpose: Loads the point-specific Tyco Thermal Controls default configuration parameters, as defined in Appendix F, for Point B. As well, all of Point B's maintenance data are reset. All load-shedding parameters (including fail safe) are configured with default values. The CONSOLE SET-POINT MAXIMUM and MINIMUM are also configured with default values.

Procedure: Enter the “Copy Configuration Sub-Menu” and select DEFAULTS TO B.

3.11.4 COPY POINT A TO POINT B (V3.11 AND UP)

Purpose: Copies the point-specific configuration parameters of Point A to Point B. Point A's configuration parameters are not changed.

Procedure: Enter the “Copy Configuration Sub-Menu” and select A TO B.



Notes:

- To ensure that the TAGs for both points are not the same, Point A's TAG is copied, the last character incremented by one, and then written to Point B's TAG.
- None of the communications addresses or the maintenance data values are copied.

3.11.5 COPY POINT B TO POINT A (V3.11 AND UP)

Purpose: Copies the point-specific configuration parameters of Point B to Point A. Point B's configuration parameters are not changed.

Procedure: Enter the “Copy Configuration Sub-Menu” and select B TO A.



Notes:

- To ensure that the TAGs for both points are not the same, Point B's TAG is copied, the last character incremented by one, and then written to Point A's TAG.
- None of the communications addresses or the maintenance data values are copied.

Section 4 Monitored Parameters

4.1 Introduction

The following is a brief summary of each of the measured and calculated parameters the 920 series control module provides to the user. Detailed information regarding settings, alarms limits, etc. may be found in Section 3 on page 18. For detailed information regarding the display of these variables using the 920 operator console or the Model 780/GCC-9000, refer to the appropriate user manuals.

4.2 Analog Readings

4.2.1 CONTROL TEMPERATURE

Purpose: This is the temperature the controller uses to determine whether its output switch should be on or off. Depending on the TS CONTROL MODE setting, whether one or two RTDs are installed, and TEMPBUS™ is being used, the CONTROL TEMPERATURE may be derived from TS 1, TS 2, TEMPBUS™ or a combination of the three temperatures. See section 3.5.12 on page 24 of this manual for further details regarding the TS CONTROL MODE settings.

4.2.2 TS 1 TEMPERATURE

Purpose: This temperature is the value the controller reads from the RTD connected to its TS 1 input. Depending on the TS CONTROL MODE, it may be used to determine the CONTROL TEMPERATURE (see section 4.2.1 on page 47).



Note (V3.11 and up): If the TS 1 input is not being used by the controller, the TS 1 TEMPERATURE is not displayed.

Note: Changing the TS Type will affect the temperature reading.

4.2.3 TS 2 TEMPERATURE

Purpose: This temperature is the value that the controller is reading from the RTD connected to its TS 2 input. Depending on the TS CONTROL MODE, it may be used to determine the CONTROL TEMPERATURE (see section 4.2.1 on page 47).



Note (V3.11 and up): If the TS 2 input is not being used by the controller, the TS 2 TEMPERATURE is not displayed.

Note: Changing the TS Type will affect the temperature reading.

4.2.4 LOAD CURRENT

Purpose: The LOAD CURRENT reading indicates the average current being drawn by the heating cable.



Note: The controller calculates the LOAD CURRENT using the current sensed by the switch interface module multiplied by the CURRENT TURNS RATIO to yield an adjusted current value.

4.2.5 RESISTANCE

Purpose: Resistance is calculated using the average adjusted voltage reading divided by the average adjusted current reading to yield a load resistance in ohms. If the controller's output switch is on but no current is present, the RESISTANCE will read "open circuit."



Note: If the controller's output switch is off, the RESISTANCE will display the last resistance which was calculated while the output switch was on.

4.2.6 GROUND FAULT CURRENT

Purpose: If the controller detects any leakage current in the output circuit, it will indicate the level in milliamperes.



Note: To minimize nuisance alarms, the controller will not report a leakage current of less than 20 mAmps.

4.2.7 VOLTAGE

Purpose: The voltage reading indicates the average circuit voltage being measured by the switch interface.



Note: The controller calculates this parameter using the voltage sensed by the switch interface module and multiplying it by the VOLTAGE TURNS RATIO to yield an adjusted voltage value.

4.2.8 POWER

Purpose: Load power provides an indication of the average power being consumed by the heat trace cable or the total 3-phase power being consumed by a balanced 3-phase star ("Y") connected load.



Notes:

- The controller calculates load power by multiplying the average adjusted voltage reading by the average adjusted current reading.
- The controller may be set up to calculate total 3-phase power for a balanced star ("Y") connected load if the 3-PHASE POWER CALCULATION parameter is enabled. In this case, total 3-phase power is calculated using the following equation:

$$P_{\text{total}} = \sqrt{3} \times I_{\text{phase}} \times V_{\text{line-line}}$$

Where I_{phase} = the adjusted phase current being measured, and $V_{\text{line-line}}$ = the adjusted voltage reading being measured. The VOLTAGE and CURRENT TURNS RATIOS affect both calculations.

4.3 Maintenance Data

4.3.1 MAX / MIN TEMPERATURE VALUES

MAX CONTROL TEMP

MIN CONTROL TEMP

TS 1 MAX TEMP

TS 1 MIN TEMP

TS 2 MAX TEMP

TS 2 MIN TEMP

Purpose: This feature indicates the maximum and minimum temperatures ever recorded by the HTC since the last time the values were reset. It may be useful to log the maximum/minimum temperatures ever experienced on a particular trace circuit for the purposes of troubleshooting or gathering data for future design criteria. The temperature values are written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user. maximum/minimum temperatures are recorded for TS 1, TS 2 and the CONTROL TS.

Range: Can only be reset (cleared) by the operator.

Procedure: The maximum/minimum temperatures can be reset using the optional 920 Operator Console (V3.11+) or a communicating device. Resetting any one of the temperatures will reset all of them.

4.3.2 POWER ACCUMULATOR

Purpose: This feature indicates the total power consumption of the trace circuit since the last time the POWER ACCUMULATOR was reset. It may be useful to log the amount of power consumed on a particular trace circuit for the purposes of energy management or gathering data for future design criteria. The value of this accumulator is written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user.

Procedure: The POWER ACCUMULATOR may be reset to zero using the optional 920 Operator Console (V3.11+) or a communicating device.



Note: The POWER ACCUMULATOR value will roll over to zero when the upper limit of the POWER ACCUMULATOR has been exceeded. This upper limit is 429,496,729.5 kW-hours for V3.00, and 214,748,364.7 kW-hours for V3.11 and up.

4.3.3 CONTACTOR CYCLE COUNTER (V3.11 AND UP)

Purpose: This feature indicates the total number of off-to-on transitions a contactor has completed since the last time the CONTACTOR CYCLE COUNTER was reset. This serves as a method to do preventative maintenance on the contactor according to the manufacturer's specifications. The count value is written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user.

Procedure: The CONTACTOR CYCLE COUNTER may be reset to zero using the optional 920 Operator Console or a communicating device.



Notes:

- Once the CONTACTOR CYCLE COUNTER reaches 999,999,999 it stops counting.
- The CONTACTOR CYCLE COUNTER is only indicated if the SWITCH CONTROL MODE is set to either DEADBAND or PROPORTIONAL AMBIENT CONTACTOR.

4.3.4 TIME IN USE

Purpose: The purpose of this feature is to indicate the total hours of controller use since its initial operation. It may be useful to log the amount of time a controller has been in service for the purposes of maintenance planning or reliability testing. The value of this accumulator is written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user.

Procedure: The IN USE hours accumulator can be reset to zero using the optional 920 Operator Console (V3.11+) or a communicating device.



Note: The IN USE hours accumulator value will roll over to zero when the upper limit of the accumulator has been exceeded. This limit is 4,294,967,295 hours for V3.00, and 999,999,999 hours for V3.11 and up.

4.3.5 TIME SINCE LAST RESET

Purpose: This feature indicates the total hours of controller use since the last reset. It may be useful to log the amount of time a particular controller has been in service since the last time the controller's power was cycled for troubleshooting purposes.

Procedure: The TIME SINCE LAST RESET hours accumulator can only be reset by cycling the controller's power.



Note: The TIME SINCE LAST RESET will roll over to zero when the upper limit of 65,535 hours has been exceeded.

4.3.6 PEAK LOAD CURRENT (V3.11 AND UP)



Note: The PEAK LOAD CURRENT is not displayed on the optional 920 Operator Console.

Purpose: This feature indicates the highest instantaneous load current measured since the last time the PEAK LOAD CURRENT was reset. This value is written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user.

Procedure: The PEAK LOAD CURRENT may only be reset to zero using a communicating device.

4.3.7 PEAK GROUND-FAULT CURRENT (V3.11 AND UP)



Note: The PEAK GROUND-FAULT CURRENT is not displayed on the optional 920 Operator Console.

Purpose: This feature indicates the highest instantaneous ground-fault current measured since the last time the PEAK GROUND-FAULT CURRENT was reset. This current value is written to the controller's nonvolatile memory once every 24 hours or whenever any maintenance data is reset by the user.

Procedure: The PEAK LOAD CURRENT may only be reset to zero using a communicating device.

4.3.8 EXTERNAL INPUT STATUS (V3.11 AND UP)



Note: The EXTERNAL INPUT STATUS is not displayed on the optional 920 Operator Console.

Purpose: This feature indicates the actual status of the external input regardless of the controller's configuration. This can assist the operator who wishes to use the controller's external input to monitor the status of an external dry contact and pass this on to another device.

Procedure: The EXTERNAL INPUT STATUS may only be viewed using a MODBUS™-capable software package.

Section 5 Control Modes

5.1 Introduction

There are several types of control modes in the controller. Some of these modes require further explanation in order to fully understand and implement their operation.

This section describes the control modes available in the HTC and how to set their associated parameters.

5.2 Switch Control Modes

There are four SWITCH CONTROL modes associated with the HTC. The following is an explanation of their implementation in the controller and the differences between them.

5.2.1 PROPORTIONAL CONTROL (FOR USE WITH SSRS ONLY)

Proportional control on the HTC is implemented as follows:

When using SSRs to directly control the power applied to a trace circuit, the output may be switched on/off very rapidly. The controller implements proportional temperature control on a cycle-by-cycle basis (50 or 60 Hz power line cycle). This algorithm monitors the temperature of the heating circuit and compares it to the CONTROL SETPOINT temperature. If the temperature of the control sensor is at or below the CONTROL SETPOINT temperature, power is applied to the trace with a duty cycle of 100%—the controller output is full on. If the temperature sensed by the control sensor is equal to or greater than the CONTROL SETPOINT temperature + the PROPOR-TIONAL BAND setting, the controller output will have a duty cycle of 0%—the output will be off. The temperature of the control sensor is constantly monitored and the output duty cycle is adjusted proportionally according to where the temperature falls within the 0%–100% band.

Proportional Control Temperature Band	
Control Sensor Temperature	Duty Cycle
Setpoint + proportional band	0%
Setpoint + proportional band/2	50%
Setpoint	100%

5.2.2 DEADBAND CONTROL (FOR USE WITH EXTERNAL CONTACTORS)

Deadband control on the HTC is implemented as follows:

When using the HTC in an application where the controller is used to open and close a contactor, proportional control cannot be used. In these cases a deadband control algorithm is used. The output duty cycle is not controlled; instead, the output is either fully on or completely off. The user can set the DEADBAND value. The controller monitors the temperature of the trace circuit and compares it to the CONTROL SETPOINT temperature as in the proportional control. If the control sensor temperature is above the CONTROL SETPOINT temperature by more than the DEAD-BAND value, the output is turned off. If the control sensor temperature falls below the CONTROL SETPOINT temperature the output is turned on. This is a simple control algorithm but it works very effectively in heat trace applications where the temperature of a traced system changes relatively slowly.

Deadband Control Temperature Band	
Control Sensor Temperature	Output State
Setpoint + deadband	Off
Setpoint	On

When the control sensor temperature is within the deadband, the output does not change its state. Also, when using deadband control a contactor is not allowed to toggle faster than every two seconds. If an AC alarm with an alarm filter time greater than 0 is detected, the contactor will not toggle until the alarm filter time has expired.

5.2.3 PROPORTIONAL AMBIENT SSR CONTROL (FOR USE WITH SSRS ONLY)

When an HTC using an SSR is used to control the output using the ambient temperature, this control mode should be used.

Proportional ambient SSR control on the HTC is implemented as follows:

- When using SSRs to directly control the power applied to a heating circuit, the output may be switched on/off very rapidly. The controller implements proportional temperature control on a cycle-by-cycle basis (50 or 60 Hz power line cycle).
- This algorithm monitors ambient temperature and compares it to the CONTROL SETPOINT temperature. If the temperature of the control sensor is at or below the CONTROL SETPOINT temperature minus the PROPORTIONAL BAND setting, power is applied to the trace with a duty cycle of 100%—the controller output is fully on.

- If the temperature sensed by the control sensor is equal to or greater than the CONTROL SETPOINT temperature, the output will have a duty cycle of 0%—the controller output will be off.
- The temperature of the control sensor is constantly monitored and the output duty cycle is adjusted proportionally according to where the temperature falls within the 0%–100% band.

Proportional Ambient SSR Control Temperature Band

Control Sensor Temperature	Duty Cycle
Setpoint	0%
Setpoint - proportional band/2	50%
Setpoint - proportional band	100%

Note: The load shedding fail-safe mode is not supported when using proportional ambient SSR control, since ambient temperature is being monitored rather than pipe temperature.

5.2.4 PROPORTIONAL AMBIENT CONTACTOR CONTROL (FOR USE WITH EXTERNAL CONTACTORS)

When an HTC using a contactor is used to control the output based on the ambient temperature this control mode should be used.

Proportional ambient contactor control on the HTC is implemented as follows:

- The output may not be switched on/off rapidly when using a contactor, so proportional temperature control is implemented by applying the required duty cycle over the selected CYCLE TIME.
- The output is fully on for a portion of the CYCLE TIME as determined by the calculated duty cycle, and it will be completely off for the remainder of the CYCLE TIME.
- The duty cycle is calculated each time the output toggles, based on the ambient temperature, PROPORTIONAL BAND setting, and the CONTROL SETPOINT temperature setting.
- The controller monitors the ambient temperature and compares it to the CONTROL SETPOINT temperature as in proportional ambient SSR control. If the temperature of the control sensor is at or below the CONTROL SETPOINT temperature minus the PROPORTIONAL BAND setting, power is applied to the trace with a duty cycle of 100%. The controller output will be fully on for 1/30th of the CYCLE TIME setting before the duty cycle is calculated again.
- If the temperature sensed by the control sensor is equal to or greater than the CONTROL SETPOINT temperature, the output will have a duty cycle of 0%. The controller output will be off for 1/30th of the CYCLE TIME setting before the duty cycle is calculated again.

Proportional Ambient Contactor Control Temperature Band

Control Sensor Temperature	Duty Cycle
Setpoint	0%
Setpoint - proportional band/2	50%
Setpoint - proportional band	100%



Note: The load shedding fail-safe mode is not supported when using proportional ambient contactor control, since ambient temperature is being monitored rather than pipe temperature.

If an AC alarm with an alarm filter time greater than 0 is detected, the contactor will not toggle until the alarm filter time has expired.

5.3 Load Shedding Control Mode

Load shedding is a control mode that can be programmed and initiated only by an external communicating device, or by the Model 780/GCC-9000 Group Communications Controller, which overrides temperature control and forces the output of the controller OFF until reset by the 780/GCC. When using a GCC, load shedding is initiated by a contact closure (or opening) on one of the four contact inputs. Each contact input initiates a load shedding command for the group of

controllers associated with that contact input. Each controller may be associated with one or more groups. Refer to the Load Shedding Section in the GCC manual for details on setting up the load shedding features of the HTC when using a GCC.

When power is applied to the controller, it determines if load shedding mode has been enabled. If enabled, the controller immediately enters load shedding operation (holding its output off) and waits to see if the GCC or an external communicating device has initiated a load shedding command. If no command is present the controller resumes normal operation. If a load shedding command is present, the controller will continue to hold the output OFF, until one of three conditions occurs:

1. The GCC contact input or zone definition bits of an external communicating device which initiated load shedding clears and the command to terminate load shedding mode is issued.
2. Communications are interrupted between the controller and its communicating device, as in the case of a damaged communications wire. Approximately 30 seconds after communications ceases the controller will return to normal operation.
3. Communications between the controllers and the external communicating device goes off-line for approximately two minutes, as occurs when the 760 Hand Held Programmer is used to communicate with the controller.



Note: The controller will return to normal operation if communications between the 780 or external communicating device and the controller are disrupted in any way. This will return temperature control to the HTC. Also, the HTC does not perform a periodic autocycle test while operating in load shed mode. When using a GCC, it must be configured for load shedding operation before the controller can be set up for load shedding control.

Three parameters must be set in the controller to configure it for load shedding operation:

1. The load shedding feature must be enabled.
2. The FAIL SAFE MODE parameter must be enabled or disabled depending on the application requirements. If FAIL SAFE MODE is enabled, then at least one LOW TS ALARM (of a TS used in the TS CONTROL MODE) must be enabled. If the alarm temperature exceeds the CONTROL SET-POINT temperature, fail-safe mode will be disabled.
3. The GCC contact input(s) or zone definition bits of an external communicating device that are to be associated with the load shedding action for the controller must be defined.

These parameters can only be configured using an external communicating device or the Model 780/GCC-9000 Group Communications Controller. Refer to the Model 780/GCC-9000 user manual for details on how to set up these options. The optional 920 Operator Console can be used to enable or disable the load shedding feature, but not to set any other load-shedding parameters.



Notes:

- Fail-safe mode is always disabled if the SWITCH CONTROL MODE is set to either of the two proportional ambient control modes, or the TS CONTROL MODE = EXT INPUT, FAIL OFF/ON
- Fail-safe mode is disabled if the TS CONTROL MODE is set to either EXT INPUT, FAIL TS 1 or EXT INPUT, FAIL TS 2 and a control temperature failure occurs.
- The HTC will turn on its output switch when the control temperature becomes less than the highest LOW TS ALARM temperature if the following conditions are met:
 - Fail-safe mode is enabled
 - Load shedding is active
 - The TS CONTROL MODE uses both TS 1 and TS 2
 - Both TS 1 and TS 2 have their LOW TS ALARMS enabled
- A FORCE ON override signal has higher priority than a load shedding signal. An INHIBIT signal has higher priority than fail safe mode.

5.4 TEMPBUS™ Control Mode

TEMPBUS™ is short for Temperature Bus. This refers to a connection that allows one “master” HTC to share its control temperature with a number of “slave” HTCs. Up to 25 “slave” HTCs can be connected to this bus. Refer to the wiring diagrams in Appendix C for example connection details.

5.4.1 TEMPBUS™ MASTER

Only Point A of a 920 HTC can be configured as a TEMPBUS™ “master.” A TS CONTROL MODE using either TS 1 and/or TS 2 should be selected and the EXTERNAL OUTPUT should be set to TEMPBUS™. This will cause the measured control temperature of Point A to be sent out the EXTERNAL OUTPUT port.



Notes:

- If a TEMPBUS™ “master” has its temperature control overridden by an INHIBIT override or a FORCE ON override signal, it will pass this override signal over the TEMPBUS™ to its “slaves.”
- Load shedding, fail-safe, or auto-cycling conditions are not passed over the TEMPBUS™ from a “master” to its “slaves.”

5.4.2 TEMPBUS™ SLAVE

Both Point A and/or Point B of a 920 HTC can be configured as a TEMPBUS™ “slave.” The EXTERNAL INPUT should be set to TEMPBUS™, then the point’s TS CONTROL MODE must be set to a mode using the EXTERNAL INPUT. The “slave” controller will perform its own temperature control using the control temperature of the “master.”

If a TEMPBUS™ “slave” does not receive a control temperature from a TEMPBUS™ “master” at least once every 15 seconds, then a CONTROL TS FAILURE ALARM will occur. This alarm is non-latching for TEMPBUS™ “slaves” and will be cleared automatically once a control temperature is received again. Point B can be a “slave” to Point A of the same controller.



Note: Other features that require the use of the EXTERNAL INPUT (INHIBIT or OVERRIDE) may not be used at the same time as the TEMPBUS “slave” feature.

Section 6 Troubleshooting

6.1 Operator Checks

Upon receipt of the controller, or to check the controller for an indication of normal operation, follow the operational procedures shown below. These procedures are designed to familiarize the operator with the controller and to provide an understanding of its operation.

To determine if a fault is associated with the heat tracing, wiring or the controller, it is necessary to troubleshoot the wiring and tracer circuit. If the fault remains, remove power from the controller and exchange it with another controller. This may require some reprogramming of the new HTC.

If the fault clears, exchange the controller on another circuit to determine if the fault moves with the controller. If the fault moves with the controller, verify that the HTC has been configured correctly for the application. If the configuration is correct, return the controller to Tyco Thermal Controls for evaluation.



Note: If the controller does not operate properly and is being returned to Tyco Thermal Controls for service, information must be provided as to why the unit was removed from service. Contact the Tyco Thermal Controls customer service department for an authorization form and number prior to returning any units for repair.

6.1.1 GETTING STARTED

To access the functions of the 920 Series HTC, use the optional 920 Operator Console. If the modem communications option is installed in the 920 control module, the Model 780/GCC-9000 Group Communications Controller may also be used to access controller parameters. Refer to the operating manual for the particular device that you are using for operational details.

6.2 Common Problem Areas

The HTC can be used as an effective troubleshooting tool to pinpoint problem areas of heat trace circuits. Described below are a few of the more common problem areas, their symptoms, and parameters to check to determine the actual faulty portion of the heat trace circuit.

6.2.1 CONTROL POINT A VERSUS CONTROL POINT B

Remember that the 920 series controller is a two-point device!

One of the most common errors is to confuse settings, displays, or alarms for one control point with the second control point. When programming or troubleshooting, *always confirm that you are referencing the control point of interest*—either Point A or Point B.

6.2.2 RTDS

RTD failures after installation can generally be attributed to incorrect wiring or improper installation of the sensor. Some specific RTD problems and troubleshooting methods follow.

1. TS Failure Alarm(s)

If the HTC controller indicates a failure of an RTD:

- Ensure that the RTD is a 3-wire 100 Ω Platinum Type (for V3.00). For V3.11 and up ensure that the TS TYPE setting matches the RTD being used.
- *Turn off the power to the controller before proceeding!*
- Disconnect the RTD wiring from the input terminals.
- Measure the RTD's resistance between the source (WHT) and sense (WHT) leads at the controller. It should not exceed 40 Ω . Excessive lead resistance will cause a TS FAILURE ALARM and must be corrected. Look for loose terminals, excessive lead length, or insufficient wire gauge and correct as necessary.
- Measure the RTD's resistance between the source (WHT) or sense (WHT) lead and the common (RED) lead of the RTD at the controller. This should be between 60 Ω and 330 Ω depend-

ing on the temperature and the lead resistance. See Appendix D on page 74 or Appendix E on page 75.

- Verify that the RTD is wired correctly. The heat-tracing controllers will always be terminated in the order: source (WHT), sense (WHT), common (RED). When using the terminal board, these terminals are marked as follows:

Terminal No.	Description
25	Point A, Shield
26	Point A, TS 1 Source (WHT)
27	Point A, TS 1 Sense (WHT)
28	Point A, TS 1 Common (RED)
9	Point A, Shield
10	Point A, TS 2 Source (WHT)
11	Point A, TS 2 Sense (WHT)
12	Point A, TS 2 Common (RED)
29	Point B, Shield
30	Point B, TS 1 Source (WHT)
31	Point B, TS 1 Sense (WHT)
32	Point B, TS 1 Common (RED)
13	Point B, Shield
14	Point B, TS 2 Source (WHT)
15	Point B, TS 2 Sense (WHT)
16	Point B, TS 2 Common (RED)

The RTD manufacturer will typically color code the leads with the source and sense being the same color, and the common a different color. Ensure that the RTD extension wire shield is terminated at one end only, normally using the terminal block provided at the terminal board.



Note: Some RTDs may have the Sense wire color coded as Black.

2. Questionable Temperature

If you feel that the indicated or displayed temperature is not correct, the controller and the RTD can be quickly checked for correct operation.

To verify the RTD:

Turn off the power to the controller before proceeding!

- Disconnect the RTD wiring from the input terminals.
- To calculate the temperature indicated by the RTD, measure the resistance from source (white wire) or sense (white wire) to common (red wire) and subtract the resistance measured between source and sense. This will give a compensated resistance value that can be cross-referenced to the RTD table, DIN Standard 43760 found in Appendix D on page 74 or Appendix E on page 75. Compare the measured resistance and cross-referenced temperature value obtained from the RTD table to the indicated or displayed value. These should agree to within the accuracy standards of the HTC and the RTD.

To verify the Controller:

Turn off the power to the controller before proceeding!

- Disconnect the RTD wiring from the input terminals.
- Connect a 100 Ω resistor across the source or sense terminal and common. Insert a jumper between the source and sense terminals.
- Apply power to the controller. The indicated or displayed temperature should be about 0°C (32°F) depending on the actual resistance of the test resistor if TS TYPE is set to 100 Ω Platinum.

3. Unstable or Bouncing Temperature

An erratic indication of temperature can be caused by several factors external to the controller; however, a bouncing temperature of a few degrees should not be confused with incorrect opera-

tion. The controller's accuracy and resolution will result in an indicated temperature change of a couple of degrees if the measured resistance temperature falls between two discrete values. This is sometimes referred to as quantization error.

If the bounce or instability is excessive, check:

- Wire used for extension of the RTD should be three-wire, twisted and shielded with the shield grounded at the controller only. Each of the three lead wires must be of the same gauge.
- The ideal installation has a separate conduit for the RTD leads (if they have been extended). It is not usually a problem to run low signal levels in the same conduit as the power leads even in high-power applications, as long as the RTD wire is a twisted, shielded type with an insulation rating equal to or greater than the highest voltage in the conduit. Follow the proper Electrical Code for your particular installation.
- Terminal connections that are not tight can add resistance to an RTD circuit. Check the tightness of all screw terminal connections at time of installation and during subsequent maintenance checks.
- Check the specifications for the particular cable being used to ensure that it does not have excessive capacitance when used in long lengths. This can cause a temperature offset between what the controller reads and what the RTD actually measures. This again is normally not a problem since the controller compensates for all but the worst cases of this.
- Lastly, it is possible for the RTD itself to fail on an intermittent basis but this failure mode should be considered unusual. This kind of failure is probably the most difficult to find but fortunately it is also the least likely as a failure mechanism.

6.2.3 GROUND FAULT

Ground-fault alarms can be due to incorrect installation as well as leakage resulting from wet system components or faulted cables.

The 920 series switch interface detects ground faults by summing the outgoing and return trace currents through an internal current transformer. Under normal operating conditions (no ground fault condition) this current will be zero. When there is a flow of current from one of the trace supply wires to ground, a ground-fault condition occurs.

If a ground-fault alarm is present on start-up of a new installation, it is likely due to a wiring error or damaged cable. To verify this condition:

- Check that the heating circuit neutrals return to the controller and are not connected directly to the distribution panel. This can be a common problem if the installation is a retrofit situation.
- On paralleled circuits, be certain that ALL neutrals return. The late addition of a circuit may not be obvious.

Use the monitoring feature available at the 920 Operator Console or the Model 780/GCC-9000 Group Communications Controller to view the measured ground-fault current at the heat-trace controller. If this value is at the maximum that the controller can measure, it is usually an indication that the wiring is incorrect. If the value is less than 250 mAmps, an actual ground-fault condition may exist in the cable.



Note: The controller monitors the integrity of the ground-fault (GF) detection transformer and associated wiring. If a fault is detected, the controller will report a GF value of 300 mAmps.

6.3 Common Alarms—What to look for

Alarm	Description	Cause of Alarm
High TS 1/TS 2 Temperature	Appears when the temperature exceeds the HIGH TS ALARM	<ul style="list-style-type: none"> • Alarm temperature setting too close to maintain temperature • Flow of hot product • Steaming out lines • Incorrect tracer wiring • Incorrect RTD TYPE selected
Low TS 1/TS 2 Temperature	Appears when the temperature decreases below the LOW TS ALARM temperature.	<ul style="list-style-type: none"> • Alarm temperature setting too close to maintain temperature • Flow of cold product • Empty pipe • Damaged, wet, or missing insulation • Heating cable not sized properly for the application • Heating cable damaged • Incorrect RTD TYPE selected
TS 1/TS 2 Failure	Indicates that a sensor is operating improperly.	<ul style="list-style-type: none"> • Incorrect or damaged field wiring—open leads or excess resistance, either intermittent or continuous, may be due to broken or damaged wires or loose terminals • Damaged or inoperative temperature sensors
Control TS Failure	Alarms a failure of the temperature-sensing element designated as the control element by the TS CONTROL MODE setting. Depending on the chosen TS FAIL MODE and TS CONTROL MODE, the output switch may be latched off or on until this failure is corrected.	<ul style="list-style-type: none"> • Incorrect or damaged field wiring—open leads or excess resistance, either intermittent or continuous, may be due to broken or damaged wires or loose terminals • Damaged or inoperative temperature sensors
High Current	Alarms current levels that are greater than the HIGH CURRENT ALARM setting for the application.	<ul style="list-style-type: none"> • Alarm setting too close to normal operating • High in-rush current from cold start of self-regulating cable • Damaged or partially shorted heating cable • “As built” cable length is greater than design value • Incorrect CURRENT TURNS RATIO setting
Low Current	Alarms current levels that are less than the LOW CURRENT ALARM setting	<ul style="list-style-type: none"> • Alarm setting too close to normal operating current • Low source voltage • Damaged or inoperative heating cable • Open connection—wiring problem, SSR or contactor failed open • Incorrect CURRENT TURNS RATIO setting
High GFI	Alarms ground-fault current levels that are greater than the HIGH GFI ALARM setting	<ul style="list-style-type: none"> • Alarm setting too close to normal leakage current • Damaged cable insulation and/or moisture present • Moisture in junction box • Poor splice or termination • Moisture provides conductive ground path that allows ground-fault current
GFI Trip	This value sets the upper limit of allowable ground-fault leakage. Exceeding this limit results in the output switch being latched off and the alarm activated to indicate a ground-fault condition.	<ul style="list-style-type: none"> • Trip setting too normal leakage current • Damaged cable insulation and/or moisture present • Moisture in junction box • Poor splice or termination • Moisture provides conductive ground path that allows ground-fault current
High Voltage	Alarms voltage levels that are greater than the HIGH VOLTAGE ALARM setting	<ul style="list-style-type: none"> • Alarm setting too close to normal operating voltage • Incorrect wiring • Incorrect VOLTAGE TURNS RATIO • Power surge
Low Voltage	This alarms voltage levels which are less than the LOW VOLTAGE ALARM setting.	<ul style="list-style-type: none"> • Alarm setting too close to normal operating voltage • Damaged power cable • Incorrect VOLTAGE TURNS RATIO • Brown-out conditions • Loss of power to the circuit

6.3 Common Alarms—What to look for (Continued)

Alarm	Description	Cause of Alarm
Overcurrent Trip	If the controller is unable to start the cable due to high current or after attempting to soft start it, the controller trips off its output switch.	<ul style="list-style-type: none"> • Excessive in-rush current • Incorrect wiring • Damaged cable • Switch rating set too low • Incorrect CURRENT TURNS RATIO setting
Switch Failure	This alarm will indicate that the controller senses current flow when the output switch should be off.	<ul style="list-style-type: none"> • Some other device has energized the heat trace cable • Output switch has failed
HTC Reset	This alarm is latched when power is restored after an interruption. Used to identify intermittent power losses.	<ul style="list-style-type: none"> • Circuit breaker tripped • Power line transient
Power Limiting	This alarm indicates that the solid-state relay is limiting the average amount of power that is applied to the trace circuit as defined by the MAXIMUM POWER setting.	<ul style="list-style-type: none"> • Power applied to trace circuit is being limited to the MAXIMUM POWER setting • Incorrect VOLTAGE and/or CURRENT TURNS RATIO setting
C B Limiting	This alarm indicates that the controller is limiting the average current to the CIRCUIT BREAKER CURRENT RATING setting.	<ul style="list-style-type: none"> • Excessive current caused by in-rush current • C.B. CURRENT RATING setting too low for normal heater current draw or not matched to actual circuit breaker size • Incorrect CURRENT TURNS RATIO setting
Switch Limiting	This alarm indicates that the controller is limiting the average current that is applied to the trace circuit based on the SWITCH RATING setting to protect the solid-state relay from excess current.	<ul style="list-style-type: none"> • Excessive current caused by in-rush current • Incorrect CURRENT TURNS RATIO setting
High Resistance	This alarm indicates that the heating cable resistance has deviated from the NOMINAL RESISTANCE setting by more than the HIGH RESISTANCE ALARM setting.	<ul style="list-style-type: none"> • Alarm setting too close to actual operating resistance • NOMINAL RESISTANCE not set properly • Open connection—wiring problem • Damaged cable • Incorrect VOLTAGE and/or CURRENT TURNS RATIO setting
Low Resistance	This alarm indicates that the heating cable resistance has deviated from the NOMINAL RESISTANCE setting by more than the LOW RESISTANCE ALARM setting.	<ul style="list-style-type: none"> • Alarm setting too close to actual operating resistance • NOMINAL RESISTANCE not set properly • Partial short—wiring problem • Damaged cable • Incorrect VOLTAGE and/or CURRENT TURNS RATIO setting
EEROM Data Failure	This alarm indicates that the controller has detected a failure in its nonvolatile memory (this is where all of the controller's configuration and calibration settings are stored). This indicates an internal problem and the HTC should be replaced and returned to Tyco Thermal Controls for repair.	<ul style="list-style-type: none"> • The HTC cannot bypass the failed area of its memory and has loaded factory defaults into this failed area.
Contactor Count (V3.11 and up)	This alarm indicates that the number of off-to-on transitions of a contactor has exceeded the CONTACTOR COUNT ALARM setting and needs to be replaced.	<ul style="list-style-type: none"> • Contactor may be worn. • Some configuration parameter (i.e. DEADBAND, AUTO CYCLE INTERVAL, load shedding etc.) is causing the contactor to toggle more than usual.

Section 7 Maintenance

7.1 Operator Maintenance

The 920 series controller is designed to be a maintenance-free product. Once installed properly, the only maintenance required is retightening of the terminal connections approximately one week after installation and inspection periodically thereafter. Also, alarm pilot lamps (if installed) and contactors may need periodic replacement.



Caution: Make sure that the power to the controller is OFF when replacing the pilot lamps! Also, be certain power to the controller is OFF before attempting to test or service the heat tracing. *Do not rely on the controller as a disconnect device!*

7.2 Replaceable Parts

There are no user-serviceable parts in the 920 series controller or accessories, except lamps in optional alarm pilot lights. The unit is designed to be modular and easily changed out in the field. Modules appearing inoperative should be returned to the nearest Tyco Thermal Controls Service Center for service.



Warning: Tampering with the 920 components without approval from Tyco Thermal Controls could result in the product's warranty being void.

Appendix A Specifications

Specifications are @ 25°C unless otherwise noted and are subject to change without notice.

System Ratings	
Storage ambient	–40°F to 185°F (–40°C to 85°C)
Approvals	CSA C/US, Factory Mutual
Classification	<ul style="list-style-type: none"> • CI I, Div 2, Grp A,B,C,D and Ex nA IIA, IIB, IIC (Zone 2) • SSR Version T-code: T4 (T3A with optional pilot light) • Ordinary locations (SSR and contactor versions)

920 Series Wiring Terminal Ratings	
Terminal board	28-12 AWG, strip length: 0.22"
Switch interface	28-14 AWG, strip length: 0.33"
Power terminals	30 A: 22-8 AWG, strip length: 0.47", torque: 16.0 lb-in 60 A: 14-6 AWG, strip length: 0.47", torque: 26.5 lb-in

920 Series Control Module (per control point)	
Operating temperature	–40°F to 140°F (–40°C to 60°C)
Power requirement	9 Vdc nominal, 600 ma maximum
Control modes	Proportional, deadband, proportional ambient (SSR), proportional ambient (contactor) modes, adjustable 2°F to 90°F (1°C to 50°C) above setpoint
Temperature inputs	(2) RTD inputs: 3-wire 100Ω Platinum (DIN 43760, $\alpha=0.00385\Omega/\Omega/^\circ\text{C}$) or 2/3-wire 100Ω Ni-Fe, open/shorted sensor detection/protection, lead resistance compensated 0 to 20Ω per lead.
Temperature measurement range	–76°F to 1058°F (–60°C to 570°C), accuracy: $\pm 0.5\%$ of span $\pm 1\text{LSD}$
Voltage measurement range	50 to 295 Vac (with voltage turns ratio @ 1:1), accuracy: $\pm 1\%$ of span $\pm 2\text{LSD}$, repeatability: $\pm 1.5\%$ of span
Current measurement range	0.3 to 100 A (with current turns ratio @ 1:1), resolution: 0.1 A (0.3 to 11 A range), 0.3 A (11 to 40 A range), 0.7 A (40 to 100 A range), accuracy: $\pm 2.5\%$ of reading \pm resolution, repeatability: $\pm 3\%$ of reading \pm resolution
GF current measurement range	20 to 250 ma, accuracy: $\pm 2.5\%$ of span $\pm 2\text{LSD}$ at nominal load, repeatability: $\pm 4\%$ of span
Alarm relay output	Dry contact, 48 Vac/dc, 500 ma, 10 VA switching maximum

920 Series SSR Switch Interface Module	
Operating temperature	–40°F to 140°F (–40°C to 60°C)
Power requirements	100 to 277 Vac nominal, 1 PH, 60 Hz $\pm 3\text{ Hz}$ or 50 Hz $\pm 2\text{ Hz}$, 100 ma. maximum
Output power	+9 Vdc nominal, 650 ma maximum
SSR drive	+9 Vdc nominal, 75 ma maximum
Current sense range	1000:1, 0.3 to 60 A, 50/60 Hz, 1 PH
GF current sense range	1000:1, 20 to 250 ma, 50/60 Hz, 1 or 3 PH
Wiring terminals	28-14 AWG, strip length: 0.33"

920 Series SSR Output Modules

Operating Temperature	–40°F to 104°F (–40°C to 40°C)
Switch Rating	<ul style="list-style-type: none">• 30 A resistive continuous @ 277Vac max. standard, 600 Vac max. optional, 1 PH, 50/60 Hz, 80 A 1 sec. in-rush, 625 A 1 cycle in-rush• 60 A resistive continuous @ 600 Vac max., 1 PH, 50/60 Hz, 120 A 1 sec. in-rush, 1000 A 1 cycle in-rush
Input Drive Requirement	4-32 Vdc, 1500 Ω nominal input resistance
Environment	Type 4X / IP66

920 Series Contactor Ratings

Operating Temperature	–40°F to 104°F (–40°C to 40°C)
Contact Rating	30 A resistive continuous @ 600 Vac max. standard, 60 A maximum opt., 50/60Hz, 3 pole
Coil Rating	120 or 208/240 or 277 Vac, 50/60 Hz, 109 VA in-rush, 10 VA sealed

920 Series Operator Console

Operating Temperature	–40°F to 104°F (–40°C to 60°C)
Power Requirement	+9 Vdc nominal, 500 ma maximum

Appendix B Typical Enclosure Dimensions

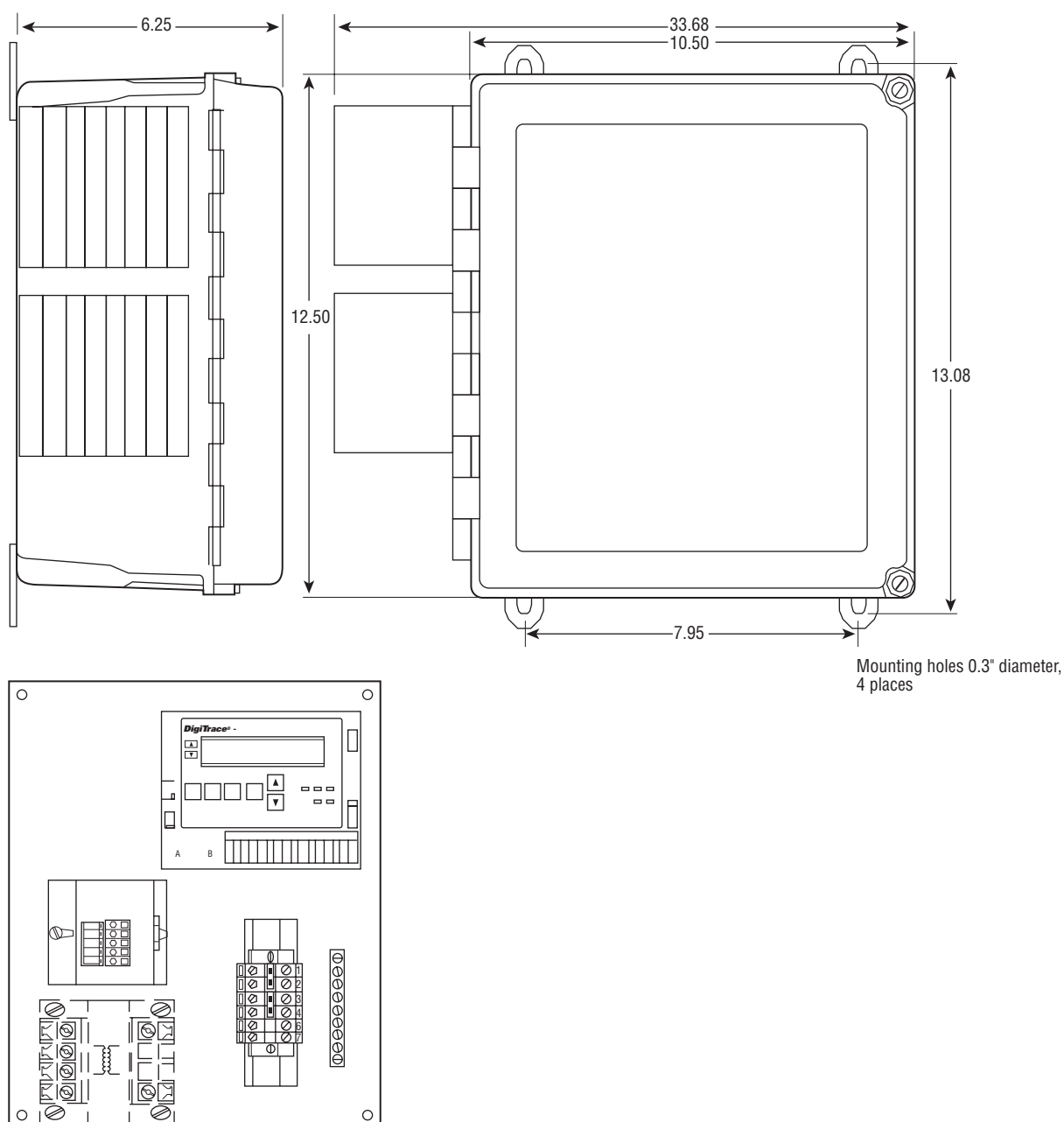
The following drawings provide the user with enclosure size and mounting dimensions for the stock enclosure assemblies. Please contact your local Tyco Thermal Controls representative for information regarding other available sizes and configurations.

B.1 Single-Point Assemblies #10160-003 and #10160-009

1 Point FRP 1- or 2-pole 30 A SSR assembly

1 Pole Model: 920*E2FWL*SIS301*SS3101

2 Pole Model: 920*E2FWL*SIS301*SS3201



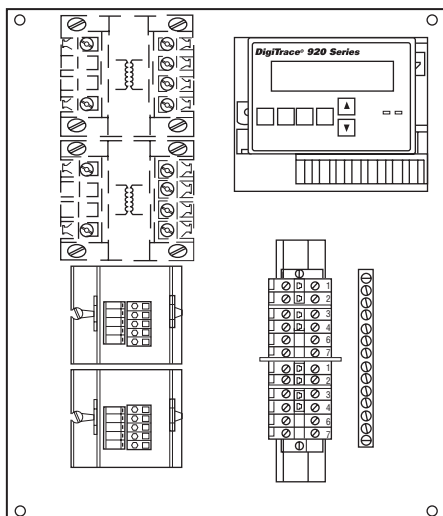
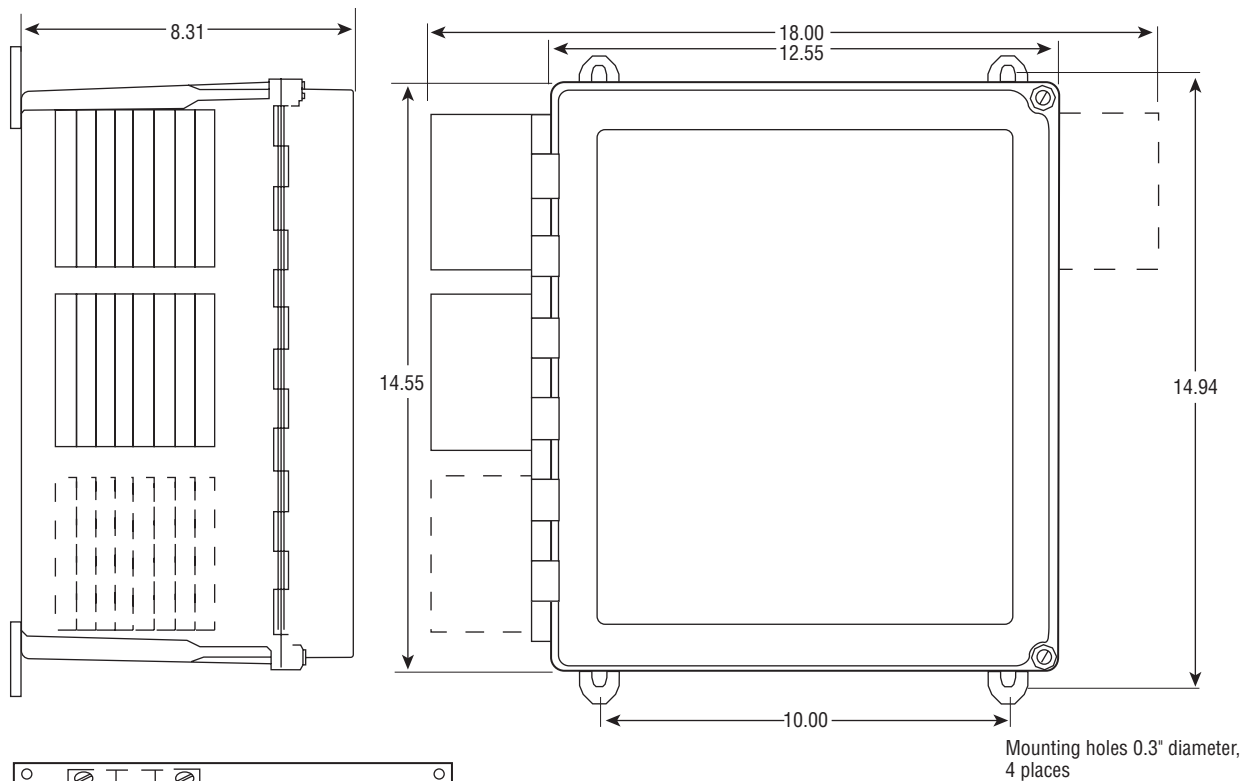
B.2 Dual-Point Assemblies #10160-120 and #10160-121

2 Point FRP

1- or 2-pole 30 A SSR assembly

1 Pole Model: 920*E4FWL*SIS302*SS3102

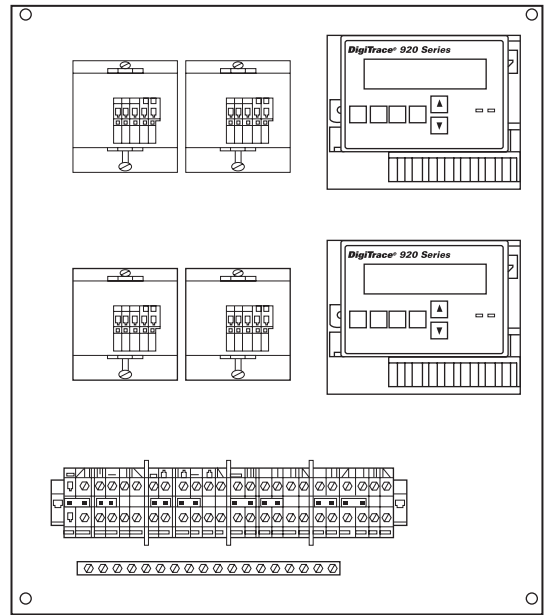
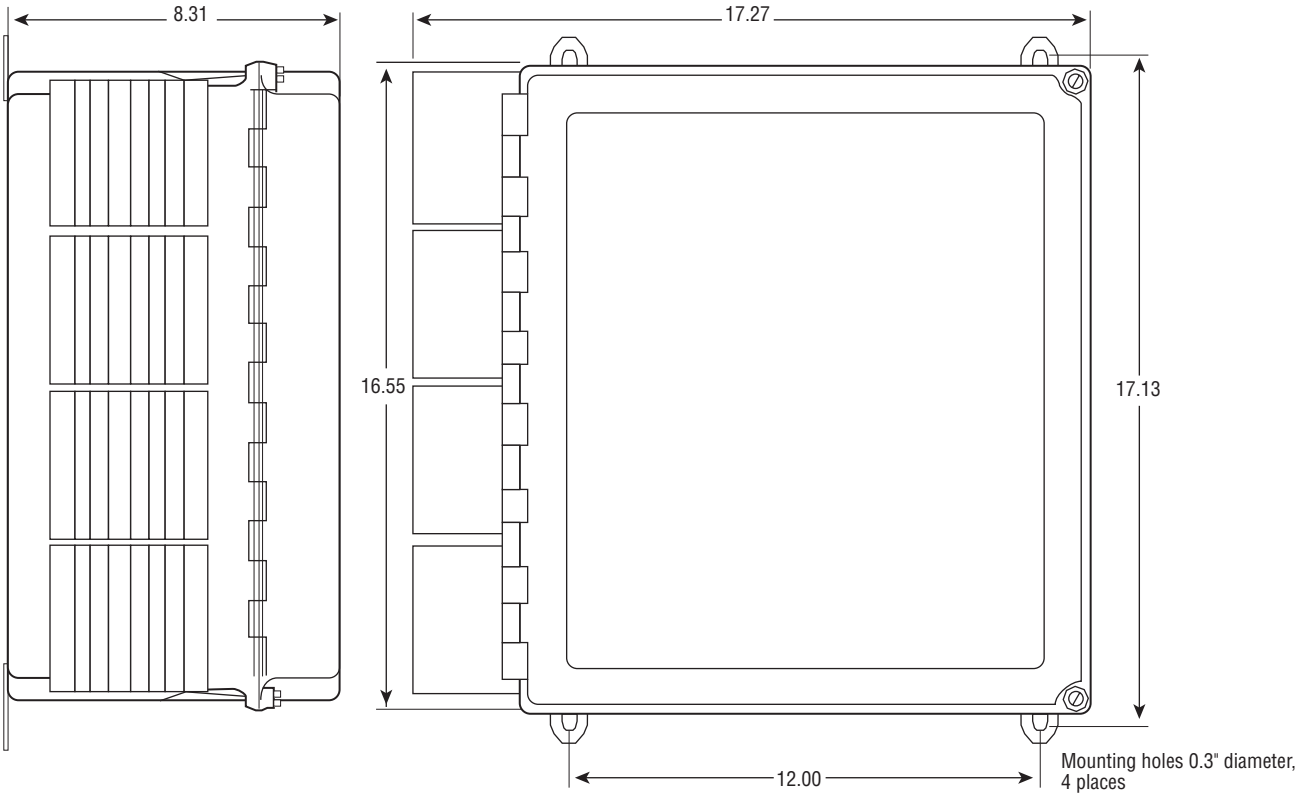
2 Pole Model: 920*E4FWL*SIS302*SS3202



B.3 Four-Point Assembly #10160-125

**4 Point FRP
1-pole 30 A SSR assembly**

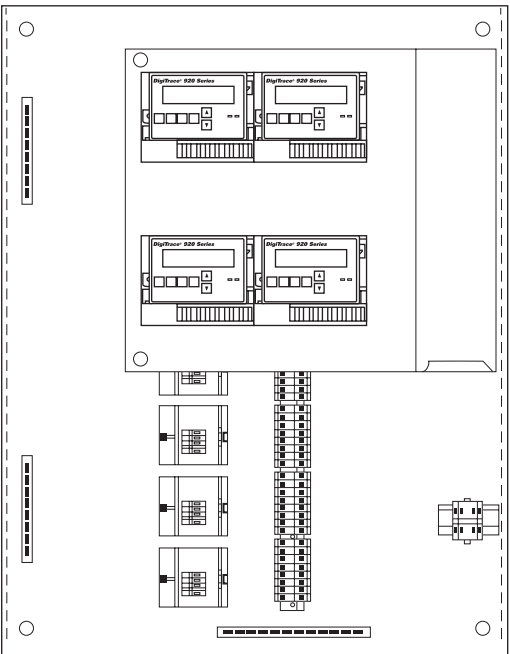
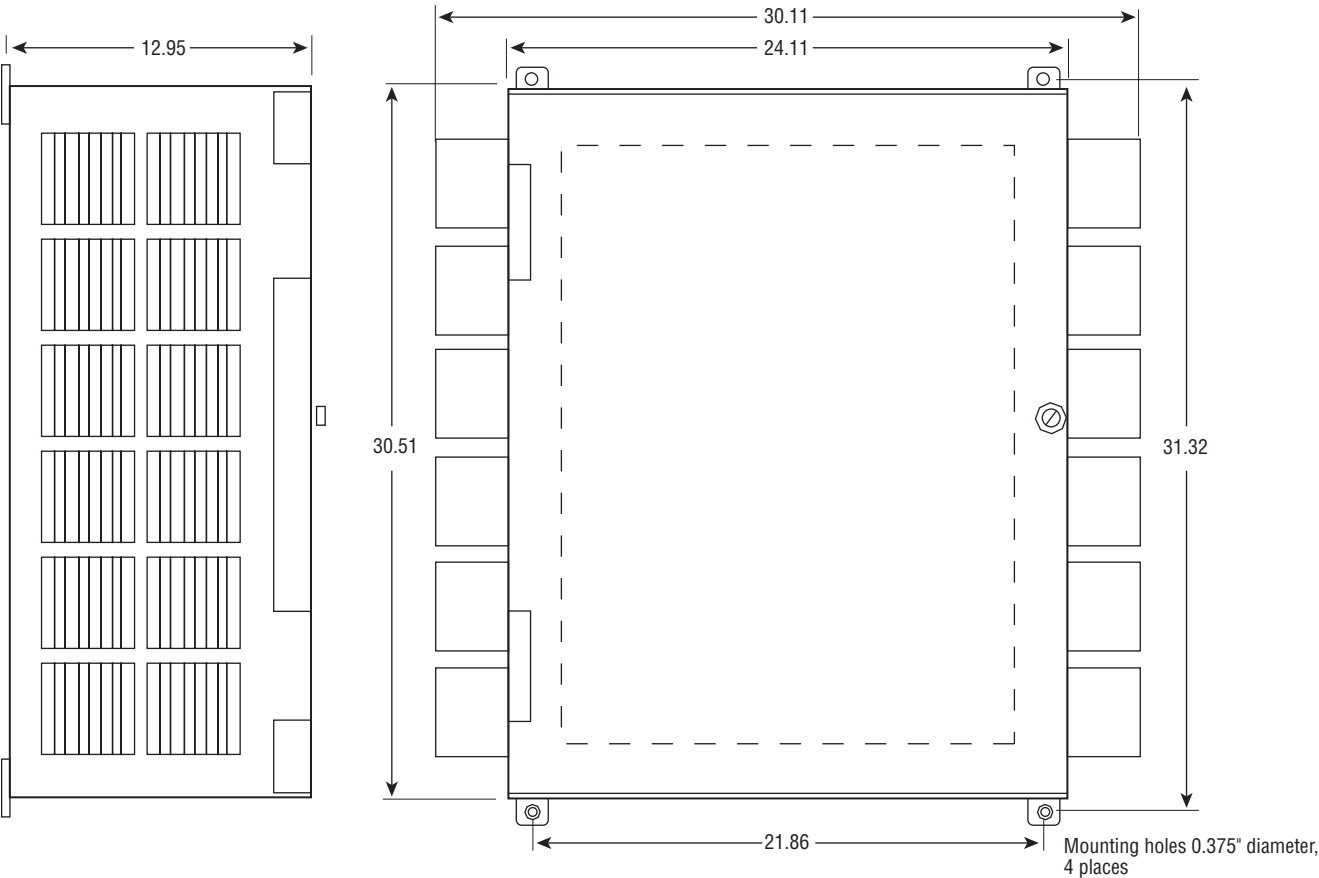
Model: 920*E6FWL*SIS304*SS3104



B.4 Eight-Point Assembly #10160-035

**8-Point FRP
1-pole 30 A SSR assembly**

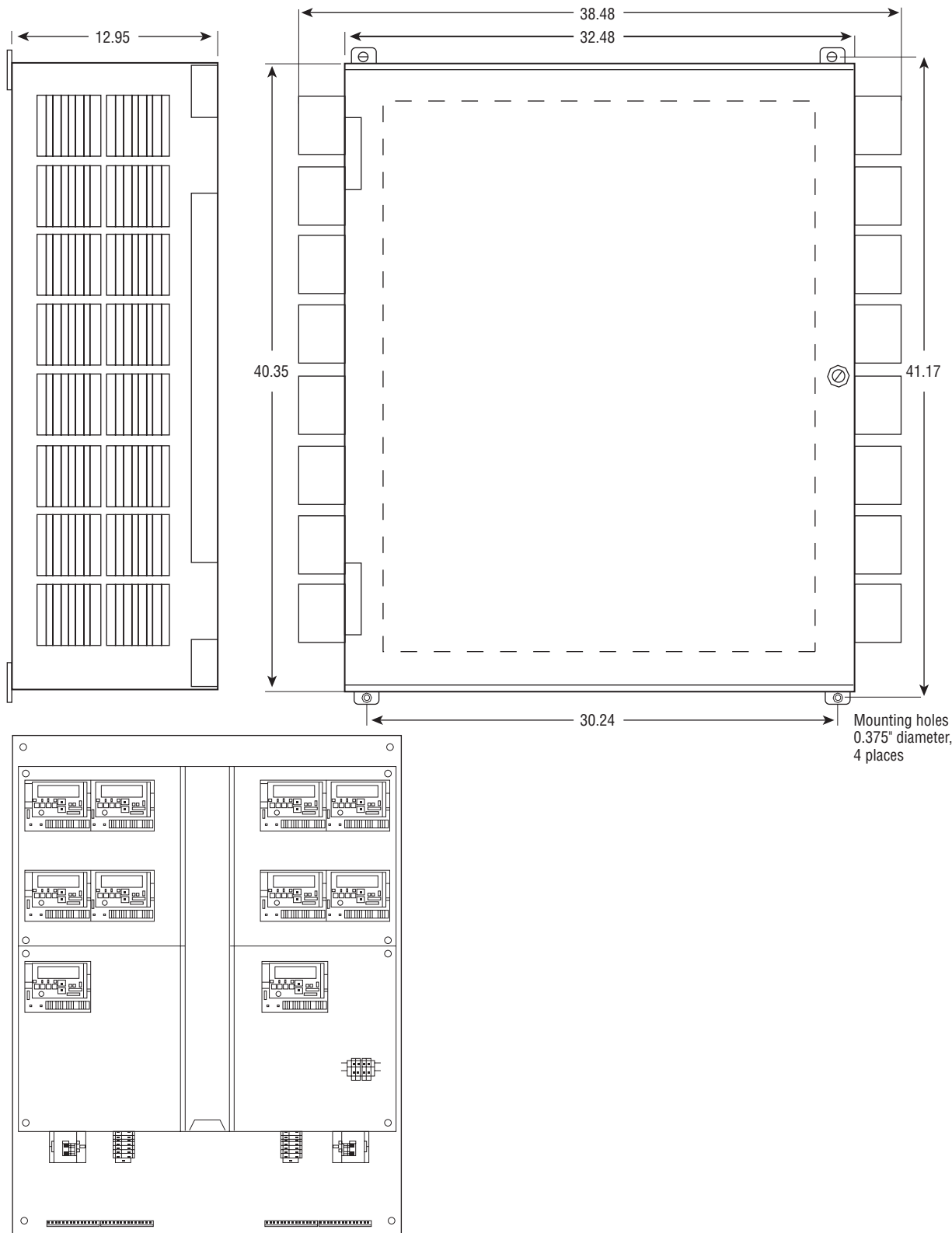
Model: 920*E10FWQ1*SIS308*SS3108



B.5 Twenty-Point Assembly #10160-045

**20-Point FRP
1-pole 30 A SSR assembly**

Model: 920*E14FWQ1*SIS320*SS3120

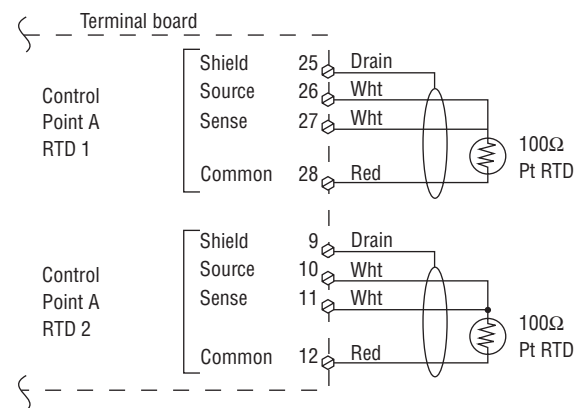


Appendix C Wiring Diagrams

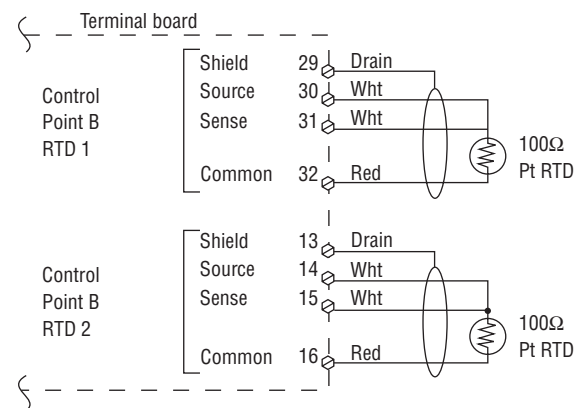
The following drawings provide sample wiring diagrams for the 920 Series control products and optional accessories. Please contact your local Tyco Thermal Controls representative for information regarding other available options.

C.1 TS Wiring

C.1.1 100 Ω PLATINUM RTD WIRING



Control Point A
TS1 and TS2 Wiring Diagram



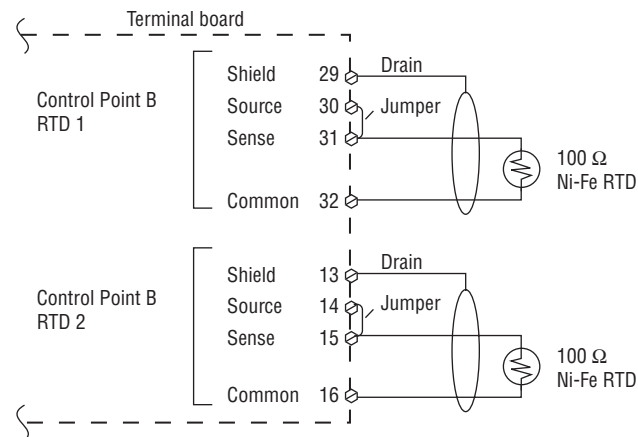
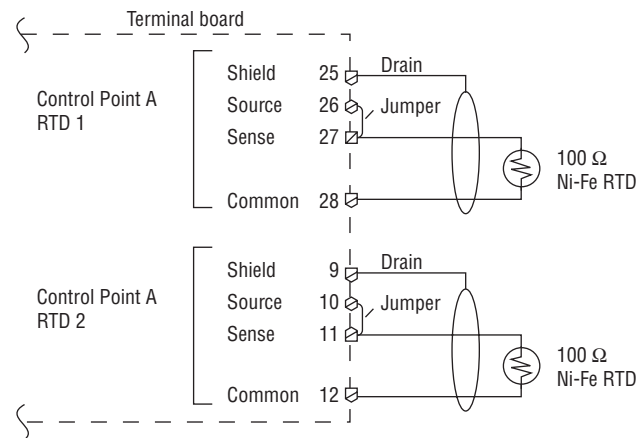
Control Point B
TS1 and TS2 Wiring Diagram



Note: Temperature sensor manufacturers may use different lead wire colors than those shown in the diagram above. Some common color combinations are shown in the table below, but others may also be available. See sections 3.7.1 on page 32 and 6.2.2 on page 55 for additional details.

Signal Description	Lead Wire Color Scheme #1	Lead Wire Color Scheme #2	IEC 751 Color Scheme #3
Source	White	White	Red
Sense	White	Black	Red
Common	Red	Red	White

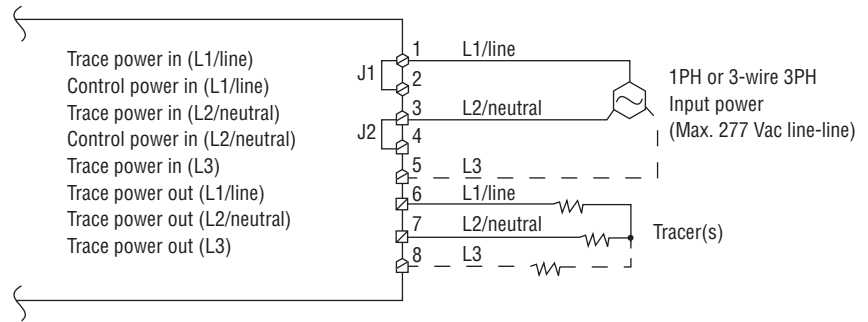
C.1.2 100Ω NICKEL IRON RTD WIRING



Control Point B
TS1 and TS2 wiring diagram

C.2 Power Wiring

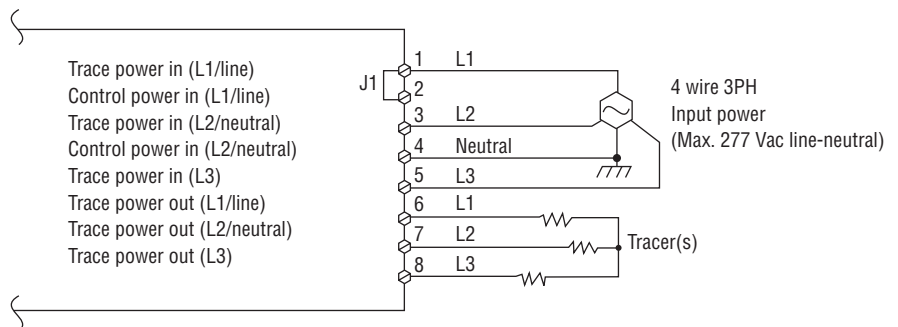
C.2.1 CONTROLLER POWERED DIRECTLY FROM 1 PH OR 3-WIRE 3 PH SOURCE



Notes:

1. Jumpers J1 and J2 are normally supplied by the Factory
2. Terminals 5 and 8 are only supplied when 3 phase versions are ordered from the Factory

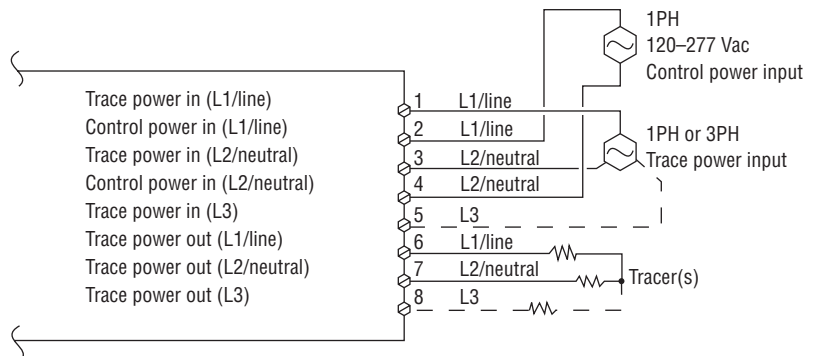
C.2.2 CONTROLLER POWERED DIRECTLY FROM 4-WIRE 3 PH SOURCE



Notes:

1. Jumpers J1 and J2 are normally supplied by the Factory
2. Terminals 5 and 8 are only supplied when 3 phase versions are ordered from the Factory
3. Remove jumper J2

C.2.3 CONTROLLER POWERED FROM A SEPARATE CIRCUIT

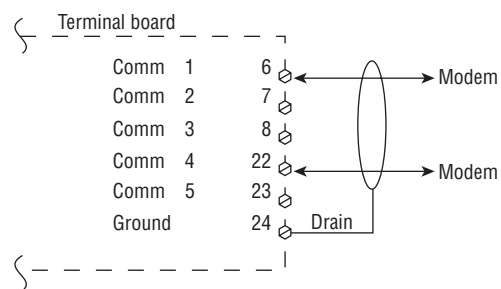


Notes:

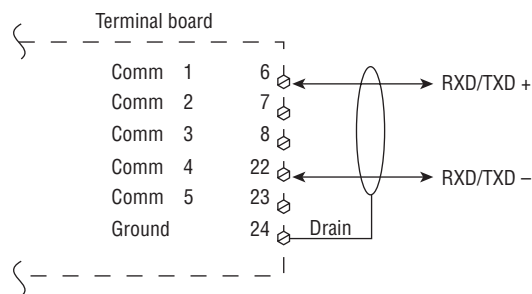
1. Jumpers J1 and J2 are normally supplied by the Factory
2. Terminals 5 and 8 are only supplied when 3 phase versions are ordered from the Factory
3. Remove jumpers J1 and J2

C.3 Communication Wiring

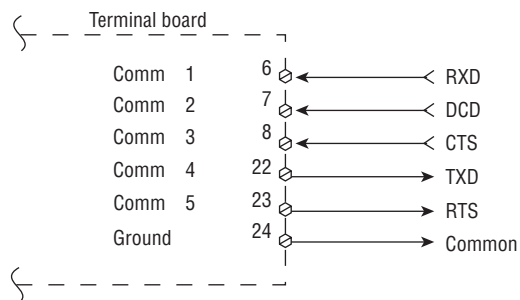
C.3.1 2-WIRE MODEM OPTION



C.3.2 2-WIRE RS-485 OPTION

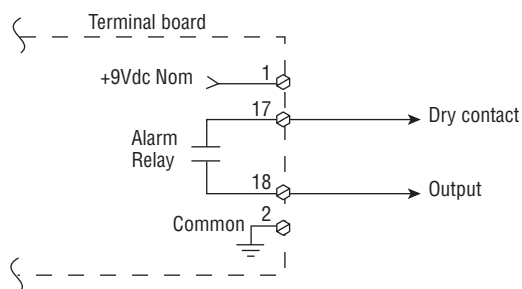


C.3.3 RS-232 OPTION

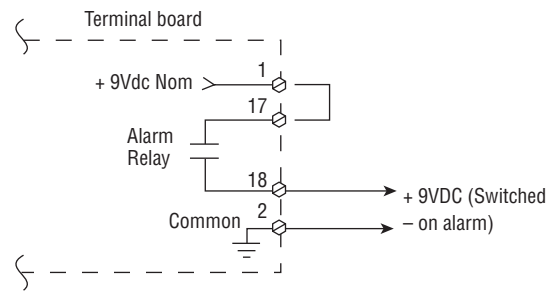


C.4 Alarm Output Wiring

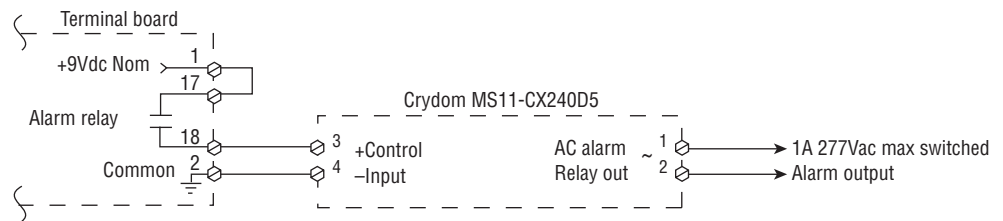
C.4.1 USED AS A DRY CONTACT



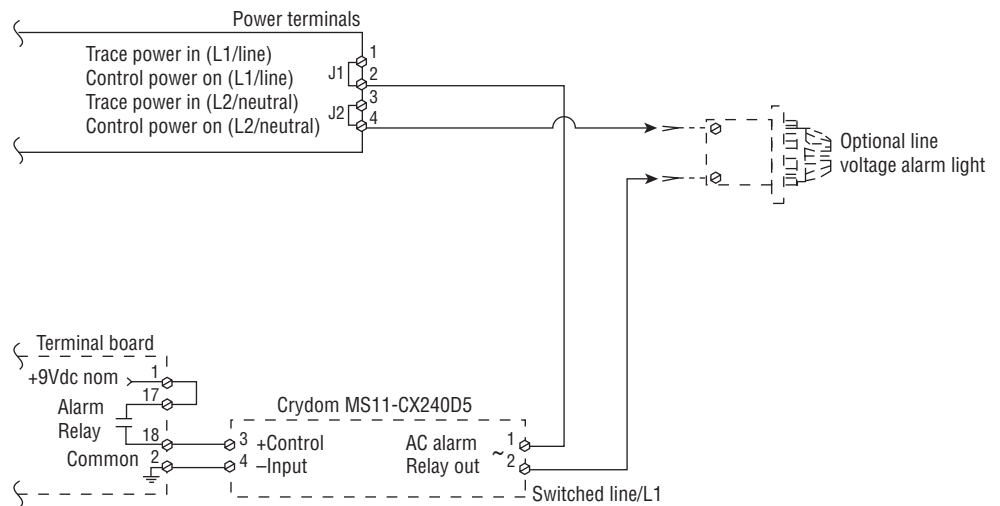
C.4.2 USED AS A SWITCHED DC CONTACT



C.4.3 USED TO DRIVE AN OPTIONAL EXTERNAL RELAY

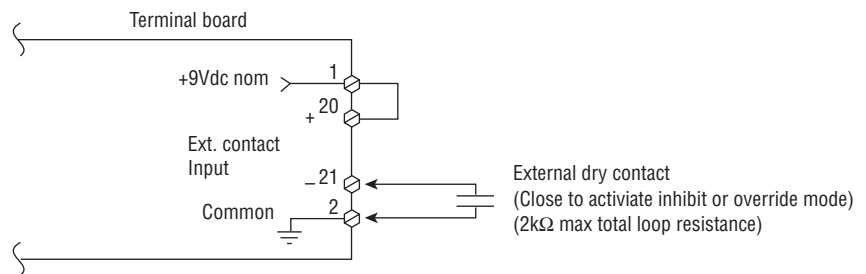


C.4.4 USED TO DRIVE AN OPTIONAL EXTERNAL PILOT LIGHT

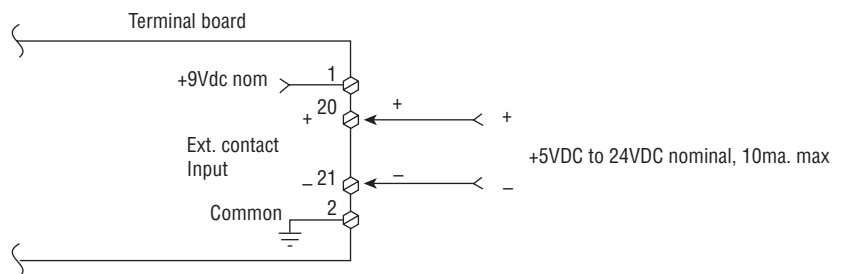


C.5 External Input/Output Port Wiring

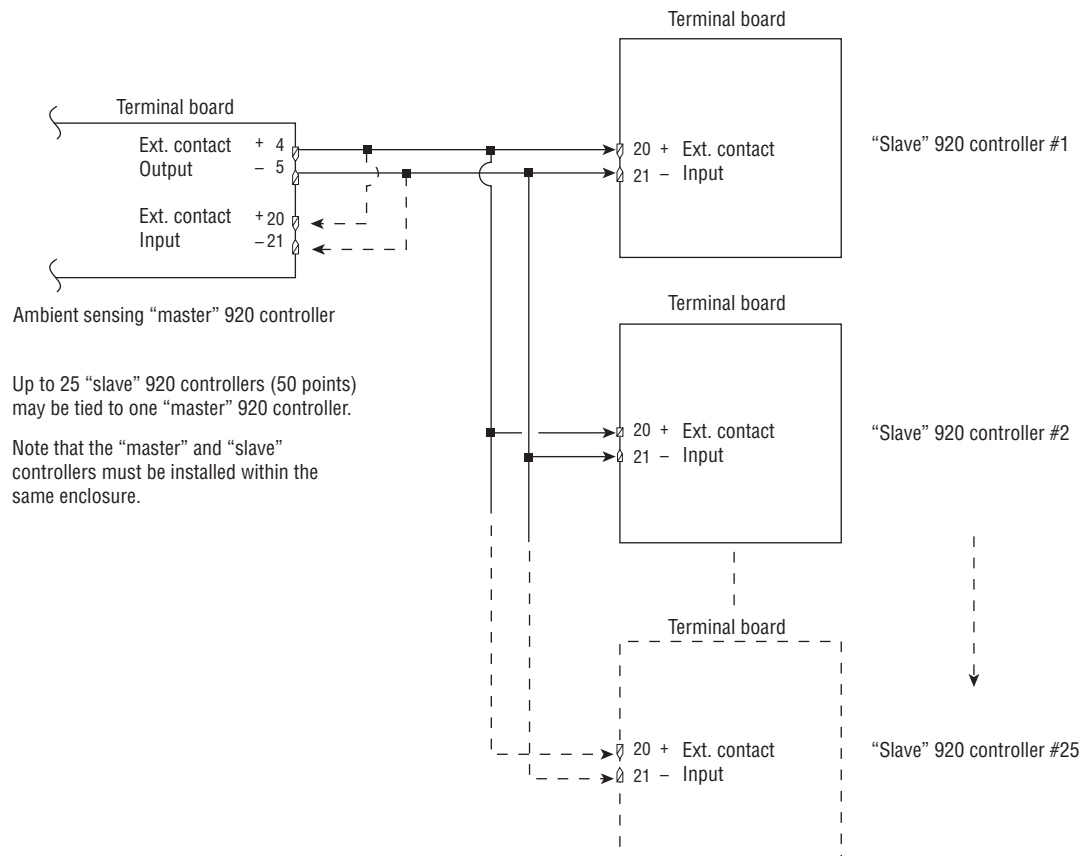
C.5.1 EXTERNAL INHIBIT/OVERRIDE USING A DRY CONTACT



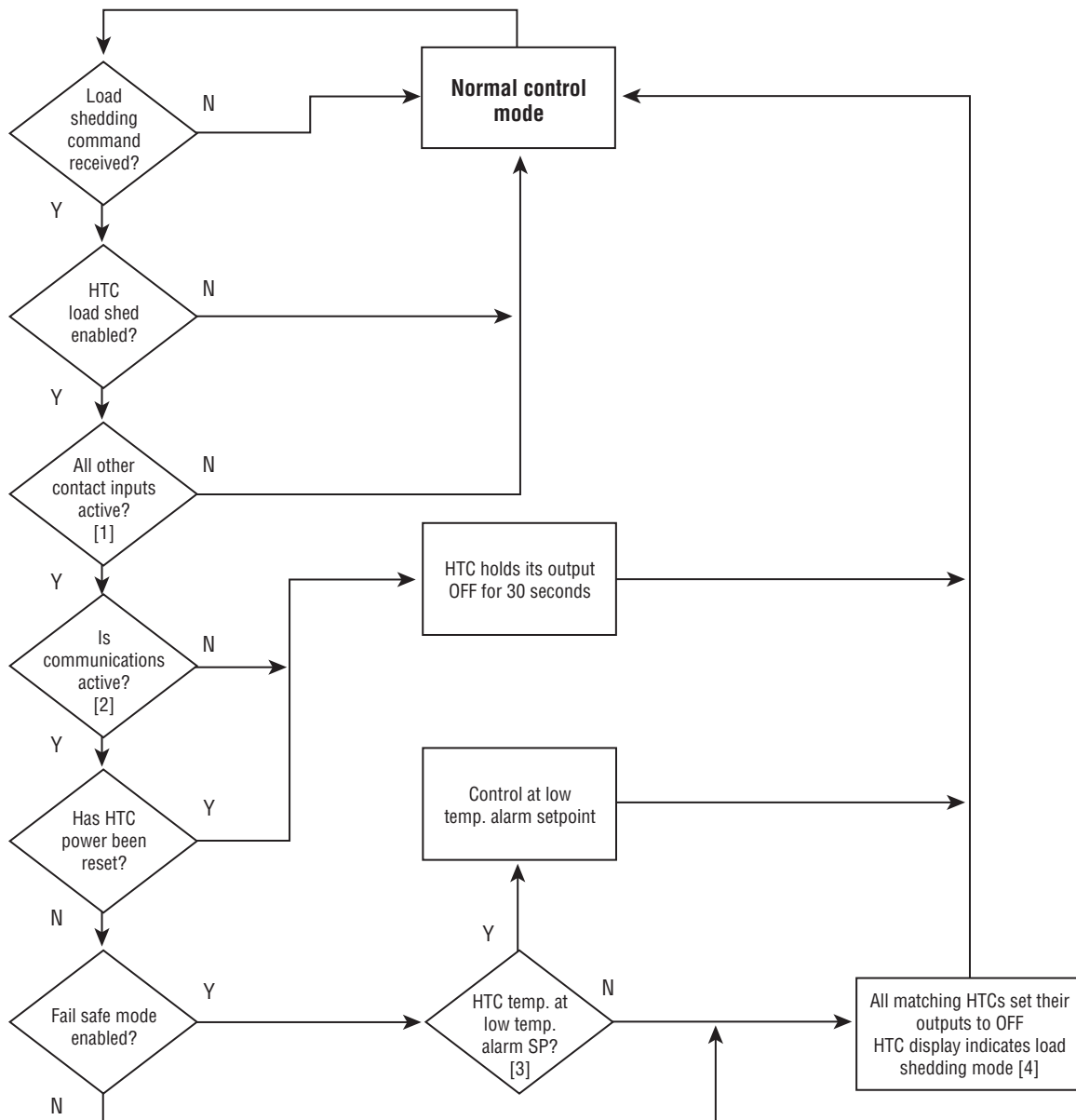
C.5.2 EXTERNAL INHIBIT/OVERRIDE USING A DC SIGNAL



C.5.3 TEMPBUS AND INHIBIT MASTER/SLAVE CONNECTIONS



Appendix D HTC Load Shedding Sequence



1. If an HTC is associated with more than one contact input, all inputs must be activated before the HTC will go into a Load Shedding mode.
2. If communications between an HTC and an upstream device such as a GCC or supervisory software are interrupted, or if the power has been reset to the HTC, the HTC will hold its output OFF, waiting for a Load Shedding command
3. Only if the Low Temperature Alarm is ENABLED.
4. For 920 Series controllers, a "<Load Shedding>" message will displayed after the load current reading.

Appendix E 100 Ω Platinum RTD Table

IEC751 (1983)—100 Ω Platinum Resistance Temperature (RTD)—0.00385 Ohms/Ohm/°C								
Ohms	°F	°C	Ohms	°F	°C	Ohms	°F	°C
62.28	−139	−95	159.18	311	155	248.76	761	405
64.30	−130	−90	161.04	320	160	250.48	770	410
66.31	−121	−85	162.90	329	165	252.19	779	415
68.33	−112	−80	164.76	338	170	253.90	788	420
70.33	−103	−75	166.61	347	175	255.61	797	425
72.33	−94	−70	168.46	356	180	257.32	806	430
74.33	−85	−65	170.31	365	185	259.02	815	435
76.33	−76	−60	172.16	374	190	260.72	824	440
78.32	−67	−55	174.00	383	195	262.42	833	445
80.31	−58	−50	175.84	392	200	264.11	842	450
82.29	−49	−45	177.68	401	205	265.80	851	455
84.27	−40	−40	179.51	410	210	267.49	860	460
86.25	−31	−35	181.34	419	215	269.18	869	465
88.22	−22	−30	183.17	428	220	270.86	878	470
90.19	−13	−25	184.99	437	225	272.54	887	475
92.16	−4	−20	186.82	446	230	274.22	896	480
94.12	5	−15	188.63	455	235	275.89	905	485
96.09	14	−10	190.45	464	240	277.56	914	490
98.04	23	−5	192.26	473	245	279.23	923	495
100.0	32	0	194.07	482	250	280.90	932	500
101.95	41	5	195.88	491	255	282.56	941	505
103.90	50	10	197.69	500	260	284.22	950	510
105.85	59	15	199.49	509	265	285.87	959	515
107.79	68	20	201.29	518	270	287.53	968	520
109.73	77	25	203.08	527	275	289.18	977	525
111.67	86	30	204.88	536	280	290.83	986	530
113.61	95	35	206.67	545	285	292.47	995	535
115.54	104	40	208.45	554	290	294.11	1004	540
117.47	113	45	210.24	563	295	295.75	1013	545
119.40	122	50	212.02	572	300	297.39	1022	550
121.32	131	55	213.80	581	305	299.02	1031	555
123.24	140	60	215.57	590	310	300.65	1040	560
125.16	149	65	217.35	599	315	302.28	1049	565
127.07	158	70	219.12	608	320	303.91	1058	570
128.98	167	75	220.88	617	325	305.53	1067	575
130.89	176	80	222.65	626	330	307.15	1076	580
132.80	185	85	224.41	635	335	308.76	1085	585
134.70	194	90	226.17	644	340	310.38	1094	590
136.60	203	95	227.92	653	345	311.99	1103	595
138.50	212	100	229.67	662	350	313.59	1112	600
140.39	221	105	231.42	671	355	315.20	1121	605
142.29	230	110	233.17	680	360	316.80	1130	610
144.17	239	115	234.91	689	365	318.40	1139	615
146.06	248	120	236.65	698	370	319.99	1148	620
147.94	257	125	238.39	707	375	321.59	1157	625
149.82	266	130	240.13	716	380	323.18	1166	630
151.70	275	135	241.86	725	385	324.76	1175	635
153.58	284	140	243.59	734	390	326.35	1184	640
155.45	293	145	245.31	743	395	327.93	1193	645
157.31	302	150	247.04	752	400	329.51	1202	650

Appendix F 100 Ω Nickel-Iron RTD Table

Ohms	°F	°C	Ohms	°F	°C	Ohms	°F	°C
69.8	-100	-73	133.4	155	68	218.2	410	210
71.1	-95	-70	134.8	160	71	220.1	415	212
72.3	-90	-67	136.3	165	73	222.0	420	215
73.1	-85	-65	137.8	170	76	223.9	425	218
74.3	-80	-62	139.3	175	79	225.8	430	221
75.5	-75	-59	140.8	180	82	227.7	435	223
76.7	-70	-56	142.3	185	85	229.6	440	226
78.0	-65	-53	143.8	190	87	231.5	445	229
78.8	-60	-51	145.3	195	90	233.5	450	232
80.0	-55	-48	146.8	200	93	235.4	455	235
81.2	-50	-45	148.4	205	96	237.4	460	237
82.2	-45	-42	149.9	210	98	239.3	465	240
82.9	-40	-40	151.5	215	101	241.3	470	243
84.2	-35	-37	153.0	220	104	243.3	475	246
85.7	-30	-34	154.6	225	107	245.3	480	248
86.9	-25	-31	156.2	230	110	247.2	485	251
88.1	-20	-28	157.7	235	112	249.3	490	254
88.9	-15	-26	159.3	240	115	251.2	495	257
90.1	-10	-23	160.9	245	118	253.3	500	260
91.4	-5	-20	162.5	250	121	255.2	505	262
92.2	0	-17	164.2	255	123	257.3	510	265
93.4	5	-15	165.8	260	126	259.3	515	268
94.5	10	-12	167.4	265	129	261.4	520	271
95.8	15	-9	169.0	270	132	263.4	525	273
97.1	20	-6	170.7	275	135	265.5	530	276
98.3	25	-3	172.3	280	137	267.6	535	279
99.5	30	-1	174.0	285	140	269.6	540	282
100.8	35	1	175.7	290	143	271.7	545	285
102.0	40	4	177.4	295	146	273.8	550	287
103.3	45	7	179.1	300	148	275.9	555	290
104.5	50	10	180.8	305	151	278.0	560	293
105.9	55	12	182.5	310	154	280.1	565	296
107.2	60	15	184.2	315	157	282.3	570	298
108.5	65	18	185.9	320	160	284.4	575	301
109.8	70	21	187.6	325	162	286.5	580	304
111.1	75	23	189.	330	165	288.6	585	307
112.5	80	26	191.1	335	168	290.8	590	310
113.8	85	29	192.9	340	171	293.1	595	312
115.2	90	32	194.5	345	173	295.2	600	315
116.5	95	35	196.4	350	176	297.5	605	318
117.9	100	37	198.2	355	179	299.8	610	321
119.2	105	40	199.9	360	182	301.4	615	323
120.6	110	43	201.7	365	185	303.7	620	326
122.0	115	46	203.5	370	187	306.0	625	329
123.4	120	48	205.3	375	190	308.3	630	332
124.8	125	51	207.2	380	193	310.6	635	335
126.2	130	54	209.0	385	196	312.2	640	337
127.6	135	57	210.8	390	198	314.5	645	340
129.0	140	60	212.7	395	201	316.8	650	343
130.5	145	62	214.5	400	204	319.1	655	346
131.9	150	65	216.4	405	207	320.6	660	348

Appendix G Factory Default/Configuration Sheets

G.1 Configuration Sheet V3.00

The following defines the default 920 Series control module configuration as set by Tyco Thermal Controls for firmware V3.00. These settings are subject to change without notice. It is the user's responsibility to verify that all configuration parameters are chosen appropriately for the intended application. Note: It is recommended that all parameters common to both Control Points A and B be programmed first.

Common Setup Sub-Menu

Parameter	Factory	User
Temp. Units	°F	
Firmware Version	V3.0	n/a
Ext. Contact Input	Not used	
Ext. Contact Output	Not used	
Flash Alarm Output	Yes	
Alarm Output State	N.C.	
Language	English	
Point B Used	Yes	
Passcode	0	

Communication Setup Sub-Menu

Parameter	Factory	User
HTCBUS Addr	(factory ID)	
Protocol	HTCBUS	
Baud Rate	AUTO	
Hardware	None, modem, RS-232 (if installed)	
Driver	Auto	
Profile	Auto	
Tx Delay	0.02 secs	

Point Setup Sub-Menu

Parameter	Factory	User
Tag	TAG-32768	
Switch Control Mode	Proportional	
Prop Band	4°F (2°C)	
Deadband	n/a	
Switch Rating	30.0 A	
Circuit Breaker	30.0 A	
Max Power	7200 W	
TS CTL Mode	TS1-Fail Off	
TS1 – High Limit	Disable	
TS2 – High Limit	Disable	
Volt Turns Ratio	1.00 to 1	

Point Setup Sub-Menu (Continued)

Current Turns Ratio	1.00 to 1
Autocycle	Enable
Autocycle Interval	8
Autocycle Units	Hours
Inhibit Ctl	Disable
Load Shedding	Disable

Configuration Mode Main Menu

Parameter	Factory	User
Control Setpoint	68°F (20°C)	

TS Alarms Configuration Sub-Menu

Parameter	Factory	User
TS 1 Fail	Enable	
Lo TS 1 Alarm	Enable	
Lo TS 1	14°F (–10°C)	
Hi TS 1 Alarm	Enable	
Hi TS 1	212°F (100°C)	
TS 2 Fail	Disable	
Lo TS 2 Alarm	Disable	
Lo TS 2	—	
Hi TS 2 Alarm	Disable	
Hi TS 2	—	
Latch TS Alarms	Yes	
TS CTL Fail Alarm	Enable	

Other Alarms Configuration Sub-Menu		
Parameter	Factory	User
Lo Load Alarm	Enable	
Lo Load	1.00 A	
Hi Load Alarm	Disable	
Hi Load	—	
Hi GFI Alarm	Enable	
Hi GFI	50 ma	
GFI Trip Alarm	Enable	
GFI Trip	75 ma	
Lo Volt Alarm	Enable	
Lo Volt	90 V	
High Volt Alarm	Enable	
Hi Volt	270 V	
Nominal Resist	6.00 Ω	
Lo Resist Alarm	Disable	
Lo Resist	—	
Hi Resist Alarm	Disable	
Hi Resist	—	
Overcurrent Trip	Enable	
Switch Fail Alarm	Enable	
HTC Reset Alarm	Disable	
C.B. Limit Alarm	Disable	
Power Limit Alarm	Disable	
Switch Limit Alarm	Disable	
EEROM Data Fail	Disable	

G.2 920 Series HTC Configuration Sheet V3.1X and V3.2X

 = Most commonly changed setting

Note: Select temperature units before any other settings are entered.

Configuration Mode Main Menu

Parameter	Factory	User
Control Setpoint	68°F (20°C)	
Lo TS 1	14°F (–10°C)	
Lo Load	1.0 A	
Hi GFI	50 mA	
GFI Trip	75 mA	

TS Alarms Configuration Sub-Menu

Parameter	Factory	User
TS 1 Fail	Enable	
Lo TS 1	Enable	
Lo TS 1	14°F (–10°C)	
Hi TS 1	Disable	
Hi TS 1	*n/a (212°F (100°C))	
TS 2 Fail	Disable	
Lo TS 2	Disable	
Lo TS 2	*n/a (14°F (–10°C))	
Hi TS 2	Disable	
Hi TS 2	*n/a (212°F (100°C))	
Lo TS Filter	0 min	
Hi TS Filter	*n/a (0 min)	
Latch TS Alarms	Yes	
CTL TS Fail	Enable	

Other Alarms Configuration Sub-Menu

Parameter	Factory	User
Lo Load	Enable	
Lo Load	1.0 A	
Lo Load Filter	0 sec	
Hi Load	Disable	
Hi Load	*n/a (30.0 A)	
Hi Load Filter	*n/a (0 sec)	
Hi GFI	Enable	
Hi GFI	50 mA	
Hi GFI Filter	0 sec	

Other Alarms Configuration Sub-Menu (Continued)

GFI Trip	Enable
GFI Trip	75 mA
Lo Volt	Enable
Lo Volt	90 V
Lo Volt Filter	0 sec
Hi Volt	Disable
Hi Volt	*n/a (270 V)
Hi Volt Filter	*n/a (0 sec)
Lo Resist	Disable
Lo Resist	*n/a (50%)
Lo Resist Filter	*n/a (0 sec)
Hi Resist	Disable
Hi Resist	*n/a (50%)
Hi Resist Filter	*n/a (0 sec)
Nominal Resist	*n/a (6.00 Ω)
Overcurrent Trip	Enable
Switch Fail	Enable
HTC Reset	Disable
C.B. Limiting	Disable
Power Limiting	Disable
Switch Limiting	Disable
Contacto Count	*n/a (Enable)
Countactor Count	*n/a (200,000)
EEROM Data Fail	Enable

Point Setup Sub-Menu		
Parameter	Factory	User
Tag	TAG-(factory ID)	
Switch Control Mode	Proportional	
Prop Band	4°F (2°C)	
Deadband	*n/a (5°F(3°C))	
Cycle Time	*n/a (10 min)	
Switch Rating	30.0 A	
Circuit Breaker	30.0 A	
Max Power	7200 W	
3 Ph Pwr Calc	No	
TS Fail Mode	Off	
TS CTL Mode	TS1-Fail Off	
TS 1 Type	100 Ω Plat	
TS 1 Lead Resist	*n/a (0 Ω)	
TS 1 Hi Limit	Disable	
TS 2 Type	100 Ω Plat	
TS 2 Lead Resist	*n/a (0 Ω)	
TS 2 Hi Limit	Disable	
Volt Source	Pt A (or Pt B)	
Fixed Volt	*n/a (120V)	
Volt Turns Ratio	1.00 to 1	
Current Turns Ratio	1.00 to 1	
Autocycle	Enable	
Autocycle Interval	8	
Autocycle Units	Hours	
Override Source	Remote	
Load Shedding	Disable	

Common Setup Sub-Menu		
Parameter	Factory	User
Temperature Units	°F	
Version	V3.2x.xx	n/a
Ext. Input	Not used	
Ext. Output	Not used	
Flash Alarm Output	Yes	
Alarm Output	N.C.	
Language	English	
Point B Used	Yes	
Passcode	0	
Scroll Delay	0.15 secs	
Copy Config...	(see user manual)	

Communication Setup Sub-Menu

Parameter	Factory	User
Protocol	HTCBUS	
HTCBUS Addr	(factory ID)	
Modbus Addr	*n/a (1)	
Modbus Sub Addr	*n/a (0)	
Baud Rate	Auto	
Parity	*n/a (None)	
Hardware	None, modem, RS-232, RS-485	n/a
Driver	Auto	
Profile	Auto	
Tx Delay	0.06 secs	

*n/a Parameter may only appear if certain features are enabled. Values shown in brackets are Tyco Thermal Controls defaults if the settings are enabled.

This information defines the default 920 Series control module configuration as set by Tyco Thermal Controls for firmware up to V3.2x. These settings are subject to change without notice.

It is the user's responsibility to verify that all configuration parameters are chosen appropriately for the intended application.

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